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Users' Manual for Linear Freight Car Forced Lateral Response Analysis Computer Program

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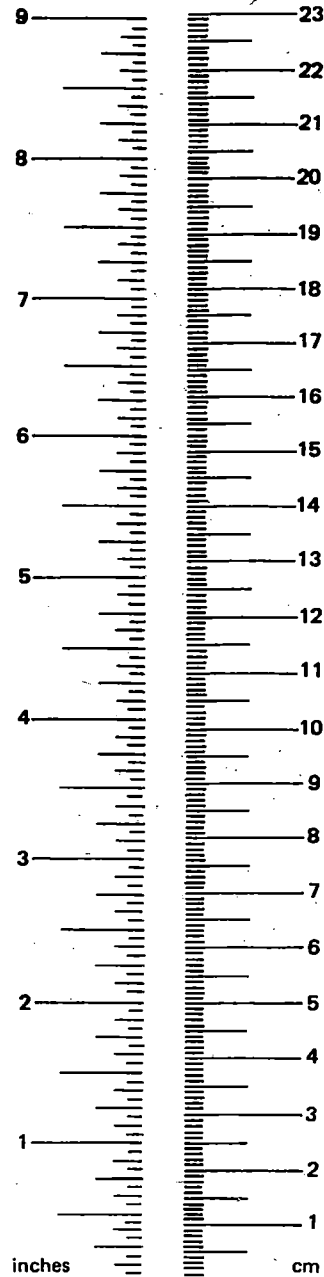
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METRIC CONVERSION FACTORS

Approximate Conversions to Metric Measures

Symbol	When You Know	Multiply by	To Find	Symbol
LENGTH				
in	inches	*2.5	centimeters	cm
ft	feet	30	centimeters	cm
yd	yards	0.9	meters	m
mi	miles	1.6	kilometers	km
AREA				
in ²	square inches	6.5	square centimeters	cm ²
ft ²	square feet	0.09	square meters	m ²
yd ²	square yards	0.8	square meters	m ²
mi ²	square miles	2.6	square kilometers	km ²
	acres	0.4	hectares	ha
MASS (weight)				
oz	ounces	28	grams	g
lb	pounds	0.45	kilograms	kg
	short tons (2000 lb)	0.9	tonnes	t
VOLUME				
tap	teaspoons	5	milliliters	ml
Tbsp	tablespoons	15	milliliters	ml
fl oz	fluid ounces	30	milliliters	ml
c	cups	0.24	liters	l
pt	pints	0.47	liters	l
qt	quarts	0.95	liters	l
gal	gallons	3.8	liters	l
ft ³	cubic feet	0.03	cubic meters	m ³
yd ³	cubic yards	0.76	cubic meters	m ³
TEMPERATURE (exact)				
°F	Fahrenheit temperature	5/9 (after subtracting 32)	Celsius temperature	°C

*1 in. = 2.54 cm (exactly). For other exact conversions and more detail tables see NBS Misc. Publ. 286, Units of Weight and Measures, Price \$2.25 SD Catalog No. C13 10 286.



Approximate Conversions from Metric Measures

Symbol	When You Know	Multiply by	To Find	Symbol
LENGTH				
mm	millimeters	0.04	inches	in
cm	centimeters	0.4	inches	in
m	meters	3.3	feet	ft
m	meters	1.1	yards	yd
km	kilometers	0.6	miles	mi
AREA				
cm ²	square centimeters	0.16	square inches	in ²
m ²	square meters	1.2	square yards	yd ²
km ²	square kilometers	0.4	square miles	mi ²
ha	hectares (10,000 m ²)	2.5	acres	
MASS (weight)				
g	grams	0.035	ounces	oz
kg	kilograms	2.2	pounds	lb
t	tonnes (1000 kg)	1.1	short tons	
VOLUME				
ml	milliliters	0.03	fluid ounces	fl oz
l	liters	2.1	pints	pt
l	liters	1.06	quarts	qt
l	liters	0.26	gallons	gal
m ³	cubic meters	36	cubic feet	ft ³
m ³	cubic meters	1.3	cubic yards	yd ³
TEMPERATURE (exact)				
°C	Celsius temperature	9/5 (then add 32)	Fahrenheit temperature	°F

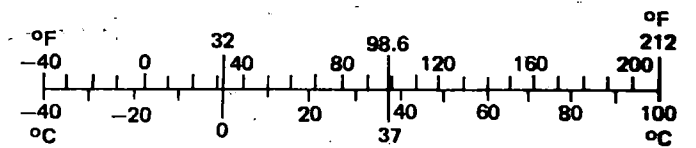


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Chapter 1

INTRODUCTION

This Users' Manual documents the FR9DOF computer program that computes the forced response of a rail freight car to roadbed alignment and crosslevel disturbances. Both the sinusoidal and random response to roadbed disturbances are computed using linear system analysis techniques. The 9 degree-of-freedom vehicle model incorporated in the program is appropriate for the response of rail freight cars with 3-piece trucks of the type widely used in North America. Due to the assumptions inherent in this model and analysis, this program is not appropriate for studying the behavior of vehicles with very flexible bodies or for the vehicle response when hunting. The reader is referred to [1] for a more detailed description of the models and their uses.

This computer program was developed as a part of the "Freight Car Dynamics" research project conducted by Clemson University and Arizona State University in cooperation with the Association of American Railroads. The Freight Car Dynamics project was sponsored by the Federal Railroad Administration under contract DOT-OS-40018, with the broad objective of developing the background and mathematical tools that designers and operators of rail vehicles need to quantitatively understand present freight

car dynamic problems. The total research effort was directed at the problems of rail vehicle curving behavior and freight car hunting as well as the problem of response to track irregularities. The overall project effort is described in [2].

This computer program is a companion to the 9 degree - of - freedom eigenvalue/eigenvector computer program described in [3]. Identical input formats for the vehicle parameters are used for the two programs, although the program control cards must, of necessity, differ. As the response computed by this program is only valid when the linear equations of vehicle motion have stable solutions, it is always advisable to establish the region of stable operation before using this forced response analysis.

The vehicle and roadbed model incorporated in the program is described in the following chapter along with the solution approach. Chapter 3 contains a description of the program including the input and output variables. A sample problem with input data, output listing and accompanying plots is contained in Chapter 4. The entire program listing may be found in the Appendix.

MODELING AND ANALYSIS

INTRODUCTION

This analysis of the forced lateral response of a rail freight car utilizes a linear, 9 degree of freedom model of the freight car. Provision for sinusoidal and random disturbances in the rail alignment and crosslevel are made. Although the model is described in detail elsewhere [1], its major features are reviewed below.

The sinusoidal and random response are solved in the frequency domain. The mathematical techniques utilized are briefly reviewed at the close of this chapter.

FREIGHT CAR MODEL

Degrees of Freedom

The 9 degree of freedom model for the lateral dynamics of railway freight cars consists of a rigid car body on two, conventional three-piece trucks. A representative example of a three-piece truck is shown in Figure 1.

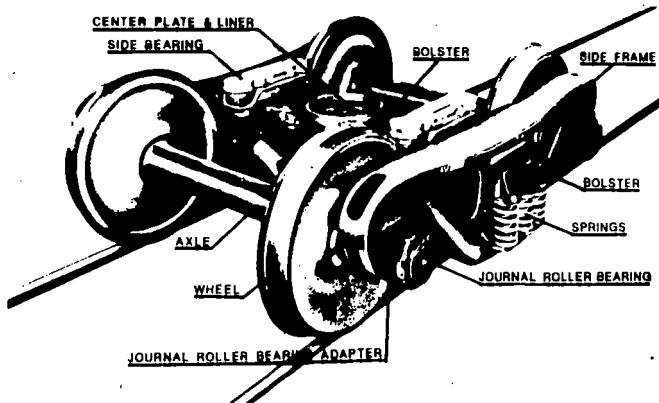


Figure 1. Three Piece Freight Truck

As shown in Figure 1, the sideframes rest on bearing adapters which, in turn, rest directly on the axle bearings. The kinematic assumption is made in this model that the sideframe-wheelset connections permit only relative rotational motion. Consequently, the wheelsets and the sideframes are forced to remain parallel. Thus, the truck and wheelset assembly may move laterally, rotate in yaw with respect to the car body, and may distort from a rectangular to a parallelogram planform. These three permissible motions, or degrees of freedom, (lateral, yaw, and warp) are shown in Figure 2 for each truck.

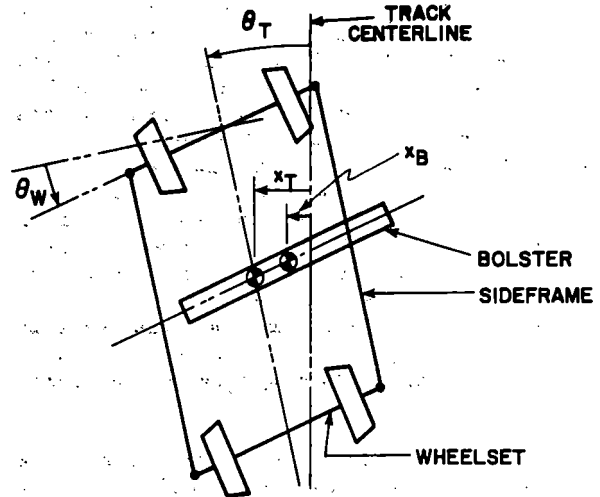


Figure 2. Freight Truck Schematic

The car body is assumed to be rigid and to have the three degrees of freedom represented by lateral, yawing, and rolling motions. Each end of the car body rests on the center plate of its respective truck bolster. It is assumed that the bolster/sideframe connection (see Figure 3) permits relative lateral and vertical motions as well as relative roll and yaw rotations. However, longitudinal clearances are sufficiently tight that it is assumed that there are no relative longitudinal motions. Thus, the truck bolster remains parallel to the wheelsets (in plan) during dynamic motions. No relative rocking or separation is considered between car body and truck bolster. The truck bolster moves laterally and in roll with the car body and yaws with the truck.

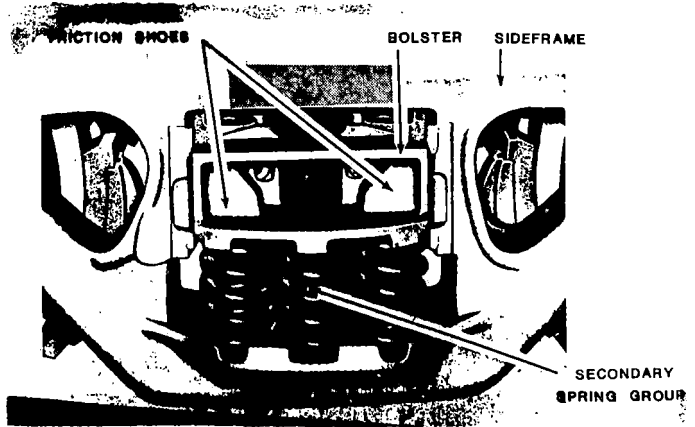


Figure 3. Suspension Configuration

Although there are other motions that may occur in the vehicle such as sideframe rocking, relative roll, vertical, and lateral motions between car body and truck bolster, flexible car body modes, etc., the 9 degree of freedom model described above is the simplest credible model for the lateral dynamic response of conventional North American freight cars. If the particular car body of interest is very flexible, appropriate degrees of freedom corresponding to these motions may be added. If large amplitude phenomena such as rock and roll are to be investigated, degrees of freedom should be added to allow for the possibility of relative roll and vertical motions of the car body and truck bolster. The adequacy of the 9 degrees of freedom model is obviously dependent on the particular problem being investigated.

The degrees of freedom for this model are summarized in Table 1 and shown in Figure 4.

Wheel-Rail Geometry

The transverse profiles of the wheels and rails enter the equations of motion through the wheel-rail geometry constraint characteristics [1,4]. These constraint functions are: (a) one half the normalized difference in rolling radii, $(r_L - r_R)/(2a)$; (b) one half the difference in contact angles, $(\delta_L - \delta_R)/2$; (c) the wheelset roll angle, ϕ , and (d) the average contact angle, $(\delta_L + \delta_R)/2$. In general, these constraint

characteristics are nonlinear functions of the lateral displacement of the wheelset with respect to the track centerline, $x_w - x_a$. As long as flange contact does not occur, the dependence of these functions on the wheelset yaw angle is very small and may be considered negligible. A sketch of a typical normalized rolling radii difference is shown in Figure 5.

Radii Difference

For wheel and rail profiles that are mirror images of each other on the left and right, the functions $(r_L - r_R)/(2a)$, $(\delta_L - \delta_R)/2$, and ϕ are odd functions of $x_w - x_a$ while $(\delta_L + \delta_R)/2$ is an even function of $x_w - x_a$.

If we consider that the constraint functions are linearized, they may be expressed as:

$$(r_L - r_R)/(2a) = (\lambda/a)(x_w - x_a) \quad (1)$$

$$(\delta_L - \delta_R)/2 = (\Delta/a)(x_w - x_a) \quad (2)$$

$$\phi = (\Gamma/a)(x_w - x_a) \quad (3)$$

$$(\delta_L + \delta_R)/2 = \delta_0 \quad (4)$$

Table 1. Nine Degree of Freedom Model

x_{TF}, x_{TR}^*	Lateral displacement of geometric center of truck frame at height of axle centerline; positive to left facing forward, measured from the track centerline.
θ_{TF}, θ_{TR}	Yaw angle of the truck centerline with respect to the track centerline; positive counterclockwise when viewed from above.
θ_{WF}, θ_{WR}	Warp angle of the truck frame; measured from the normal to the truck centerline to the axle centerline, positive counterclockwise when viewed from above.
x_C	Lateral displacement of the car body center of gravity from the track centerline; positive to the left facing forward.
θ_C	Yaw angle of the car body centerline with respect to the track centerline; positive counterclockwise when viewed from above.
ϕ_C	Roll angle of the car body with respect to the vertical; positive clockwise when viewed from the rear.

*Subscript F refers to front truck, R to rear.

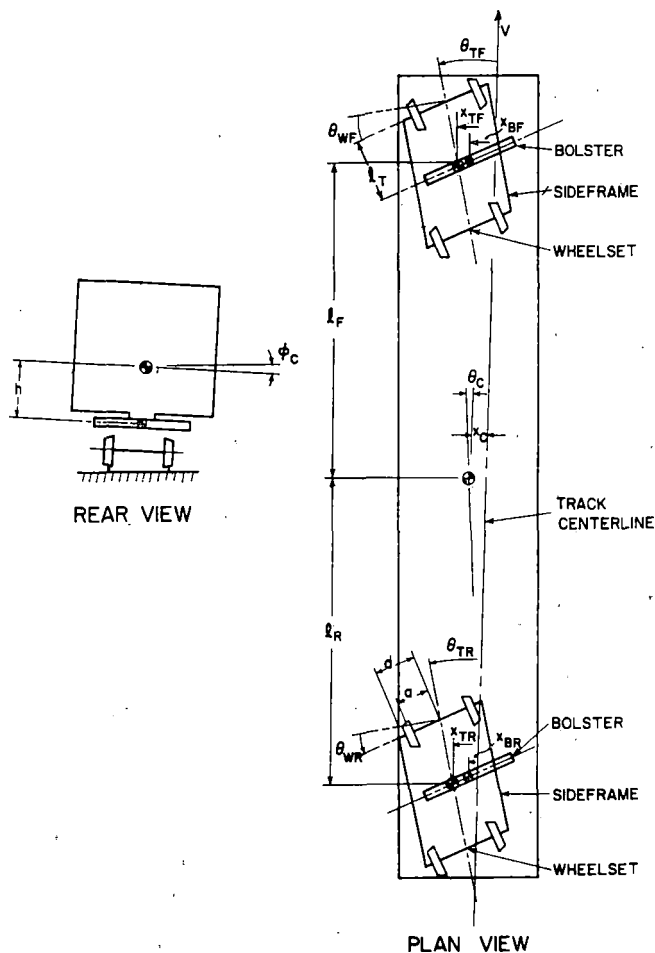


Figure 4. Freight Car Schematic

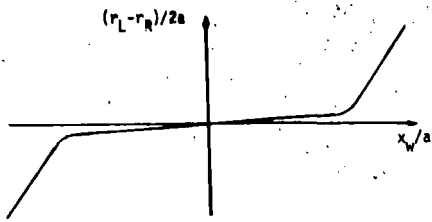


Figure 5. Typical Form for Normalized Rolling Radii Difference

Where: x_w - wheelset lateral displacement
 a - semi-rail gauge

Some method of linearization must be used to obtain the coefficients λ , Δ , Γ , and δ_0 from the actual nonlinear constraint functions. The describing function method [5] has been successfully used in many cases. Other approaches such as Taylor series expansion about $x_w = 0$, or least squares fit of a straight line over some region centered at $x_w = 0$ have also been used. The resulting equivalent linear coefficients, λ , Δ , Γ , and δ_0 are used directly in the computer programs described in this manual. The nonlinear wheel-rail geometric constraint functions may be calculated for any wheel and rail profiles using the WHRAIL or WHRAILA computer programs [6]. Estimates for the linear coefficients defined above are calculated by the describing function technique in the WHRAILA computer program.

Creep Forces

The creep forces and moments arise from the shear stresses acting between the wheels and rails. The role these forces play in the dynamics of rail vehicles is discussed in [7]. The way in which they enter the equations of motion is presented in [1]. Kalker has developed theories for calculating these forces and moments [8].

The creep forces and moments depend on the elastic properties of the wheel and rail, the normal load across the wheel-rail contact zone, and the relative linear and angular velocities between wheel and rail at the contact zone. When these relative linear and angular velocities are normalized by the forward speed of the wheel they are called linear and spin creepages, respectively. The lateral and longitudinal components of the vector creep force and the creep moment about the normal to the contact zone depend nonlinearly on the creepages. For "large" values of creepage, gross slip may occur between wheel and rail and the vector creep force is limited by the level of adhesion. In such cases, Kalker's nonlinear theory may be used to calculate the creep forces and moments using computer codes such as those given in [9, 10].

For small creepages, Kalker's linear theory [8] provides the following relationships between the creep forces and creepages:

$$\begin{aligned} \underline{F}_L = & \{ [f_{11L} (-\dot{x}_L \cdot \underline{e}_{1L}) \\ & + f_{12L} (-\underline{\omega}_L \cdot \underline{e}_{2L})] \underline{e}_{1L} \\ & + f_{22L} (\dot{x}_L \cdot \underline{e}_{2L}) \underline{e}_{2L} \} / V \end{aligned} \quad (5)$$

$$\begin{aligned} \underline{M}_L = & \{ [f_{11L} (\dot{x}_L \cdot \underline{e}_{1L}) \\ & + f_{22L} (-\underline{\omega}_L \cdot \underline{e}_{2L})] / V \end{aligned} \quad (6)$$

$$\begin{aligned} \underline{F}_R = & \{ [f_{11R} (-\dot{x}_R \cdot \underline{e}_{1R}) \\ & + f_{12R} (-\underline{\omega}_R \cdot \underline{e}_{2R})] \underline{e}_{1R} \\ & + f_{22R} (-\dot{x}_R \cdot \underline{e}_{2R}) \underline{e}_{2R} \} / V \end{aligned} \quad (7)$$

$$\begin{aligned} \underline{M}_R = & \{ [f_{11R} (\dot{x}_R \cdot \underline{e}_{1R}) \\ & + f_{22R} (-\underline{\omega}_R \cdot \underline{e}_{2R})] \underline{e}_{2R} \} / V \end{aligned} \quad (8)$$

The \underline{e}_{1L} , \underline{e}_{2L} , \underline{e}_{1R} and \underline{e}_{2R} systems of unit vectors are defined for the left and right wheels. The \underline{e}_1 and \underline{e}_2 vectors are in the plane of contact and are directed laterally and longitudinally, respectively. The \underline{e}_1 vector is along the inward normal to the contact plane. \underline{F}_L and \underline{M}_L are the vector creep force and moment of the rail acting on the left wheel while \underline{F}_R and \underline{M}_R act on the right wheel. \dot{x}_L and \dot{x}_R are the velocities of the left and right wheels relative to their respective rails at the contact points. If the rails are assumed to be rigid, these are the wheel contact point velocities. If the rails are flexible or if the wheelset is on a roller rig, \dot{x}_L and \dot{x}_R depend on the velocities of the rails or rollers as well. Similarly, $\underline{\omega}_L$ and $\underline{\omega}_R$ are the angular velocities of the left and right wheels relative to their respective rails. If the wheelset and rails are assumed to be rigid, then $\underline{\omega}_L = \underline{\omega}_R$ where $\underline{\omega}$ is the angular velocity of the wheelset. V is the forward speed of the wheelset. The parameters f_{11} , f_{12} , f_{22} , and f_{23} are the lateral, lateral-spin, spin, and longitudinal linear creep coefficients, respectively. The subscripts L and R refer to the left and right wheels, respectively. When these expressions are linearized and when (a) identical profiles are used on the left and right wheels, (b) the rail profile is the same for left and right rails, and (c) the loading is symmetrical about the vehicle centerline, then the creep coefficients for the left and right wheels are identical. Almost without exception, the yaw moments due to lateral spin and pure spin (\underline{M}_L and \underline{M}_R) are much smaller than the contribution to the yaw moment of the longitudinal creep forces. Consequently, in formulating the linear equations of motion, this contribution may be neglected if desired. However, the lateral force due to spin creep, $f_{12} (-\underline{\omega} \cdot \underline{e}_2) / V$ is generally not negligible although it is small if the contact angle between wheel and rail is small.

The linear creep coefficients may be calculated using the program based on Kalker's linear theory described in [11]. The values depend on the elastic properties of the wheel and rail, the radii of curvature of the surfaces at the contact zone, and the wheel load. For new, 33 inch diameter, AAR 1/20 wheels on rails with a 10 inch crown radius, these coefficients are:

$$f_{11} = 3552. (P)^{2/3} \text{ lb/wheel} \quad (9)$$

$$f_{12} = 1.1447 (P) \text{ ft lb/wheel} \quad (10)$$

$$f_{22} = 4.1006 \times 10^{-4} (P)^{4/3} \text{ lb ft}^2/\text{wheel} \quad (11)$$

$$f_{33} = 3839. (P)^{2/3} \text{ lb/wheel} \quad (12)$$

where P is the load carried by one wheel, i.e., one-half the axle load. Because of the wide variations of the actual values prevailing in the field (due to surface contamination, work-hardening of the wheels and rails, changing rail head radii of curvature along the track, etc.), it is recommended that several values in the range of 30 to 100% of the Kalker values be used in dynamic analyses. The sensitivity of the lateral dynamic response to changes in creep coefficients is highly configuration-dependent. No general statement can be made regarding this, and the safest procedure is to check this sensitivity for the configuration under study.

Suspension

The 9 degree of freedom model is intended to represent a conventional North American freight car with three piece trucks. This model does not have a distinct primary suspension. The suspension elements are considered to be parallel combinations of linear springs and viscous dampers. These are: (a) The warp suspension element (one per truck) opposes warping deformation of the truck frame. Contributions to this lumped element are made by the resistances to relative yaw at the interfaces between the wheelsets and sideframes and the sideframes and bolster. (b) The yaw suspension element (one per truck) opposes relative yaw between the car body and truck bolster at the centerplate. (c) The lateral suspension elements (two per truck) oppose relative lateral motions between the truck sideframes and the truck bolster. (d) The vertical suspension elements (two per truck) oppose relative roll between the car body and truck bolster.

The actual suspension of a three piece freight truck is highly nonlinear due to the presence of Coulomb friction, clearances and stops. One of the major difficulties facing the user of this program is the determination of equivalent linear values for these nonlinearities. Certain elements may be treated by linearization about the equilibrium position. However, Coulomb friction can only be treated by a quasi-linearization process such as the sinusoidal or random input describing function. This procedure for rail vehicle applications is described in [5].

Roadbed Inputs

The response of the freight car to roadbed disturbances is of interest in evaluating such matters as the riding quality, the vibration environment at any point on the vehicle, or the wheel-rail force levels. This computer program provides for the lateral alignment, u_a , and crosslevel disturbances, u_θ , shown in Figure 6.

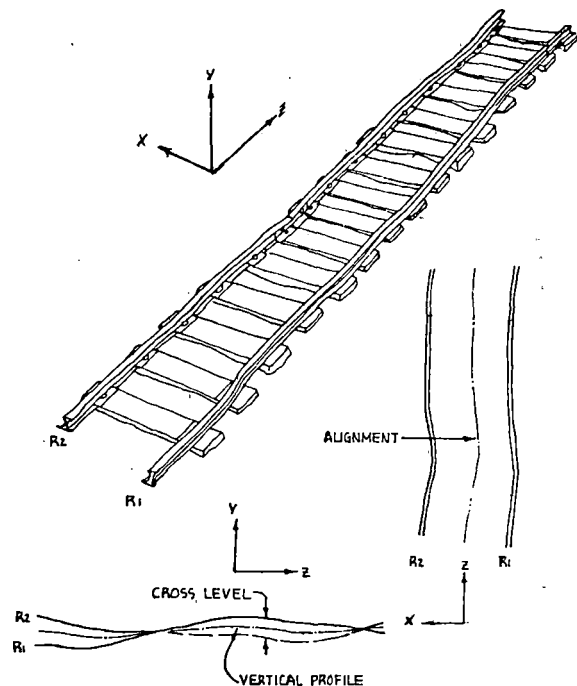


Figure 6. Roadbed Irregularities

The alignment disturbances enter the equations of motion through the wheel-rail geometry terms. Variation in alignment along the track leads to changes in the rolling radii difference and contact angle difference that, in turn, elicit a dynamic response from the vehicle. As a result, the alignment input terms appear in the creep force and gyroscopic force expressions.

The most dominant influence of the alignment variations on the vehicle motions is through the rolling radii difference and contact angle difference mechanisms. However, the time rate of change of lateral alignment will also give rise to a small wheelset roll velocity that in turn generates a lateral creep force and a gyroscopic force. The alignment time rate of change driving these effects should be interpreted as

$$\begin{aligned} \dot{u}_a &= du_a/dt = (du_a/dz)(dz/dt) \\ &= V(du_a/dz) \end{aligned} \quad (13)$$

Crosslevel disturbances were defined, in the analysis accompanying this program, as the rotation of the rail plane about a longitudinal axis relative to a fixed, level reference. The motions of the vehicle components, wheelsets,

sideframes, etc. were also referenced to the fixed level reference. As a result of these definitions, crosslevel disturbances appear in the vertical suspension forces between bolster and sideframe, and in the creep force and gravitational force expressions at the wheel-rail contact. The contributions to the latter are due to the relative lateral displacement that arises when the roadbed and wheelset rotate together without lateral wheelset movement, as well as to the relative lateral velocity at the wheel-rail contact that must accompany such movement. Both crosslevel displacement and its rate of change with time appear in the equations. The crosslevel rate of change with time, \dot{u}_ϕ , should be interpreted here, as follows,

$$du_\phi/dt = (du_\phi/dz)(dz/dt) = (du_\phi/dz)V \quad (14)$$

This lateral freight car response analysis provides for sinusoidal and random irregularities in the roadbed centerline alignment and/or the roadbed crosslevel. Because the model is linear, only the transfer function amplitudes between the input and the response variables are provided in the sinusoidal input analysis. A sum of the response to lateral alignment and crosslevel irregularities is not computed in the program.

The random characteristics of the centerline alignment and crosslevel disturbances are represented by spatial power spectral densities (PSD's) of the form

$$S_a(\Omega) = A_a / [\Omega^2(1 + \Omega^2/\Omega_c^2)] \quad (15)$$

[ft²/(rad/ft)]

$$S_s(\Omega) = A_s \Omega_c^2 / [(\Omega^2 + \Omega_c^2)(\Omega^2 + \Omega_s^2)] \quad (16)$$

[rad²/(rad/ft)]

where: Ω - spatial frequency, rad/ft
 A_a - alignment constant
 A_s - crosslevel constant
 Ω_c - long wavelength rolloff frequency
 Ω_s - short wavelength rolloff frequency

These single sided PSD expressions have been developed to represent the characteristics of existing roadbed [12].

ANALYSIS METHOD

The linear equations of motion for the forced response of the freight car to roadbed disturbances may be expressed in the following matrix form,

$$M\ddot{x} + C\dot{x} + Kx = B_{A1}\dot{u}_a + B_{A2}\ddot{u}_a + B_{\phi1}\dot{u}_\phi + B_{\phi2}\ddot{u}_\phi \quad (17)$$

where: x - displacement vector
 M, C, K - mass, damping, and stiffness matrices
 u_a - alignment input vector (one component/wheelset)
 u_ϕ - crosslevel input vector
 B_{A1}, B_{A2} - alignment input matrices
 $B_{\phi1}, B_{\phi2}$ - crosslevel input matrices

If we take the LaPlace transform of this equation, and recognize that we can obtain the transfer functions for the steady state response to a harmonic disturbance by letting $s = j\omega$, then we obtain the following complex matrix equation,

$$[(K - \omega^2 M) + j\omega C]X = [B_{A1} + j\omega B_{A2}]U_a + [B_{\phi1} + j\omega B_{\phi2}]U_\phi \quad (18)$$

A solution for the response X to either an alignment or a crosslevel input is computed in this program by inverting the matrix,

$$[(K - \omega^2 M) + j\omega C]$$

at each frequency of interest, and multiplying with the appropriate matrix on the right hand side of eq. (18), i.e. for alignment input:

$$X = [(K - \omega^2 M) + j\omega C]^{-1} [B_{A1} + j\omega B_{A2}]U_a \quad (19)$$

and for crosslevel input

$$X = [(K - \omega^2 M) + j\omega C]^{-1} [B_{\phi1} + j\omega B_{\phi2}]U_\phi \quad (20)$$

The input vectors u_a and u_ϕ consist of the values of these quantities at each wheelset. These variables are related by a time delay. We assume the vehicle is travelling at constant speed such that if

$$U_{a1} = A_x \cos \omega t \quad (21)$$

then the input at subsequent wheelsets is given by,

$$U_{ai} = A_x \cos (t - l_i/V) \quad (22)$$

where

l_i - distance from i th wheelset to leading wheelset.

These time delay terms may be expressed in terms of an in-phase and out of phase term,

$$U_{xi} = [A_x \cos(\omega l_i/V)] \cos \omega t + [A_x \sin(\omega l_i/V)] \sin \omega t \quad (23)$$

or, employing complex variable notation in terms of a real and imaginary component,

$$U_{xi} = A_x \cos(\omega l_i/V) + j A_x \sin(\omega l_i/V) \quad (24)$$

The complex notation is used in the program, and the input vector, U_x or $U_{\phi0}$, is reduced to the product of a time delay vector and a scalar defining the amplitude of the sinusoidal input. In a transfer function computation the scalar is taken as unity, and the input vector becomes,

$$U_\phi = U = \begin{bmatrix} 1 \\ \cos(\omega l_2/V) + j \sin(\omega l_2/V) \\ \cos(\omega l_3/V) + j \sin(\omega l_3/V) \\ \cos(\omega l_4/V) + j \sin(\omega l_4/V) \end{bmatrix} \quad (25)$$

The transfer functions are computed using the above matrices as follows:

$$\underline{T}_{Rx} = [(K-\omega^2M)+j\omega C]^{-1} [B_{x1} + j\omega B_{x2}]$$

$$\underline{x} \begin{bmatrix} 1 \\ \cos(\omega l_2/\sigma) + j\sin(\omega l_2/\sigma) \\ \cos(\omega l_3/V) + j\sin(\omega l_3/V) \\ \cos(\omega l_4/V) + j\sin(\omega l_4/V) \end{bmatrix} \quad (26)$$

$$\underline{T}_{R\theta} = [(K-\omega^2M)+j\omega C]^{-1} [B_{\theta 1} + j\omega B_{\theta 2}]$$

$$\underline{x} \begin{bmatrix} 1 \\ \cos(\omega l_2/\sigma) + j\sin(\omega l_2/\sigma) \\ \cos(\omega l_3/V) + j\sin(\omega l_3/V) \\ \cos(\omega l_4/V) + j\sin(\omega l_4/V) \end{bmatrix} \quad (27)$$

In the computer program, certain additional quantities such as the wheel-rail contact forces, the suspension displacements, and component accelerations are also computed. These quantities are linear combinations of the component displacements and velocities, and may

be computed directly from the transfer functions given in the equations above.

The power spectral densities (PSD's) of the displacements, velocities, and related quantities are computed as follows,

$$S_{xi}(f) = T_{Ri}^* T_{Ri} S_R(f) \quad (28)$$

where:

- S_{xi} - PSD for i th element of \underline{x}
- S_R - PSD for input (alignment or crosslevel)
- T_{Ri}^* - complex conjugate of T_{Ri}

Note that the input PSD must be appropriately transformed from the spatial domain to the time domain.

The root mean square (RMS) values for the response variables are obtained by integrating the PSD's over the frequency range specified as input. Although the mean square value is the integral of the PSD over all frequencies from 0 to ∞ , we find for the response predicted by this 9 DOF model that the error introduced by integration over a finite band width, roughly 0.1-20.0 Hz is small. The integration is handled numerically using the trapezoid rule.

PROGRAM DESCRIPTION

INTRODUCTION

The FR9DOF computer program consists of a main program and ten subroutines. The program is written in FORTRAN IV. Input data is handled in the main program in a format compatible with the 9 DOF eigenvalue program described in [3]. The main program calls subroutines SETUP, VEL and FREQ to compute various portions of the mass, damping, stiffness and roadbed input matrices. Subroutines DCMINV, DMULT and DDIV called from the main program invert the complex system matrix. The transfer functions, PSD's and RMS values are computed, and calls to PLOTA, PLOTB, PLOT C and PLOT D made to plot the PSD's.

Input to the program includes specification of the velocities at which the vehicle response is to be computed, the frequency range and frequency increment to be used in the computations.

The program prints the input data, the transfer functions, the PSD's and the RMS values for all the degrees of freedom as well as the centerplate contact position, the centerplate vertical force, and the net lateral wheel-rail contact force/wheelset at each wheelset. The transfer functions and PSD's are computed at frequency intervals evenly spaced on a logarithmic scale.

Plots are generated for the PSD's of the vehicle displacements. Transfer function magnitudes TRA and TRAI and PSD's are found by appropriate matrix multiplications.

MAIN PROGRAM AND SUBROUTINES

Listings for the main program and all subroutines may be found in the appendix. Each is briefly described below.

MAIN PROGRAM--FR9DOF

The main program handles all input and output, calls subroutines to set up the system matrices, calls the matrix inversion subroutine, computes the transfer function magnitudes and PSD's, integrates the PSD's to obtain RMS values, and calls plot routines to display the results.

The program flows as follows: After reading and echoing the input data, subroutine SETUP is called to initialize the velocity and frequency independent terms of the mass (M), damping (C), stiffness (K) and roadbed input (FCLR, FCLF, FAR, FAI) matrices. An outer loop computes the response at the velocities specified in the input data. A call to subroutine VEL at the head of this loop initializes the velocity dependent terms of the system matrices.

The transfer functions and PSD's are computed at each frequency in an inner loop. Subroutine FREQ is called early in this loop to compute the frequency dependent coefficients in the system matrices. The matrix inversion at each frequency is carried out by subroutine DCMINV.

At the bottom of the outer (velocity) loop the mean square values are computed by simple Euler integration of the PSD values, and the transfer functions, PSD's and RMS values are printed. Subroutine PLOTA is called to plot the results before returning for a new velocity value.

DCMINV (AR, AI, N, DR, DI, L, M)

Inverts a complex matrix using double precision computation. The matrix is supplied in arrays DR and DI and the inverse returned in the same arrays. N specifies the order of the matrix, and DR and DI return the real and imaginary portions of the determinant of the matrix. L and M are working arrays of dimension N used by the subroutine.

This subroutine calls DDIV and DMULT.

DDIV (AR, AI, BR, BI, CR, CI)

Performs double precision division of two complex numbers. AR and AI contain the dividend, BR and BI the divisor and CR and CI the resulting quotient.

DMULT (AR, AI, BR, BI, CR, CI)

Performs double precision multiplication of two complex numbers. The pairs (AR, AI) and (BR, BI) contain the multiplicands, and (CR, CI) the resulting product.

FREQ (FAI, FCLI, V, W)

This subroutine computes those terms of the input matrices that involve the frequency of the crosslevel or alignment input. These terms account for the time delay between the roadbed input at different wheelsets. The frequency and velocity, W and V are input to the subroutine and all the non-zero terms of the FCLI and FAI matrices are returned.

PLOTA (LABEL)

This subroutine sets up the axes for the PSD plots and writes a label to identify the run. The label is passed to the subroutine through the array LABEL. Subroutine PLOT C is called to draw the horizontal (frequency) axis and write the label.

PLOTB (FR, TPSD, TIPSD, FPSD, FIPSD, N, KI, V, S)

This subroutine draws the plots of the PSD's on the graphs prepared by PLOTA. The frequencies are supplied in array FR, the displacement PSD's in TPSD and TIPSD, and the force PSD's in FPSD and FIPSD. The number of points in each plot is N.

PLOTB (LABEL)

This subroutine draws the horizontal frequency axis for each plot and writes an identifying label at the top of each plot. The label is supplied in the array LABEL.

PLOTD (K1, S1, S2, IVEL)

This subroutine writes an identifying symbol and the speed associated with that symbol. This allows plots at different speeds to be plotted on the same axes.

SETUP (M, C, K, FAR, FCLR)

This subroutine computes the constant terms in the mass (M), damping (C), stiffness (K), alignment input (FAR) and crosslevel input (FCLR) matrices. The values for the computation are passed through labeled COMMON.

VEL (M, C, K, V)

The velocity dependent terms of the mass, damping and stiffness matrices are computed in this subroutine. Data for the computations are supplied from the main program and SETUP via COMMON blocks.

PROGRAM INPUT

The input parameters, listed in the order they are read, are given in Table 2.

Table 2. Program Input Parameters

Program Control Specifications

IVO	Initial Velocity	ft/sec
IVF	Final Velocity	ft/sec
IDV	Velocity Increment	ft/sec
FSTART	Lowest Frequency	Hz
FSTEP	Number of frequency values per cycle	
FSTOP	Highest Frequency	Hz
LABEL	Identifying label for the plots	

Track Properties

AX	Centerline Alignment PSD Coefficient	ft ² -rad/ft
APHI	Crosslevel PSD Coefficient	
OMGC	PSD Rolloff Frequency	rad/ft
OMGC	Crosslevel Cutoff Frequency	rad/ft

Vehicle Specifications

XMW	Mass of wheelset	slugs
XIW1	Mass moment of inertia of wheelset axle centerline	slugs ft ²
XIW2	Centroidal mass moment of inertia of wheelset in yaw	slugs ft ²
XMB	Centroidal mass of bolster	slugs

Table 2. Program Input Parameters (cont.)

XIB2	Centroidal mass moment of inertia of bolster in yaw	slugs ft ²
XIB3	Centroidal mass moment of inertia of bolster in roll	slugs ft ²
XMS	Mass of sideframe	slugs
XIS2	Centroidal mass moment of inertia of sideframe in yaw	slugs ft ²
XMC	Centroidal mass of car body	slugs
XIC2	Centroidal mass moment of inertia of carbody in yaw	slugs ft ²
XIC3	Centroidal mass moment of inertia carbody in roll	slugs ft ²
XIC23	Cross product of inertia of carbody	slugs ft ²
TL	Semi truck wheelbase	ft
D	One half distance between sideframes	ft
RO	Wheel rolling radius at equilibrium	ft
A	One half track gauge	ft
HCG	Vertical distance between bolster and carbody CG	ft
GAM1	Roll coefficient for Axle 1	
GAM2	Roll coefficient for Axle 2	
GAM3	Roll coefficient for Axle 3	
GAM4	Roll coefficient for Axle 4	
BDEL 1	Contact angle coefficient for axle 1	
BDEL 2	Contact angle coefficient for axle 2	
BDEL 3	Contact angle coefficient for axle 3	
BDEL 4	Contact angle coefficient for axle 4	
DEL01	Initial wheel/rail contact angle for axle 1	
DEL02	Initial wheel/rail contact angle for axle 2	
DEL03	Initial wheel/rail contact angle for axle 3	
DEL04	Initial wheel/rail contact angle for axle 4	
ALAM11	Conicity for axle 1	
ALAM12	Conicity for axle 2	
ALAM13	Conicity for axle 3	

Table 2.: Program Input Parameters (cont.)

ALAM14	Conicity for axle 4	
XKYF, XKYR	Vertical stiffness, sideframe to bolster, front and rear	lb/ft
XXXF, XKXR	Lateral stiffness, sideframe to bolster, front and rear	lb/ft
XKTWF, KXTWR	Truck warping stiffness, front and rear	lb-ft/rad
XKTCPF, XKTCPR	Centerplate stiffness, front and rear	lb-ft/rad
DYF, DYR	Vertical sideframe to bolster damping	lb-ft-sec/ft
DXF, DXR	Lateral sideframe to bolster damping	lb-ft-sec/rad
DTWF, DTWR	Truck warping damping, front and rear	lb-ft-sec/rad
DTCPF, DTCPR	Center plate damping, front and rear	lb-ft-sec/rad
CLF, CLF	Distance of carbody CG to truck, front and rear	ft
F11	Linear lateral creep coefficient	lb/wheel
F12	Linear lateral spin creep coefficient	lb-ft/wheel
F22	Linear spin creep coefficient	lb-ft ² /wheel
F33	Linear longitudinal creep coefficient	lb/wheel

Input Formats

The input format for this program is listed below. The system parameters must be input into the program in the arrangement shown. The input on each card is format free, which means that the input parameters can be punched anywhere in the columns 1-72, separated by blanks or commas.

Card #	Input Parameter	8	XMC, XIC2, XIC3, XIC23
		9	TL, D, RO, A
		10	HCG, CLF, CLR
		11	GAM1, GAM2, GAM3, GAM4
		12	BDEL1, BDEL2, BDEL3, BDEL4
1	IVO, IVF, IDV	13	DELO1, DELO2, DELO3, DELO4
2	FSTART, FSTEP, FSTOP	14	ALAM11, ALAM12, ALAM13, ALAM14
3	AX, APHI, OMGC, OMGS	15	F11, F12, F22, F33
4	LABEL	16	DYF, DXF, XKYF, XXXF
5	XMW, XIW1, XIW2	17	DYR, DXR, XKYR, XKXR
6	XMB, XIB2, XIB3	18	DTCPF, DTWF, XKTCPF, KXTWF
7	XMS, XIS2	19	DTCPR, DTWR, XKTCPR, KXTWR

PROGRAM OUTPUT

The program prints out, in order of appearance, the following:

1. Vehicle Parameters
2. Track Parameters
3. Vehicle Speed
4. Mass, Damping and Stiffness Parameters
5. Component Displacement PSD's for Centerline Alignment Input
6. Displacement and Alignment R.M.S. Values
7. Component Displacement PSD's for Crosslevel Input
8. Displacement and Crosslevel R.M.S. Values
9. Lateral Wheel-Rail and Centerplate Lateral Force for Alignment Input
10. Lateral R.M.S. Forces for Alignment Input
11. Lateral Wheel-Rail and Centerplate Force for Crosslevel Input
12. Lateral R.M.S. Forces for Crosslevel Input

In addition, the program prepares CALCOMP PSD plots for the leading truck lateral and warp displacements, the car body lateral and roll displacements, and the lateral wheel-rail contact forces at the leading axle of each truck. These plots are prepared for both alignment and crosslevel inputs.

Most of the output is self explanatory, as seen in the sample run presented in the next section. However, the displacement PSD's are only identified by number. These numbers refer to positions in the following state vector:

PSD(1), RMS(1)	Front truck lateral
PSD(2), RMS(2)	Front truck yaw
PSD(3), RMS(3)	Front truck warp
PSD(4), RMS(4)	Rear truck lateral
PSD(5), RMS(5)	Rear truck yaw
PSD(6), RMS(6)	Rear truck warp
PSD(7), RMS(7)	Car Body lateral
PSD(8), RMS(8)	Car Body yaw
PSD(9), RMS(9)	Car Body roll
SPD(10), RMS(10)	Track input

SAMPLE OUTPUT LISTING

EXAMPLE PROBLEM TYPICAL OF OPEN HOPPER CARS

00004

MASS PROPERTIES

XMC	(MASS OF THE CAR BODY)	= 0.1102E+04	SLUGS
XMB	(MASS OF THE BOLSTER)	= 0.3610E+02	SLUGS
XMS	(MASS OF THE SIDEFRAME)	= 0.2400E+02	SLUGS
XMW	(MASS OF THE WHEELSET)	= 0.7660E+02	SLUGS
XIC2	(MOMENT OF INERTIA OF THE CAR BODY IN YAW)	= 0.2340E+06	SLUG-FT**2
XIC3	(MOMENT OF INERTIA OF THE CAR BODY IN ROLL)	= 0.1300E+05	SLUG-FT**2
XIC23	(CROSS PRODUCT OF INERTIA FOR CAR BODY)	= 0.0	SLUG-FT**2
XIB2	(MOMENT OF INERTIA OF THE BOLSTER IN YAW)	= 0.1786E+03	SLUG-FT**2
XIB3	(MOMENT OF INERTIA OF THE BOLSTER IN ROLL)	= 0.1786E+03	SLUG-FT**2
XIS2	(MOMENT OF INERTIA OF THE SIDEFRAME IN YAW)	= 0.7760E+02	SLUG-FT**2
XIW1	(MOMENT OF INERTIA OF THE WHEELSET ABOUT AXLE)	= 0.5310E+02	SLUG-FT**2
XIW2	(MOMENT OF INERTIA OF THE WHEELSET IN YAW)	= 0.4485E+03	SLUG-FT**2

STIFFNESS PROPERTIES

XKXF	(LATERAL STIFFNESS, SIDEFRAME TO BOLSTER -FRONT-)	= 0.2400E+05	LB/FT
XKXR	(LATERAL STIFFNESS, SIDEFRAME TO BOLSTER -REAR-)	= 0.2400E+05	LB/FT
XKYF	(VERTICAL STIFFNESS, SIDEFRAME TO BOLSTER -FRONT-)	= 0.2658E+06	LB/FT
XKYR	(VERTICAL STIFFNESS, SIDEFRAME TO BOLSTER -REAR-)	= 0.2658E+06	LB/FT
XKICPF	(CENTERPLATE STIFFNESS -FRONT-)	= 0.0	FT-LB/RAD
XKICPR	(CENTERPLATE STIFFNESS -REAR-)	= 0.0	FT-LB/RAD
XKITWF	(TRUCK WARPING STIFFNESS -FRONT-)	= 0.3810E+07	FT-LB/RAD
XKITWR	(TRUCK WARPING STIFFNESS -REAR-)	= 0.3810E+07	FT-LB/RAD

DAMPING PROPERTIES

DIWF	(WARPING DAMPING -FRONT-)	= 0.1322E+05	LB-SEC/FT
DIWR	(WARPING DAMPING -REAR-)	= 0.1322E+05	LB-SEC/FT
DXF	(LATERAL SIDEFRAME TO BOLSTER DAMPING -FRONT-)	= 0.9520E+04	LB-SEC/FT
DXR	(LATERAL SIDEFRAME TO BOLSTER DAMPING -REAR-)	= 0.9520E+04	LB-SEC/FT
DYF	(VERTICAL SIDEFRAME TO BOLSTER DAMPING -FRONT-)	= 0.3035E+04	LB-SEC/FT
DYR	(VERTICAL SIDEFRAME TO BOLSTER DAMPING -REAR-)	= 0.3035E+04	LB-SEC/FT
DICPF	(CENTERPLATE DAMPING -FRONT-)	= 0.2220E+04	LB-SEC/FT
DICPR	(CENTERPLATE DAMPING -REAR-)	= 0.2220E+04	LB-SEC/FT

DIMENSIONS

A	(SEMI-DISTANCE BETWEEN WHEEL CONTACT POINTS)	= 0.2460E+01 FT
D	(SEMI-SPACING OF SIDEFRAE CENTER CF GRAVITIES)	= 0.3250E+01 FT
HCG	(VERTICAL DISTANCE BETWEEN TRUCK CG AND BODY CG)	= 0.299CE+01 FT
TL	(SEMI TRUCK WHEELBASE)	= 0.2833E+01 FT
CLF	(DISTANCE FRCM BODY CG TC FRCNT TRUCK)	= 0.1685E+02 FT
CLR	(DISTANCE FROM BODY CG TC REAR TRUCK)	= 0.1685E+02 FT
RO	(WHEEL ROLLING RADIUS)	= 0.1375E+01 FT

WHEEL CHARACTERISTICS

GAM1	(ROLL COEFFICIENT, AXLE 1)	= 0.5000E-01
GAM2	(ROLL COEFFICIENT, AXLE 2)	= 0.5000E-01
GAM3	(ROLL COEFFICIENT, AXLE 3)	= 0.5000E-01
GAM4	(ROLL COEFFICIENT, AXLE 4)	= 0.5000E-01

BDEL1	(CONTACT ANGLE COEFFICIENT, AXLE 1)	= 0.0
BDEL2	(CONTACT ANGLE COEFFICIENT, AXLE 2)	= 0.0
BDEL3	(CONTACT ANGLE COEFFICIENT, AXLE 3)	= 0.0
BDEL4	(CONTACT ANGLE COEFFICIENT, AXLE 4)	= 0.0

DELO1	(INITIAL WHEEL/RAIL CONTACT ANGLE, AXLE 1)	= 0.5000E-01
DELO2	(INITIAL WHEEL/RAIL CONTACT ANGLE, AXLE 2)	= 0.5000E-01
DELO3	(INITIAL WHEEL/RAIL CONTACT ANGLE, AXLE 3)	= 0.5000E-01
DELO4	(INITIAL WHEEL/RAIL CONTACT ANGLE, AXLE 4)	= 0.5000E-01

ALAM11	(CONICITY, AXLE 1)	= 0.5000E-01
ALAM12	(CONICITY, AXLE 2)	= 0.5000E-01
ALAM13	(CONICITY, AXLE 3)	= 0.5000E-01
ALAM14	(CONICITY, AXLE 4)	= 0.5000E-01

CREEP COEFFICIENTS

F11	(LATERAL CREEP COEFFICIENT)	= 0.6359E+06 LB
F12	(LATERAL/SPIN CREEP COEFFICIENT)	= 0.3633E+04 LB-FT
F22	(SPIN CREEP COEFFICIENT)	= 0.2410E+02 LB-FT**2
F33	(LONGITUDINAL CREEP COEFFICIENT)	= 0.6580E+06 LB

TRACK PROPERTIES

AX	(CENTERLINE ALIGNMENT PSD COEFFICIENT)	= 0.1104E-06 FT**2-RAD/FT
APHI	(CROSS LEVEL PSD COEFFICIENT)	= 0.1104E-06 FT**2-RAD/FT
OMGC	(PSD ROLL OFF FREQUENCY)	= 0.2513E+00 RAD/FT
OMGS	(CROSS LEVEL PSD CONSTANT)	= 0.1340E+00 RAD/FT

VELOCITY= 40.00FT/SEC

K-MATRIX

0.485E+05	-.254E+07	-.254E+07	0.0	0.0	0.0	-.480E+05	-.809E+06	-.144E+06
0.235E+06	0.156E+05	0.114E+05	0.0	0.0	0.0	0.0	0.0	0.0
0.235E+06	0.114E+05	0.382E+07	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.485E+05	-.254E+07	-.254E+07	-.480E+05	0.809E+06	-.144E+06
0.0	0.0	0.0	0.235E+06	0.156E+05	0.114E+05	0.0	0.0	0.0
0.0	0.0	0.0	0.235E+06	0.114E+05	0.382E+07	0.0	0.0	0.0
-.480E+05	0.0	0.0	-.480E+05	0.0	0.0	0.960E+05	0.0	0.287E+06
-.809E+06	0.0	0.0	0.809E+06	0.0	0.0	0.0	0.273E+08	0.0
-.258E+06	0.0	0.0	-.258E+06	0.0	0.0	0.287E+06	0.0	0.120E+08

C-MATRIX

0.826E+05	0.301E+03	0.301E+03	0.0	0.0	0.0	-.190E+05	-.321E+06	-.569E+05
-.311E+03	0.925E+06	0.400E+06	0.0	0.0	0.0	0.0	-.222E+04	0.0
-.311E+03	0.400E+06	0.414E+06	0.0	0.0	0.0	0.0	-.222E+04	0.0
0.0	0.0	0.0	0.826E+05	0.301E+03	0.301E+03	-.190E+05	0.321E+06	-.569E+05
0.0	0.0	0.0	-.311E+03	0.925E+06	0.400E+06	0.0	-.222E+04	0.0
0.0	0.0	0.0	-.311E+03	0.400E+06	0.414E+06	0.0	-.222E+04	0.0
-.190E+05	0.0	0.0	-.190E+05	0.0	0.0	0.381E+05	0.0	0.114E+06
-.321E+06	-.222E+04	-.222E+04	0.321E+06	-.222E+04	-.222E+04	0.0	0.108E+08	0.0
-.582E+05	0.0	0.0	-.582E+05	0.0	0.0	0.114E+06	0.0	0.469E+06

M-MATRIX

0.201E+03	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.297E+04	0.158E+04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.158E+04	0.158E+04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.201E+03	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.297E+04	0.158E+04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.158E+04	0.158E+04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.117E+04	0.0	0.216E+03
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.254E+06	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.140E+05

*****PSD VALUES FOR ALIGNMENT INPUTS*****

FREQUENCY	PSD (1)	PSD (2)	PSD (3)	PSD (4)	PSD (5)	PSD (6)	PSD (7)	PSD (8)	PSD (9)
0.10000	.7648E-04	.1770E-07	.2252E-09	.7648E-04	.1772E-07	.2255E-09	.7156E-04	.1856E-07	.4358E-10
0.10593	.6877E-04	.1784E-07	.2426E-09	.6878E-04	.1787E-07	.2429E-09	.6383E-04	.1869E-07	.4717E-10
0.11220	.6192E-04	.1801E-07	.2628E-09	.6192E-04	.1804E-07	.2631E-09	.5694E-04	.1883E-07	.5123E-10
0.11885	.5581E-04	.1820E-07	.2860E-09	.5582E-04	.1823E-07	.2865E-09	.5079E-04	.1899E-07	.5580E-10
0.12589	.5039E-04	.1841E-07	.3129E-09	.5039E-04	.1845E-07	.3135E-09	.4532E-04	.1918E-07	.6095E-10
0.13335	.4556E-04	.1866E-07	.3440E-09	.4557E-04	.1871E-07	.3448E-09	.4044E-04	.1940E-07	.6675E-10
0.14125	.4128E-04	.1894E-07	.3801E-09	.4129E-04	.1900E-07	.3810E-09	.3609E-04	.1964E-07	.7326E-10
0.14962	.3748E-04	.1927E-07	.4220E-09	.3749E-04	.1933E-07	.4232E-09	.3221E-04	.1992E-07	.8058E-10
0.15849	.3411E-04	.1965E-07	.4707E-09	.3412E-04	.1972E-07	.4722E-09	.2876E-04	.2024E-07	.8881E-10
0.16788	.3113E-04	.2008E-07	.5277E-09	.3115E-04	.2017E-07	.5297E-09	.2568E-04	.2061E-07	.9805E-10
0.17783	.2851E-04	.2059E-07	.5947E-09	.2852E-04	.2069E-07	.5972E-09	.2294E-04	.2104E-07	.1084E-09
0.18836	.2620E-04	.2119E-07	.6739E-09	.2622E-04	.2130E-07	.6770E-09	.2050E-04	.2154E-07	.1201E-09
0.19953	.2418E-04	.2189E-07	.7680E-09	.2420E-04	.2202E-07	.7720E-09	.1832E-04	.2213E-07	.1332E-09
0.21135	.2243E-04	.2273E-07	.8807E-09	.2246E-04	.2287E-07	.8859E-09	.1639E-04	.2282E-07	.1480E-09
0.22387	.2093E-04	.2372E-07	.1017E-08	.2096E-04	.2389E-07	.1024E-08	.1467E-04	.2364E-07	.1646E-09
0.23714	.1966E-04	.2492E-07	.1183E-08	.1970E-04	.2512E-07	.1192E-08	.1314E-04	.2462E-07	.1834E-09
0.25119	.1862E-04	.2639E-07	.1389E-08	.1866E-04	.2662E-07	.1401E-08	.1178E-04	.2580E-07	.2046E-09
0.26607	.1780E-04	.2819E-07	.1647E-08	.1785E-04	.2847E-07	.1662E-08	.1057E-04	.2724E-07	.2288E-09

0.28184	.1722E-04	.3045E-07	.1976E-08	.1727E-04	.3079E-07	.1997E-08	.9506E-05	.2903E-07	.2564E-09
0.29854	.1688E-04	.3334E-07	.2404E-08	.1694E-04	.3374E-07	.2432E-08	.8568E-05	.3129E-07	.2881E-09
0.31623	.1683E-04	.3711E-07	.2975E-08	.1691E-04	.3760E-07	.3013E-08	.7747E-05	.3421E-07	.3250E-09
0.33496	.1714E-04	.4215E-07	.3760E-08	.1724E-04	.4277E-07	.3813E-08	.7037E-05	.3805E-07	.3684E-09
0.35481	.1792E-04	.4913E-07	.4877E-08	.1804E-04	.4991E-07	.4952E-08	.6431E-05	.4330E-07	.4205E-09
0.37584	.1938E-04	.5920E-07	.6541E-08	.1953E-04	.6022E-07	.6650E-08	.5929E-05	.5074E-07	.4845E-09
0.39811	.2190E-04	.7449E-07	.9161E-08	.2210E-04	.7585E-07	.9324E-08	.5535E-05	.6180E-07	.5656E-09
0.42169	.2621E-04	.9921E-07	.1358E-07	.2646E-04	.1010E-06	.1382E-07	.5253E-05	.7923E-07	.6718E-09
0.44668	.3374E-04	.1420E-06	.2164E-07	.3400E-04	.1443E-06	.2197E-07	.5075E-05	.1084E-06	.8133E-09
0.47315	.4672E-04	.2185E-06	.3765E-07	.4671E-04	.2200E-06	.3730E-07	.4873E-05	.1578E-06	.9799E-09
0.50118	.6306E-04	.3274E-06	.6176E-07	.6165E-04	.3221E-06	.6074E-07	.3971E-05	.2207E-06	.1004E-08
0.53088	.5797E-04	.3339E-06	.7004E-07	.5535E-04	.3202E-06	.6715E-07	.1627E-05	.2086E-06	.5207E-09
0.56234	.3057E-04	.1952E-06	.4551E-07	.2948E-04	.1887E-06	.4397E-07	.1902E-06	.1134E-06	.7865E-10
0.59566	.1355E-04	.9578E-07	.2480E-07	.1332E-04	.9413E-07	.2437E-07	.1722E-08	.5117E-07	.5544E-12
0.63095	.6285E-05	.4917E-07	.1413E-07	.6265E-05	.4887E-07	.1404E-07	.6501E-07	.2371E-07	.3861E-10
0.66834	.3148E-05	.2722E-07	.8668E-08	.3167E-05	.2724E-07	.8674E-08	.1207E-06	.1160E-07	.9244E-10
0.70794	.1681E-05	.1605E-07	.5658E-08	.1702E-05	.1612E-07	.5684E-08	.1431E-06	.5895E-08	.1398E-09
0.74989	.9424E-06	.9922E-08	.3868E-08	.9586E-06	.9987E-08	.3894E-08	.1418E-06	.3051E-08	.1764E-09
0.79432	.5481E-06	.6357E-08	.2735E-08	.5589E-06	.6403E-08	.2756E-08	.1273E-06	.1577E-08	.2022E-09
0.84139	.3277E-06	.4181E-08	.1982E-08	.3345E-06	.4211E-08	.1997E-08	.1070E-06	.7979E-09	.2176E-09
0.89125	.2001E-06	.2805E-08	.1461E-08	.2040E-06	.2822E-08	.1471E-08	.8523E-07	.3861E-09	.2231E-09
0.94406	.1241E-06	.1909E-08	.1090E-08	.1262E-06	.1918E-08	.1096E-08	.6477E-07	.1730E-09	.2193E-09
0.99999	.7785E-07	.1313E-08	.8197E-09	.7883E-07	.1317E-08	.8227E-09	.4696E-07	.6804E-10	.2071E-09
1.02919	.6186E-07	.1092E-08	.7118E-09	.6248E-07	.1095E-08	.7138E-09	.3926E-07	.3941E-10	.1983E-09
1.05925	.4923E-07	.9094E-09	.6184E-09	.4960E-07	.9111E-09	.6197E-09	.3240E-07	.2097E-10	.1878E-09
1.09018	.3922E-07	.7583E-09	.5374E-09	.3942E-07	.7593E-09	.5381E-09	.2636E-07	.9765E-11	.1758E-09
1.12201	.3127E-07	.6329E-09	.4668E-09	.3136E-07	.6334E-09	.4672E-09	.2114E-07	.3564E-11	.1627E-09
1.15477	.2494E-07	.5286E-09	.4053E-09	.2496E-07	.5288E-09	.4054E-09	.1668E-07	.7164E-12	.1486E-09
1.18849	.1989E-07	.4417E-09	.3515E-09	.1988E-07	.4417E-09	.3515E-09	.1293E-07	.4073E-15	.1335E-09
1.22320	.1585E-07	.3691E-09	.3044E-09	.1584E-07	.3691E-09	.3044E-09	.9826E-08	.5309E-12	.1187E-09
1.25891	.1263E-07	.3085E-09	.2633E-09	.1262E-07	.3085E-09	.2633E-09	.7308E-08	.1680E-11	.1035E-09
1.29567	.1004E-07	.2577E-09	.2272E-09	.1005E-07	.2578E-09	.2273E-09	.5304E-08	.3017E-11	.8849E-10
1.33351	.7975E-08	.2153E-09	.1956E-09	.7998E-08	.2155E-09	.1958E-09	.3743E-08	.4265E-11	.7396E-10
1.37245	.6320E-08	.1798E-09	.1680E-09	.6359E-08	.1800E-09	.1683E-09	.2557E-08	.5258E-11	.6023E-10
1.41252	.4998E-08	.1500E-09	.1439E-09	.5049E-08	.1503E-09	.1442E-09	.1681E-08	.5918E-11	.4753E-10
1.45377	.3942E-08	.1252E-09	.1228E-09	.4000E-08	.1254E-09	.1232E-09	.1055E-08	.6227E-11	.3611E-10
1.49622	.3101E-08	.1043E-09	.1044E-09	.3161E-08	.1046E-09	.1048E-09	.6254E-09	.6209E-11	.2614E-10
1.53991	.2434E-08	.8690E-10	.8847E-10	.2489E-08	.8718E-10	.8885E-10	.3444E-09	.5914E-11	.1775E-10
1.58487	.1905E-08	.7234E-10	.7462E-10	.1953E-08	.7258E-10	.7494E-10	.1714E-09	.5408E-11	.1104E-10
1.63115	.1487E-08	.6018E-10	.6262E-10	.1524E-08	.6037E-10	.6288E-10	.7349E-10	.4760E-11	.5990E-11
1.67878	.1159E-08	.5003E-10	.5228E-10	.1184E-08	.5016E-10	.5246E-10	.2440E-10	.4037E-11	.2561E-11
1.72780	.9023E-09	.4157E-10	.4339E-10	.9143E-09	.4164E-10	.4348E-10	.4517E-11	.3298E-11	.6261E-12
1.77826	.7017E-09	.3452E-10	.3577E-10	.7021E-09	.3454E-10	.3578E-10	.2668E-14	.2592E-11	.9790E-15
1.83018	.5455E-09	.2865E-10	.2928E-10	.5363E-09	.2863E-10	.2921E-10	.1890E-11	.1954E-11	.4474E-12
1.88362	.4239E-09	.2377E-10	.2376E-10	.4079E-09	.2372E-10	.2364E-10	.5069E-11	.1407E-11	.1687E-11
1.93863	.3294E-09	.1972E-10	.1910E-10	.3093E-09	.1965E-10	.1894E-10	.7234E-11	.9611E-12	.3417E-11
1.99523	.2556E-09	.1636E-10	.1518E-10	.2344E-09	.1629E-10	.1502E-10	.7896E-11	.6168E-12	.5331E-11
2.05350	.1978E-09	.1357E-10	.1192E-10	.1780E-09	.1350E-10	.1176E-10	.7523E-11	.3662E-12	.7143E-11
2.11346	.1522E-09	.1126E-10	.9211E-11	.1356E-09	.1120E-10	.9079E-11	.6869E-11	.1961E-12	.8605E-11
2.17517	.1162E-09	.9344E-11	.6991E-11	.1038E-09	.9306E-11	.6894E-11	.6532E-11	.9040E-13	.9534E-11
2.23869	.8759E-10	.7763E-11	.5190E-11	.7976E-10	.7741E-11	.5130E-11	.6737E-11	.3241E-13	.9823E-11
2.30406	.6491E-10	.6457E-11	.3750E-11	.6131E-10	.6448E-11	.3723E-11	.7329E-11	.6614E-14	.9454E-11
2.37134	.4707E-10	.5380E-11	.2619E-11	.4687E-10	.5379E-11	.2618E-11	.7905E-11	.1762E-16	.8496E-11
2.44058	.3323E-10	.4492E-11	.1750E-11	.3534E-10	.4496E-11	.1764E-11	.8021E-11	.2759E-14	.7094E-11
2.51185	.2275E-10	.3762E-11	.1102E-11	.2605E-10	.3766E-11	.1122E-11	.7395E-11	.8219E-14	.5450E-11
2.58520	.1507E-10	.3160E-11	.6374E-12	.1860E-10	.3163E-11	.6566E-12	.6025E-11	.1267E-13	.3783E-11
2.66069	.9688E-11	.2666E-11	.3232E-12	.1274E-10	.2666E-11	.3369E-12	.4192E-11	.1464E-13	.2301E-11
2.73838	.6124E-11	.2259E-11	.1293E-12	.8325E-11	.2258E-11	.1367E-12	.2346E-11	.1413E-13	.1156E-11
2.81834	.3913E-11	.1924E-11	.2944E-13	.5180E-11	.1923E-11	.3199E-13	.9208E-12	.1194E-13	.4180E-12
2.90064	.2634E-11	.1649E-11	.7433E-15	.3098E-11	.1648E-11	.9537E-15	.1566E-12	.9007E-14	.6725E-13
2.98534	.1927E-11	.1420E-11	.2402E-13	.1833E-11	.1421E-11	.2392E-13	.8526E-14	.6136E-14	.3646E-14
3.07251	.1511E-11	.1230E-11	.8355E-13	.1129E-11	.1233E-11	.8405E-13	.1976E-12	.3785E-14	.8478E-13
3.16223	.1206E-11	.1072E-11	.1668E-12	.7614E-12	.1075E-11	.1678E-12	.3831E-12	.2102E-14	.1762E-12
3.25457	.9225E-12	.9377E-12	.2640E-12	.5638E-12	.9406E-12	.2651E-12	.3660E-12	.1025E-14	.1973E-12
3.34960	.6479E-12	.8235E-12	.3676E-12	.4383E-12	.8252E-12	.3684E-12	.1920E-12	.4061E-15	.1420E-12
3.44741	.4134E-12	.7253E-12	.4712E-12	.3392E-12	.7258E-12	.4719E-12	.7683E-13	.9959E-16	.6077E-13
3.54808	.2552E-12	.6399E-12	.5698E-12	.2514E-12	.6399E-12	.5700E-12	.1949E-12	.1343E-17	.1295E-13
3.65168	.1856E-12	.5649E-12	.6590E-12	.1754E-12	.5651E-12	.6577E-12	.5023E-12	.4182E-16	.2079E-13
3.75831	.1825E-12	.4985E-12	.7349E-12	.1202E-12	.4994E-12	.7313E-12	.7530E-12	.1634E-15	.5663E-13
3.86806	.2024E-12	.4394E-12	.7952E-12	.9697E-13	.4407E-12	.7893E-12	.7125E-12	.3056E-15	.7265E-13

3.98101	.2051E-12	.3866E-12	.8383E-12	.1082E-12	.3877E-12	.8323E-12	.3856E-12	.4100E-15	.4702E-13
4.09725	.1740E-12	.3393E-12	.8647E-12	.1377E-12	.3397E-12	.8618E-12	.5249E-13	.4366E-15	.7244E-14
4.21690	.1194E-12	.2968E-12	.8756E-12	.1548E-12	.2964E-12	.8785E-12	.6921E-13	.3790E-15	.1049E-13
4.34003	.6517E-13	.2584E-12	.8734E-12	.1344E-12	.2576E-12	.8820E-12	.5869E-12	.2643E-15	.9641E-13
4.46676	.2899E-13	.2235E-12	.8601E-12	.7897E-13	.2228E-12	.8710E-12	.1411E-11	.1371E-15	.2493E-12
4.59719	.1246E-13	.1917E-12	.8373E-12	.2178E-13	.1914E-12	.8452E-12	.2111E-11	.4027E-16	.3993E-12
4.73143	.5629E-14	.1628E-12	.8055E-12	.3648E-14	.1628E-12	.8065E-12	.2294E-11	.4774E-18	.4638E-12
4.86959	.1465E-14	.1365E-12	.7649E-12	.3914E-13	.1366E-12	.7586E-12	.1863E-11	.2383E-16	.4025E-12
5.01179	.6000E-14	.1129E-12	.7156E-12	.1003E-12	.1130E-12	.7060E-12	.1069E-11	.9614E-16	.2470E-12
5.15813	.3367E-13	.9198E-13	.6591E-12	.1360E-12	.9198E-13	.6516E-12	.3418E-12	.1839E-15	.8452E-13
5.30875	.8986E-13	.7375E-13	.5977E-12	.1150E-12	.7374E-13	.5962E-12	.9842E-14	.2404E-15	.2611E-14
5.46377	.1563E-12	.5808E-13	.5348E-12	.5774E-13	.5814E-13	.5388E-12	.1132E-12	.2264E-15	.3219E-13
5.62332	.1966E-12	.4478E-13	.4731E-12	.2336E-13	.4489E-13	.4790E-12	.4223E-12	.1410E-15	.1292E-12
5.78752	.1832E-12	.3363E-13	.4142E-12	.5800E-13	.3371E-13	.4178E-12	.6344E-12	.3835E-16	.2091E-12
5.95652	.1261E-12	.2443E-13	.3584E-12	.1476E-12	.2442E-13	.3579E-12	.5901E-12	.1251E-17	.2098E-12
6.13045	.7313E-13	.1705E-13	.3052E-12	.2240E-12	.1697E-13	.3026E-12	.3522E-12	.7333E-16	.1352E-12
6.30946	.7348E-13	.1138E-13	.2543E-12	.2261E-12	.1130E-13	.2515E-12	.1087E-12	.2060E-15	.4509E-13
6.49370	.1324E-12	.7286E-14	.2067E-12	.1607E-12	.7272E-14	.2062E-12	.2314E-14	.2841E-15	.1039E-14
6.68332	.2010E-12	.4612E-14	.1638E-12	.9753E-13	.4649E-14	.1651E-12	.3376E-13	.7049E-17	.1633E-13
6.87848	.2191E-12	.3157E-14	.1267E-12	.9773E-13	.3194E-14	.1280E-12	.1016E-12	.9239E-16	.5301E-13
7.07933	.1735E-12	.2716E-14	.9546E-13	.1494E-12	.2722E-14	.9565E-13	.1163E-12	.2692E-17	.6516E-13
7.28605	.1111E-12	.3093E-14	.6945E-13	.1847E-12	.3078E-14	.6885E-13	.7094E-13	.4002E-16	.4252E-13
7.49881	.8656E-13	.4093E-14	.4800E-13	.1600E-12	.4081E-14	.4746E-13	.1834E-13	.1383E-15	.1169E-13
7.71778	.1044E-12	.5520E-14	.3085E-13	.1036E-12	.5518E-14	.3082E-13	.2275E-17	.1678E-15	.1481E-17
7.94314	.1209E-12	.7189E-14	.1801E-13	.7161E-13	.7188E-14	.1821E-13	.1018E-13	.9491E-16	.7140E-14
8.17509	.1029E-12	.8940E-14	.9160E-14	.7644E-13	.8939E-14	.9247E-14	.1937E-13	.1338E-16	.1402E-13
8.41380	.6524E-13	.1064E-13	.3655E-14	.8174E-13	.1064E-13	.3616E-14	.1390E-13	.7049E-17	.1026E-13
8.65949	.4127E-13	.1215E-13	.7959E-15	.6269E-13	.1215E-13	.7668E-15	.3590E-14	.4388E-16	.2668E-14
8.91235	.3649E-13	.1336E-13	.4028E-16	.3567E-13	.1336E-13	.4100E-16	.4816E-17	.4852E-16	.3522E-17
9.17260	.3189E-13	.1418E-13	.8797E-15	.2224E-13	.1417E-13	.8696E-15	.1693E-14	.1833E-16	.1231E-14
9.44044	.1954E-13	.1456E-13	.2748E-14	.1794E-13	.1456E-13	.2743E-14	.2159E-14	.3943E-18	.1540E-14
9.71611	.8530E-14	.1450E-13	.5134E-14	.1121E-13	.1450E-13	.5150E-14	.7508E-15	.3214E-17	.5293E-15
9.99982	.3556E-14	.1400E-13	.7647E-14	.4077E-14	.1400E-13	.7656E-14	.2206E-16	.4108E-17	.1600E-16
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10.90165	.7850E-15	.1032E-13	.1287E-13	.9754E-15	.1032E-13	.1286E-13	.9083E-16	.2585E-18	.1951E-16
11.21998	.2843E-14	.8640E-14	.1327E-13	.3046E-14	.8640E-14	.1326E-13	.8250E-17	.2789E-17	.2187E-17
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11.88481	.1006E-13	.5204E-14	.1192E-13	.1023E-13	.5203E-14	.1192E-13	.1026E-14	.1542E-19	.2562E-15
12.23185	.1177E-13	.3649E-14	.1043E-13	.1403E-13	.3648E-14	.1041E-13	.4375E-15	.7136E-17	.1009E-15
12.58903	.1628E-13	.2318E-14	.8582E-14	.1459E-13	.2318E-14	.8583E-14	.1674E-15	.1103E-16	.3526E-16
12.95663	.1941E-13	.1271E-14	.6589E-14	.1798E-13	.1272E-14	.6593E-14	.1579E-14	.8914E-18	.3021E-15
13.33498	.1760E-13	.5411E-15	.4670E-14	.2043E-13	.5409E-15	.4661E-14	.9437E-15	.6091E-17	.1634E-15
13.72436	.1848E-13	.1293E-15	.2959E-14	.1748E-13	.1299E-15	.2957E-14	.6323E-16	.1213E-16	.9877E-17
14.12512	.1849E-13	.1159E-16	.1588E-14	.1717E-13	.1160E-16	.1589E-14	.1336E-14	.1043E-17	.1863E-15
14.53758	.1405E-13	.1330E-15	.6450E-15	.1591E-13	.1331E-15	.6425E-15	.6270E-15	.4578E-17	.7965E-16
14.96209	.1213E-13	.4213E-15	.1309E-15	.1127E-13	.4212E-15	.1308E-15	.1022E-15	.6321E-17	.1169E-16
15.39899	.9196E-14	.7918E-15	.8946E-17	.9044E-14	.7917E-15	.8958E-17	.6789E-15	.3219E-19	.7011E-16
15.84865	.5405E-14	.1160E-14	.1901E-15	.5879E-14	.1160E-14	.1907E-15	.8591E-16	.2468E-17	.8015E-17
16.31143	.3287E-14	.1451E-14	.5573E-15	.2986E-14	.1451E-14	.5573E-15	.1078E-15	.8359E-18	.9118E-17
16.78772	.1232E-14	.1612E-14	.9808E-15	.1322E-14	.1612E-14	.9811E-15	.7030E-16	.1168E-18	.5446E-17
17.27792	.2180E-15	.1616E-14	.1344E-14	.2117E-15	.1616E-14	.1344E-14	.4526E-18	.9869E-19	.3377E-19
17.78244	.2384E-16	.1467E-14	.1559E-14	.2359E-16	.1467E-14	.1559E-14	.1707E-17	.3400E-22	.6600E-19
18.30170	.4878E-15	.1198E-14	.1584E-14	.5074E-15	.1198E-14	.1583E-14	.2063E-17	.1997E-18	.1008E-18
18.83611	.1467E-14	.8624E-15	.1420E-14	.1391E-14	.8624E-15	.1420E-14	.7288E-16	.8885E-19	.3307E-17
19.38612	.2320E-14	.5245E-15	.1117E-14	.2468E-14	.5244E-15	.1117E-14	.3576E-16	.6880E-18	.1473E-17
19.95219	.3350E-14	.2439E-15	.7486E-15	.3151E-14	.2439E-15	.7486E-15	.1245E-15	.3672E-18	.4621E-17
20.53481	.3495E-14	.6371E-16	.4002E-15	.3714E-14	.6368E-16	.3997E-15	.6734E-16	.8166E-18	.2244E-17

RMS VALUES-ALIGNMENT INPUT

RMS (1) =0.406E-02
 RMS (2) =0.238E-03
 RMS (3) =0.104E-03
 RMS (4) =0.404E-02
 RMS (5) =0.237E-03
 RMS (6) =0.103E-03
 RMS (7) =0.249E-02
 RMS (8) =0.197E-03
 RMS (9) =0.178E-04

RMS (10) =0.253E-02

**** PSD VALUES FOR CROSS LEVEL INPUT ****

FREQUENCY	PSD (1)	PSD (2)	PSD (3)	PSD (4)	PSD (5)	PSD (6)	PSD (7)	PSD (8)	PSD (9)
0.10000	-1199E-05	-4407E-10	-2090E-11	-1199E-05	-4401E-10	-2199E-11	-1075E-04	-2910E-09	-5450E-06
0.10593	-1202E-05	-4245E-10	-2633E-11	-1203E-05	-4238E-10	-2673E-11	-1066E-04	-3268E-09	-5390E-06
0.11220	-1207E-05	-4066E-10	-3318E-11	-1208E-05	-4059E-10	-3373E-11	-1056E-04	-3671E-09	-5323E-06
0.11885	-1211E-05	-3869E-10	-4182E-11	-1213E-05	-3863E-10	-4263E-11	-1045E-04	-4125E-09	-5249E-06
0.12589	-1217E-05	-3653E-10	-5275E-11	-1218E-05	-3649E-10	-5389E-11	-1033E-04	-4635E-09	-5167E-06
0.13335	-1223E-05	-3418E-10	-6656E-11	-1225E-05	-3417E-10	-6817E-11	-1019E-04	-5210E-09	-5077E-06
0.14125	-1230E-05	-3163E-10	-8404E-11	-1233E-05	-3169E-10	-8632E-11	-1004E-04	-5859E-09	-4977E-06
0.14962	-1239E-05	-2890E-10	-1062E-10	-1242E-05	-2908E-10	-1094E-10	-9870E-05	-6590E-09	-4866E-06
0.15849	-1248E-05	-2600E-10	-1343E-10	-1252E-05	-2639E-10	-1389E-10	-9683E-05	-7415E-09	-4744E-06
0.16788	-1259E-05	-2301E-10	-1699E-10	-1264E-05	-2371E-10	-1763E-10	-9477E-05	-8348E-09	-4611E-06
0.17783	-1272E-05	-1999E-10	-2153E-10	-1278E-05	-2120E-10	-2243E-10	-9249E-05	-9404E-09	-4464E-06
0.18836	-1287E-05	-1711E-10	-2731E-10	-1294E-05	-1908E-10	-2859E-10	-8999E-05	-1060E-08	-4304E-06
0.19953	-1304E-05	-1459E-10	-3470E-10	-1314E-05	-1774E-10	-3651E-10	-8723E-05	-1196E-08	-4130E-06
0.21135	-1325E-05	-1281E-10	-4418E-10	-1337E-05	-1672E-10	-4672E-10	-8422E-05	-1352E-08	-3942E-06
0.22237	-1349E-05	-1235E-10	-5637E-10	-1365E-05	-1593E-10	-5997E-10	-8094E-05	-1529E-08	-3738E-06
0.23714	-1378E-05	-1145E-10	-7214E-10	-1398E-05	-1438E-10	-7724E-10	-7737E-05	-1734E-08	-3519E-06
0.25119	-1414E-05	-1067E-10	-9265E-10	-1438E-05	-1372E-10	-9987E-10	-7352E-05	-1970E-08	-3286E-06
0.26607	-1457E-05	-9133E-10	-1195E-09	-1488E-05	-1298E-10	-1298E-09	-6937E-05	-2246E-08	-3038E-06
0.28184	-1511E-05	-8304E-10	-1551E-09	-1551E-05	-1197E-09	-1697E-09	-6496E-05	-2571E-08	-2777E-06
0.29854	-1579E-05	-7414E-10	-2028E-09	-1629E-05	-1117E-09	-2232E-09	-6027E-05	-2959E-08	-2505E-06
0.31623	-1666E-05	-6759E-10	-2677E-09	-1730E-05	-1042E-09	-2975E-09	-5536E-05	-3431E-08	-2224E-06
0.33491	-1730E-05	-6273E-10	-3578E-09	-1863E-05	-9420E-09	-4008E-09	-5025E-05	-4017E-08	-1937E-06
0.35486	-1935E-05	-4758E-09	-4865E-09	-2043E-05	-6894E-09	-5491E-09	-4501E-05	-4767E-08	-1649E-06
0.37584	-2152E-05	-8427E-09	-6768E-09	-2293E-05	-1176E-08	-768E-09	-3970E-05	-5765E-08	-1363E-06
0.39811	-2469E-05	-1537E-08	-9715E-09	-2657E-05	-2070E-08	-1103E-08	-3440E-05	-7157E-08	-1086E-06
0.42169	-2956E-05	-2934E-08	-1455E-08	-3210E-05	-3809E-08	-166E-08	-2917E-05	-9216E-08	-8250E-07
0.44468	-3738E-05	-5962E-08	-2304E-08	-4086E-05	-744E-08	-2631E-08	-2399E-05	-1244E-07	-5875E-07
0.47315	-4980E-05	-1293E-07	-3843E-08	-5333E-05	-1541E-07	-4333E-08	-1844E-05	-1748E-07	-3834E-07
0.50118	-6307E-05	-2715E-07	-6093E-08	-6736E-05	-3042E-07	-6643E-08	-1122E-05	-2296E-07	-2239E-07
0.53088	-8278E-05	-3866E-07	-9376E-08	-8453E-05	-4052E-07	-6645E-08	-3314E-06	-1969E-07	-1078E-07
0.56234	-1243E-05	-3144E-07	-3675E-08	-1176E-05	-3179E-07	-3730E-08	-3304E-07	-9271E-08	-2688E-08
0.59566	-9019E-06	-2139E-07	-1683E-08	-8824E-06	-2108E-07	-1640E-08	-2344E-09	-3399E-08	-1251E-10
0.63095	-3277E-06	-1519E-07	-7473E-09	-2821E-06	-1455E-07	-6800E-09	-2758E-07	-1165E-08	-3479E-08
0.66834	-1177E-06	-1161E-07	-3189E-09	-8694E-07	-1081E-07	-2543E-09	-1084E-06	-3628E-09	-1286E-07
0.70794	-3962E-07	-9437E-08	-1205E-09	-2170E-07	-8565E-08	-774E-10	-2538E-06	-8935E-10	-2754E-07
0.74939	-1152E-07	-8033E-08	-3672E-10	-8138E-08	-7152E-08	-2502E-10	-4628E-06	-1323E-10	-4651E-07
0.79432	-2864E-08	-7076E-08	-1745E-10	-1266E-07	-6231E-08	-4121E-10	-7221E-06	-6510E-11	-6831E-07
0.84139	-1710E-08	-6392E-08	-3976E-10	-2161E-07	-5621E-08	-9802E-10	-1009E-05	-1768E-10	-9108E-07
0.89125	-3307E-08	-5880E-08	-9264E-10	-2928E-07	-5214E-08	-1794E-09	-1294E-05	-2668E-10	-1127E-06
0.94446	-5867E-08	-5481E-08	-1707E-09	-3346E-07	-4944E-08	-2745E-09	-1542E-05	-2763E-10	-1307E-06
0.99999	-8823E-08	-5155E-08	-2710E-09	-3371E-07	-4761E-08	-3765E-09	-1723E-05	-2133E-10	-1431E-06
1.02919	-1041E-07	-5012E-08	-3289E-09	-3349E-07	-4692E-08	-4281E-09	-1778E-05	-1662E-10	-1466E-06
1.05928	-1205E-07	-4879E-08	-3916E-09	-3054E-07	-4631E-08	-4796E-09	-1807E-05	-1164E-10	-1480E-06
1.09018	-1376E-07	-4753E-08	-4587E-09	-2802E-07	-4575E-08	-5307E-09	-1807E-05	-6999E-11	-1473E-06
1.12201	-1551E-07	-4634E-08	-5299E-09	-2511E-07	-4522E-08	-5813E-09	-1778E-05	-3226E-11	-1444E-06
1.18849	-1904E-07	-4411E-08	-6825E-09	-1884E-07	-4412E-08	-6813E-09	-1635E-05	-5212E-14	-1322E-06
1.22320	-2074E-07	-4305E-08	-7624E-09	-1586E-07	-4351E-08	-7314E-09	-1524E-05	-1098E-11	-1232E-06
1.25891	-2232E-07	-4202E-08	-8437E-09	-1322E-07	-4284E-08	-7822E-09	-1351E-05	-4106E-11	-1125E-06
1.29567	-2372E-07	-4103E-08	-9253E-09	-1104E-07	-4211E-08	-8343E-09	-1241E-05	-8917E-11	-1005E-06
1.33351	-2487E-07	-4005E-08	-1006E-08	-9428E-08	-4130E-08	-8883E-09	-1079E-05	-1527E-10	-8766E-07
1.37245	-2571E-07	-3911E-08	-1085E-08	-8443E-08	-4042E-08	-9447E-09	-9110E-06	-2275E-10	-7429E-07
1.41252	-2618E-07	-3818E-08	-1160E-08	-8092E-08	-3948E-08	-1008E-08	-7432E-06	-3085E-10	-6089E-07
1.45377	-2622E-07	-3729E-08	-1231E-08	-8332E-08	-3850E-08	-1066E-08	-5817E-06	-3899E-10	-4794E-07
1.49622	-2581E-07	-3643E-08	-1297E-08	-8070E-08	-3749E-08	-1132E-08	-4326E-06	-4656E-10	-3590E-07
1.53991	-2493E-07	-3559E-08	-1355E-08	-10170E-08	-3649E-08	-1199E-08	-3010E-06	-5296E-10	-2518E-07
1.58487	-2360E-07	-3479E-08	-1406E-08	-1145E-07	-3545E-08	-1268E-08	-1910E-06	-5768E-10	-1613E-07
1.63115	-2184E-07	-3401E-08	-1448E-08	-1273E-07	-3446E-08	-1303E-08	-1055E-06	-6033E-10	-9002E-08
1.67878	-1973E-07	-3325E-08	-1482E-08	-1381E-07	-3352E-08	-1434E-08	-8578E-07	-6069E-10	-3951E-08
1.72780	-1736E-07	-3252E-08	-1507E-08	-1452E-07	-3262E-08	-1466E-08	-1131E-07	-5870E-10	-9894E-09
1.77828	-1482E-07	-3181E-08	-1523E-08	-1471E-07	-3179E-08	-1521E-08	-1649E-08	-5454E-10	-7415E-09
1.83018	-1223E-07	-3110E-08	-1533E-08	-1431E-07	-3102E-08	-1562E-08	-8264E-08	-4854E-10	-5445E-09
1.88362	-9721E-08	-3039E-08	-1535E-08	-1330E-07	-3028E-08	-1601E-08	-3119E-07	-4121E-10	-2848E-08
1.93863	-7391E-08	-2968E-08	-1533E-08	-1174E-07	-2958E-08	-1622E-08	-6313E-07	-3317E-10	-5872E-08
1.99523	-5337E-08	-2894E-08	-1527E-08	-9768E-08	-2888E-08	-1629E-08	-9813E-07	-2506E-10	-9312E-08

2.05350	.3624E-08	.2817E-08	.1518E-08	.7568E-08	.2817E-08	.1623E-08	.1306E-06	.1750E-10	.1266E-07
2.11346	.2288E-08	.2737E-08	.1509E-08	.5364E-08	.2741E-08	.1604E-08	.1557E-06	.1101E-10	.1545E-07
2.17517	.1327E-08	.2652E-08	.1498E-08	.3380E-08	.2659E-08	.1576E-08	.1702E-06	.5956E-11	.1731E-07
2.23869	.7094E-09	.2561E-08	.1488E-08	.1804E-08	.2569E-08	.1541E-08	.1723E-06	.2494E-11	.1801E-07
2.30406	.3779E-09	.2466E-08	.1477E-08	.7580E-09	.2471E-08	.1504E-08	.1624E-06	.5842E-12	.1747E-07
2.37134	.2604E-09	.2366E-08	.1465E-08	.2708E-09	.2366E-08	.1466E-08	.1423E-06	.6919E-15	.1580E-07
2.44058	.2822E-09	.2261E-08	.1451E-08	.2745E-09	.2255E-08	.1431E-08	.1154E-06	.3861E-12	.1326E-07
2.51185	.3774E-09	.2154E-08	.1432E-08	.6158E-09	.2142E-08	.1400E-08	.8565E-07	.1319E-11	.1022E-07
2.58520	.4974E-09	.2044E-08	.1408E-08	.1091E-08	.2027E-08	.1372E-08	.5717E-07	.2392E-11	.7107E-08
2.66069	.6136E-09	.1933E-08	.1377E-08	.1494E-08	.1915E-08	.1344E-08	.3324E-07	.3276E-11	.4323E-08
2.73838	.7154E-09	.1823E-08	.1338E-08	.1674E-08	.1807E-08	.1313E-08	.1585E-07	.3771E-11	.2167E-08
2.81834	.8017E-09	.1714E-08	.1292E-08	.1575E-08	.1703E-08	.1277E-08	.5396E-08	.3813E-11	.7810E-09
2.90064	.90064E-09	.1607E-08	.1238E-08	.1246E-08	.1602E-08	.1232E-08	.8083E-09	.3462E-11	.1249E-09
2.98534	.9194E-09	.1504E-08	.1178E-08	.8242E-09	.1505E-08	.1178E-08	.4034E-10	.2851E-11	.6729E-11
3.07251	.9300E-09	.1404E-08	.1115E-08	.4655E-09	.1409E-08	.1117E-08	.8404E-09	.2135E-11	.1545E-09
3.16223	.8894E-09	.1306E-08	.1050E-08	.2771E-09	.1313E-08	.1052E-08	.1512E-08	.1445E-11	.3159E-09
3.25457	.7935E-09	.1212E-08	.9844E-09	.2661E-09	.1217E-08	.9854E-09	.1370E-08	.8597E-12	.3453E-09
3.34960	.6566E-09	.1120E-08	.9207E-09	.3460E-09	.1123E-08	.9213E-09	.6902E-09	.4154E-12	.2387E-09
3.44741	.5051E-09	.1030E-08	.8588E-09	.4030E-09	.1031E-08	.8595E-09	.1778E-09	.1241E-12	.9427E-10
3.54808	.3866E-09	.9425E-09	.7984E-09	.3803E-09	.9424E-09	.7987E-09	.2964E-09	.2035E-14	.2011E-10
3.65168	.3155E-09	.8574E-09	.7388E-09	.3202E-09	.8580E-09	.7368E-09	.8981E-09	.7745E-13	.4903E-10
3.7531	.3069E-09	.7754E-09	.6789E-09	.3164E-09	.7772E-09	.6736E-09	.1399E-08	.3705E-12	.1217E-09
3.86806	.3601E-09	.6971E-09	.6184E-09	.4244E-09	.6996E-09	.6104E-09	.1316E-08	.8528E-12	.1479E-09
3.98101	.6294E-09	.6229E-09	.5574E-09	.5950E-09	.6250E-09	.5497E-09	.6966E-09	.1412E-11	.9268E-10
4.09725	.6217E-09	.5532E-09	.4970E-09	.7044E-09	.5540E-09	.4935E-09	.9217E-10	.1857E-11	.1395E-10
4.21690	.7874E-09	.4881E-09	.4389E-09	.6555E-09	.4875E-09	.4418E-09	.1181E-09	.1984E-11	.1984E-10
4.34003	.9157E-09	.4275E-09	.3847E-09	.4772E-09	.4260E-09	.3929E-09	.9710E-09	.1685E-11	.1796E-09
4.46676	.9495E-09	.3710E-09	.3353E-09	.3154E-09	.3695E-09	.3450E-09	.2268E-08	.1045E-11	.4583E-09
4.59719	.8603E-09	.3186E-09	.2909E-09	.3412E-09	.3177E-09	.2974E-09	.3298E-08	.3570E-12	.7249E-09
4.73143	.6818E-09	.2701E-09	.2507E-09	.6128E-09	.2700E-09	.2514E-09	.3492E-08	.4704E-14	.8325E-09
4.86959	.5130E-09	.2256E-09	.2136E-09	.1013E-08	.2261E-09	.2091E-09	.2769E-08	.2453E-12	.7145E-09
5.01179	.4747E-09	.1856E-09	.1786E-09	.1313E-08	.1861E-09	.1721E-09	.1555E-08	.1016E-11	.4339E-09
5.15813	.6332E-09	.1501E-09	.1457E-09	.1335E-08	.1504E-09	.1409E-09	.4878E-09	.1906E-11	.1470E-09
5.30875	.9408E-09	.1191E-09	.1154E-09	.1084E-08	.1192E-09	.1143E-09	.1381E-10	.2367E-11	.4501E-11
5.46377	.1243E-08	.9259E-10	.8883E-10	.7606E-09	.9257E-10	.9082E-10	.1569E-09	.2075E-11	.5497E-10
5.62332	.1365E-08	.7006E-10	.6669E-10	.6126E-09	.7003E-10	.6949E-10	.5754E-09	.1192E-11	.2187E-09
5.78752	.1233E-08	.5116E-10	.4895E-10	.7396E-09	.5116E-10	.5051E-10	.8650E-09	.3021E-12	.3509E-09
5.95652	.9375E-09	.3560E-10	.3488E-10	.1011E-08	.3560E-10	.3469E-10	.8027E-09	.6476E-14	.3493E-09
6.13045	.6760E-09	.2318E-10	.2360E-10	.1177E-08	.2318E-10	.2252E-10	.4801E-09	.4433E-12	.2234E-09
6.30946	.6062E-09	.1375E-10	.1454E-10	.1082E-08	.1374E-10	.1371E-10	.1492E-09	.1157E-11	.7392E-10
6.49370	.7200E-09	.7066E-11	.7665E-11	.8032E-09	.7071E-11	.7506E-11	.3214E-11	.1475E-11	.1691E-11
6.68332	.8550E-09	.2799E-11	.3081E-11	.5659E-09	.2810E-11	.3260E-11	.4780E-10	.1112E-11	.2639E-10
6.87848	.8441E-09	.5665E-12	.6770E-12	.5200E-09	.5717E-12	.7778E-12	.1474E-09	.4174E-12	.8509E-10
7.07933	.6676E-09	.1135E-13	.2394E-13	.6045E-09	.1121E-13	.2071E-13	.1737E-09	.1249E-13	.1035E-09
7.28605	.4584E-09	.8196E-12	.6477E-12	.6379E-09	.8235E-12	.7259E-12	.1098E-09	.1508E-12	.6740E-10
7.49881	.3539E-09	.2684E-11	.2270E-11	.5276E-09	.2690E-11	.2423E-11	.2955E-10	.4990E-12	.1841E-10
7.71778	.3578E-09	.5274E-11	.4727E-11	.3558E-09	.5271E-11	.4755E-11	.3877E-14	.5759E-12	.2311E-14
7.94314	.3631E-09	.8265E-11	.7722E-11	.2533E-09	.8251E-11	.7577E-11	.1794E-10	.3109E-12	.1112E-10
8.17509	.2959E-09	.1138E-10	.1082E-10	.2381E-09	.1137E-10	.1071E-10	.3571E-10	.4254E-13	.2173E-10
8.41380	.1916E-09	.1440E-10	.1370E-10	.2261E-09	.1440E-10	.1378E-10	.2675E-10	.2017E-13	.1581E-10
8.65949	.1228E-09	.1711E-10	.1629E-10	.1668E-09	.1712E-10	.1644E-10	.7192E-11	.1234E-12	.4094E-11
8.91235	.9892E-10	.1933E-10	.1856E-10	.9729E-10	.1933E-10	.1858E-10	.9998E-14	.1320E-12	.5376E-14
9.17260	.7927E-10	.2091E-10	.2028E-10	.6015E-10	.2090E-10	.2021E-10	.3615E-11	.4834E-13	.1872E-11
9.44044	.4737E-10	.2177E-10	.2123E-10	.4419E-10	.2177E-10	.2122E-10	.4724E-11	.1051E-14	.2333E-11
9.71611	.2097E-10	.2191E-10	.2141E-10	.2607E-10	.2191E-10	.2145E-10	.1677E-11	.7765E-14	.7987E-12
9.99982	.8493E-11	.2132E-10	.2090E-10	.9474E-11	.2132E-10	.2092E-10	.5045E-13	.9676E-14	.2406E-13
10.29182	.2402E-11	.2005E-10	.1976E-10	.2002E-11	.2005E-10	.1976E-10	.4723E-13	.1714E-14	.2633E-13
10.59235	.8720E-13	.1822E-10	.1802E-10	.8797E-13	.1822E-10	.1802E-10	.1024E-13	.5489E-17	.8393E-15
10.90165	.1760E-11	.1595E-10	.1584E-10	.2098E-11	.1595E-10	.1583E-10	.1794E-12	.5613E-15	.2885E-13
11.21998	.6173E-11	.1340E-10	.1336E-10	.6533E-11	.1340E-10	.1335E-10	.1676E-13	.6014E-14	.3232E-14
11.54761	.1405E-10	.1073E-10	.1073E-10	.1180E-10	.1073E-10	.1074E-10	.6150E-12	.6545E-14	.1176E-12
11.88481	.2066E-10	.8114E-11	.8148E-11	.2093E-10	.8114E-11	.8148E-11	.2077E-11	.2805E-16	.3766E-12
12.23185	.2421E-10	.5704E-11	.5772E-11	.2808E-10	.5703E-11	.5759E-11	.8770E-12	.1446E-13	.1479E-12
12.58903	.3224E-10	.3631E-11	.3701E-11	.2936E-10	.3632E-11	.3699E-11	.3317E-12	.2209E-13	.5154E-13
12.95663	.3765E-10	.1995E-11	.2047E-11	.3519E-10	.1996E-11	.2049E-11	.3091E-11	.1784E-14	.4404E-12
13.33498	.3424E-10	.8477E-12	.8902E-12	.3898E-10	.8474E-12	.8861E-12	.1825E-11	.1173E-13	.2376E-12
13.72436	.3513E-10	.1954E-12	.2187E-12	.3345E-10	.1955E-12	.2177E-12	.1207E-12	.2316E-13	.1433E-13
14.12512	.3441E-10	.1032E-15	.2062E-14	.3221E-10	.1013E-15	.1969E-14	.2520E-11	.1989E-14	.2725E-12
14.53758	.2620E-10	.1799E-12	.1644E-12	.2925E-10	.1800E-12	.1659E-12	.1169E-11	.8469E-14	.1150E-12
14.96209	.2217E-10	.6225E-12	.5945E-12	.2076E-10	.6224E-12	.5953E-12	.1882E-12	.1162E-13	.1685E-13

15.39899	.1658E-10	.1196E-11	.1165E-11	.1632E-10	.1196E-11	.1165E-11	.1237E-11	.6131E-16	.1008E-12
15.84865	.5730E-11	.1770E-11	.1736E-11	.1050E-10	.1770E-11	.1739E-11	.1549E-12	.4424E-14	.1150E-13
16.31143	.5806E-11	.2227E-11	.2201E-11	.5310E-11	.2226E-11	.2201E-11	.1926E-12	.1491E-14	.1306E-13
16.78772	.2168E-11	.2482E-11	.2466E-11	.2311E-11	.2482E-11	.2466E-11	.1244E-12	.2041E-15	.7795E-14
17.27792	.3791E-12	.2494E-11	.2488E-11	.3690E-12	.2494E-11	.2488E-11	.7935E-15	.1719E-15	.4846E-16
17.78244	.4158E-13	.2268E-11	.2272E-11	.4115E-13	.2268E-11	.2273E-11	.2957E-14	.6278E-19	.9071E-16
18.30170	.8425E-12	.1855E-11	.1867E-11	.8737E-12	.1855E-11	.1867E-11	.3557E-14	.3442E-15	.1420E-15
18.83611	.2499E-11	.1338E-11	.1353E-11	.2377E-11	.1338E-11	.1353E-11	.1248E-12	.1531E-15	.4660E-14
19.38612	.3947E-11	.8153E-12	.8302E-12	.4181E-11	.8152E-12	.8294E-12	.6082E-13	.1167E-14	.2073E-14
19.95219	.5635E-11	.3801E-12	.3911E-12	.5310E-11	.3801E-12	.3911E-12	.2104E-12	.6225E-15	.6492E-14
20.53481	.5870E-11	.9965E-13	.1058E-12	.6210E-11	.9961E-13	.1055E-12	.1131E-12	.1367E-14	.3146E-14

RMS VALUES-CROSS LEVEL INPUT

RMS(1) =0.113E-02
RMS(2) =0.122E-03
RMS(3) =0.693E-04
RMS(4) =0.116E-02
RMS(5) =0.123E-03
RMS(6) =0.696E-04
RMS(7) =0.188E-02
RMS(8) =0.602E-04
RMS(9) =0.448E-03

RMS(10) =0.692E-03

PSD VALUES FOR ALIGNMENT INPUT

FREQUENCY (HZ)	LATERAL CONTACT FORCES				CENTERPLATE FORCE LATERAL POSITION	LATERAL MAGNITUDE
	AXLE 1	AXLE 2	AXLE 3	AXLE 4		
0.100	0.2574E+03	0.8440E+02	0.1024E+05	0.8940E+04	0.8378E-07	0.1188E+02
0.106	0.2738E+03	0.8448E+02	0.1135E+05	0.9919E+04	0.9425E-07	0.1337E+02
0.112	0.2928E+03	0.8489E+02	0.1258E+05	0.1101E+05	0.1060E-06	0.1505E+02
0.119	0.3145E+03	0.8564E+02	0.1395E+05	0.1222E+05	0.1192E-06	0.1693E+02
0.126	0.3394E+03	0.8671E+02	0.1545E+05	0.1356E+05	0.1340E-06	0.1905E+02
0.133	0.3679E+03	0.8809E+02	0.1711E+05	0.1504E+05	0.1506E-06	0.2144E+02
0.141	0.4003E+03	0.8976E+02	0.1894E+05	0.1668E+05	0.1693E-06	0.2412E+02
0.150	0.4373E+03	0.9168E+02	0.2094E+05	0.1849E+05	0.1902E-06	0.2715E+02
0.158	0.4793E+03	0.9382E+02	0.2314E+05	0.2048E+05	0.2137E-06	0.3055E+02
0.168	0.5271E+03	0.9607E+02	0.2553E+05	0.2268E+05	0.2402E-06	0.3438E+02
0.178	0.5815E+03	0.9833E+02	0.2813E+05	0.2508E+05	0.2698E-06	0.3870E+02
0.188	0.6432E+03	0.1004E+03	0.3095E+05	0.2772E+05	0.3032E-06	0.4358E+02
0.200	0.7133E+03	0.1021E+03	0.3399E+05	0.3060E+05	0.3407E-06	0.4909E+02
0.211	0.7925E+03	0.1031E+03	0.3727E+05	0.3375E+05	0.3830E-06	0.5531E+02
0.224	0.8819E+03	0.1028E+03	0.4077E+05	0.3717E+05	0.4306E-06	0.6236E+02
0.237	0.9821E+03	0.1005E+03	0.4451E+05	0.4091E+05	0.4842E-06	0.7037E+02
0.251	0.1093E+04	0.9530E+02	0.4850E+05	0.4498E+05	0.5449E-06	0.7947E+02
0.266	0.1215E+04	0.8602E+02	0.5273E+05	0.4944E+05	0.6137E-06	0.8987E+02
0.282	0.1344E+04	0.7133E+02	0.5725E+05	0.5435E+05	0.6921E-06	0.1018E+03
0.299	0.1473E+04	0.5048E+02	0.6211E+05	0.5982E+05	0.7818E-06	0.1156E+03
0.316	0.1589E+04	0.2537E+02	0.6743E+05	0.6607E+05	0.8854E-06	0.1317E+03
0.335	0.1662E+04	0.7444E+01	0.7349E+05	0.7344E+05	0.1006E-05	0.1506E+03
0.355	0.1639E+04	0.3957E+02	0.8081E+05	0.8263E+05	0.1150E-05	0.1734E+03
0.376	0.1432E+04	0.2704E+03	0.9053E+05	0.9496E+05	0.1325E-05	0.2013E+03
0.398	0.9574E+03	0.1229E+04	0.1052E+06	0.1133E+06	0.1544E-05	0.2367E+03
0.422	0.5925E+03	0.4954E+04	0.1310E+06	0.1442E+06	0.1826E-05	0.2829E+03
0.447	0.4522E+04	0.2029E+05	0.1847E+06	0.2046E+06	0.2196E-05	0.3442E+03
0.473	0.4379E+05	0.8860E+05	0.3148E+06	0.3369E+06	0.2620E-05	0.4162E+03
0.501	0.2731E+06	0.3478E+06	0.5951E+06	0.5751E+06	0.2648E-05	0.4270E+03
0.531	0.6425E+06	0.6087E+06	0.7093E+06	0.5858E+06	0.1342E-05	0.2202E+03

0.562	0.4411E+06	0.3403E+06	0.6044E+06	0.2906E+06	0.1930E-06	0.3236E+02
0.596	0.1978E+06	0.1312E+06	0.1977E+06	0.1327E+06	0.2301E-08	0.3779E+00
0.631	0.9218E+05	0.5446E+05	0.1089E+06	0.7287E+05	0.1015E-06	0.1763E+02
0.668	0.4815E+05	0.2595E+05	0.6620E+05	0.4585E+05	0.2297E-06	0.4114E+02
0.708	0.2777E+05	0.1389E+05	0.4165E+05	0.3053E+05	0.3315E-06	0.6136E+02
0.750	0.1726E+05	0.8112E+04	0.2568E+05	0.2030E+05	0.3979E-06	0.7650E+02
0.794	0.1135E+05	0.5058E+04	0.1477E+05	0.1289E+05	0.4301E-06	0.8642E+02
0.841	0.7773E+04	0.3311E+04	0.7443E+04	0.7493E+04	0.4316E-06	0.9133E+02
0.891	0.5492E+04	0.2248E+04	0.2950E+04	0.3758E+04	0.4067E-06	0.9151E+02
0.944	0.3970E+04	0.1569E+04	0.6904E+03	0.1459E+04	0.3608E-06	0.7942E+02
1.000	0.2918E+04	0.1118E+04	0.3884E+02	0.3281E+03	0.3004E-06	0.7964E+02
1.029	0.2514E+04	0.9491E+03	0.1037E+03	0.9753E+02	0.2670E-06	0.7462E+02
1.059	0.1879E+04	0.8083E+03	0.3154E+03	0.2763E+02	0.2327E-06	0.6900E+02
1.122	0.1628E+04	0.5904E+03	0.5952E+03	0.7033E+02	0.1985E-06	0.6291E+02
1.155	0.1413E+04	0.5058E+03	0.8749E+03	0.1797E+03	0.1653E-06	0.5650E+02
1.188	0.1226E+04	0.4337E+03	0.1101E+04	0.3146E+03	0.1340E-06	0.4992E+02
1.223	0.1065E+04	0.3719E+03	0.1237E+04	0.4412E+03	0.1052E-06	0.4332E+02
1.259	0.9245E+03	0.3190E+03	0.1192E+04	0.5350E+03	0.7973E-07	0.3686E+02
1.296	0.8022E+03	0.2734E+03	0.1032E+04	0.5816E+03	0.5789E-07	0.3068E+02
1.334	0.6955E+03	0.2340E+03	0.8155E+03	0.5255E+03	0.3993E-07	0.2490E+02
1.372	0.6022E+03	0.2000E+03	0.5791E+03	0.4396E+03	0.2587E-07	0.1965E+02
1.413	0.5206E+03	0.1706E+03	0.3578E+03	0.3350E+03	0.1552E-07	0.1500E+02
1.454	0.4492E+03	0.1451E+03	0.1801E+03	0.2286E+03	0.8468E-08	0.1101E+02
1.496	0.3868E+03	0.1231E+03	0.6288E+02	0.1522E+03	0.4153E-08	0.7712E+01
1.540	0.3232E+03	0.1042E+03	0.9544E+01	0.6491E+02	0.1900E-08	0.5097E+01
1.585	0.2847E+03	0.8789E+02	0.1054E+02	0.2240E+02	0.9990E-09	0.3126E+01
1.631	0.2435E+03	0.7395E+02	0.4681E+02	0.6294E+01	0.7902E-09	0.1731E+01
1.679	0.2075E+03	0.6207E+02	0.9524E+02	0.1053E+02	0.7519E-09	0.8243E+00
1.728	0.1765E+03	0.5201E+02	0.1347E+03	0.2629E+02	0.5796E-09	0.3034E+00
1.778	0.1498E+03	0.4352E+02	0.1513E+03	0.4436E+02	0.2421E-09	0.6209E-01
1.830	0.1268E+03	0.3641E+02	0.1409E+03	0.5734E+02	0.1111E-11	0.3814E-04
1.884	0.1071E+03	0.3047E+02	0.1092E+03	0.4105E+02	0.3789E-09	0.3179E-01
1.939	0.9026E+02	0.2551E+02	0.6808E+02	0.5504E+02	0.2069E-08	0.9373E-01
1.995	0.7588E+02	0.2137E+02	0.3094E+02	0.4196E+02	0.5792E-08	0.1476E+00
2.053	0.6360E+02	0.1790E+02	0.7423E+01	0.2622E+02	0.1210E-07	0.1800E+00
2.113	0.5309E+02	0.1497E+02	0.4494E+00	0.1235E+02	0.2119E-07	0.1974E+00
2.175	0.4409E+02	0.1247E+02	0.6139E+01	0.3505E+01	0.3269E-07	0.2175E+00
2.239	0.3636E+02	0.1031E+02	0.1655E+02	0.6435E+00	0.4560E-07	0.2593E+00
2.304	0.2972E+02	0.8437E+01	0.2386E+02	0.2553E+01	0.5830E-07	0.3330E+00
2.371	0.2403E+02	0.6818E+01	0.2394E+02	0.6600E+01	0.6874E-07	0.4335E+00
2.441	0.1916E+02	0.5433E+01	0.1754E+02	0.9939E+01	0.7483E-07	0.5390E+00
2.512	0.1505E+02	0.4278E+01	0.8844E+01	0.1070E+02	0.7493E-07	0.6172E+00
2.585	0.1163E+02	0.3347E+01	0.2343E+01	0.8634E+01	0.6840E-07	0.6357E+00
2.661	0.8833E+01	0.2635E+01	0.1547E+00	0.5019E+01	0.5595E-07	0.5765E+00
2.738	0.6603E+01	0.2124E+01	0.1303E+01	0.1757E+01	0.3979E-07	0.4461E+00
2.818	0.4872E+01	0.1782E+01	0.3147E+01	0.2492E+00	0.2319E-07	0.2778E+00
2.901	0.3566E+01	0.1569E+01	0.3619E+01	0.6355E+00	0.9660E-08	0.1215E+00
2.985	0.2609E+01	0.1436E+01	0.2498E+01	0.1905E+01	0.1778E-08	0.2304E-01
3.073	0.1925E+01	0.1339E+01	0.9681E+00	0.2767E+01	0.1089E-09	0.1402E-02
3.162	0.1448E+01	0.1242E+01	0.1781E+00	0.2602E+01	0.2854E-08	0.3635E-01
3.255	0.1123E+01	0.1126E+01	0.2856E+00	0.1745E+01	0.6595E-08	0.7913E-01
3.350	0.9099E+00	0.9894E+00	0.6862E+00	0.9419E+00	0.8096E-08	0.8533E-01
3.447	0.7797E+00	0.8457E+00	0.8501E+00	0.6181E+00	0.6285E-08	0.5124E-01
3.548	0.7092E+00	0.7140E+00	0.7294E+00	0.6782E+00	0.2998E-08	0.5201E-01
3.652	0.6770E+00	0.6090E+00	0.5044E+00	0.8688E+00	0.1553E-08	0.6006E-01
3.758	0.6623E+00	0.5334E+00	0.2922E+00	0.1055E+01	0.3790E-08	0.1729E+00
3.868	0.6492E+00	0.4774E+00	0.1986E+00	0.1103E+01	0.7959E-08	0.2915E+00
3.981	0.6329E+00	0.4251E+00	0.3330E+00	0.8497E+00	0.9780E-08	0.3099E+00
4.097	0.6225E+00	0.3641E+00	0.5485E+00	0.4568E+00	0.6541E-08	0.1883E+00
4.217	0.6351E+00	0.2916E+00	0.4807E+00	0.4361E+00	0.1073E-08	0.2875E-01
4.340	0.6810E+00	0.2148E+00	0.1513E+00	0.8522E+00	0.1679E-08	0.4253E-01
4.467	0.7504E+00	0.1459E+00	0.1247E+00	0.9619E+00	0.1681E-07	0.4044E+00
4.597	0.8095E+00	0.9476E-01	0.5848E+00	0.9619E+00	0.4753E-07	0.1091E+01
4.731	0.6138E+00	0.6511E-01	0.8390E+00	0.3998E+00	0.8348E-07	0.1830E+01
4.870	0.7352E+00	0.5686E-01	0.4140E+00	0.4992E+00	0.1065E-06	0.2230E+01
5.012	0.5880E+00	0.7251E-01	0.1858E-01	0.7865E+00	0.1016E-06	0.2031E+01
5.158	0.4301E+00	0.1185E+00	0.1841E+00	0.2972E+00	0.6864E-07	0.1307E+01
5.309	0.3290E+00	0.1951E+00	0.3242E+00	0.1407E+00	0.2587E-07	0.4688E+00
5.464	0.3131E+00	0.2840E+00	0.7985E-01	0.5803E+00	0.8806E-09	0.1514E-01
5.623	0.3478E+00	0.3508E+00	0.4897E-01	0.3917E+00	0.1198E-07	0.1953E+00
					0.5308E-07	0.8176E+00

5.788	0.3621E+00	0.3664E+00	0.3206E+00	0.4591E-02	0.9476E-07	0.1378E+01
5.957	0.3078E+00	0.3340E+00	0.2922E+00	0.4052E+00	0.1050E-06	0.1438E+01
6.130	0.2052E+00	0.2947E+00	0.4769E-01	0.4456E+00	0.7485E-07	0.9632E+00
6.309	0.1265E+00	0.2999E+00	0.2857E-01	0.5387E-01	0.2761E-07	0.3334E+00
6.494	0.1227E+00	0.3609E+00	0.1183E+00	0.3182E+00	0.7039E-09	0.7967E-02
6.683	0.1688E+00	0.4298E+00	0.6861E-01	0.2444E+00	0.1227E-07	0.1304E+00
6.876	0.1939E+00	0.4410E+00	0.2435E-01	0.2899E-01	0.4416E-07	0.4406E+00
7.079	0.1651E+00	0.3764E+00	0.1420E+00	0.3498E+00	0.6025E-07	0.5655E+00
7.266	0.1243E+00	0.2833E+00	0.8933E-01	0.1346E+00	0.4368E-07	0.3871E+00
7.499	0.1302E+00	0.2240E+00	0.2691E-01	0.1541E+00	0.1335E-07	0.1122E+00
7.718	0.1768E+00	0.2117E+00	0.1735E+00	0.1993E+00	0.1898E-11	0.1561E-04
7.943	0.2032E+00	0.2086E+00	0.4045E-01	0.4887E-01	0.1012E-07	0.7840E-01
8.175	0.1830E+00	0.1808E+00	0.9765E-01	0.2429E+00	0.2217E-07	0.1672E+00
8.414	0.1972E+00	0.1346E+00	0.1335E+00	0.8416E-01	0.1810E-07	0.1344E+00
8.659	0.1645E+00	0.9828E-01	0.8993E-01	0.1851E+00	0.5261E-08	0.3892E-01
8.912	0.1830E+00	0.8779E-01	0.1773E+00	0.8014E-01	0.7780E-11	0.5850E-04
9.173	0.1758E+00	0.9600E-01	0.7649E-01	0.1634E+00	0.3032E-08	0.2304E-01
9.440	0.1524E+00	0.1053E+00	0.1519E+00	0.1162E+00	0.4232E-08	0.3293E-01
9.716	0.1413E+00	0.1063E+00	0.1064E+00	0.1426E+00	0.1614E-08	0.1283E-01
10.000	0.1384E+00	0.1057E+00	0.1404E+00	0.1066E+00	0.5337E-10	0.4223E-03
10.292	0.1278E+00	0.1094E+00	0.1048E+00	0.1317E+00	0.6038E-10	0.4186E-03
10.592	0.1154E+00	0.1095E+00	0.1111E+00	0.1134E+00	0.3061E-13	0.1574E-03
10.902	0.1059E+00	0.1027E+00	0.9893E-01	0.1130E+00	0.1309E-09	0.2442E-02
11.220	0.9271E-01	0.9588E-01	0.8519E-01	0.1040E+00	0.1492E-10	0.2488E-03
11.543	0.8278E-01	0.8679E-01	0.7090E-01	0.1062E+00	0.5998E-09	0.1022E-01
11.865	0.7780E-01	0.7170E-01	0.7916E-01	0.7256E-01	0.2163E-08	0.3892E-01
12.232	0.5402E-01	0.6241E-01	0.4210E-01	0.9205E-01	0.9665E-09	0.1861E-01
12.589	0.5369E-01	0.6229E-01	0.5180E-01	0.7657E-01	0.3853E-09	0.7984E-02
12.957	0.5296E-01	0.5878E-01	0.4098E-01	0.4517E-01	0.3781E-08	0.8445E-01
13.335	0.4307E-01	0.5184E-01	0.2987E-01	0.5963E-01	0.2351E-08	0.5662E-01
13.724	0.4011E-01	0.5427E-01	0.3858E-01	0.5607E-01	0.1639E-09	0.4255E-02
14.125	0.4335E-01	0.5543E-01	0.3082E-01	0.4135E-01	0.3613E-08	0.1009E+00
14.533	0.3904E-01	0.4674E-01	0.3804E-01	0.3196E-01	0.1772E-08	0.5309E-01
14.962	0.4486E-01	0.4365E-01	0.2836E-01	0.3168E-01	0.3024E-09	0.9704E-02
15.399	0.4575E-01	0.4215E-01	0.4437E-01	0.4390E-01	0.2111E-08	0.7235E-01
15.849	0.4629E-01	0.3683E-01	0.4159E-01	0.4248E-01	0.2814E-09	0.1027E-01
16.311	0.4851E-01	0.3744E-01	0.3777E-01	0.4295E-01	0.3732E-09	0.1446E-01
16.788	0.4549E-01	0.3922E-01	0.4284E-01	0.4057E-01	0.2581E-09	0.1058E-01
17.278	0.4370E-01	0.3946E-01	0.4244E-01	0.4020E-01	0.1776E-11	0.7639E-04
17.782	0.3954E-01	0.3905E-01	0.3937E-01	0.3920E-01	0.6500E-11	0.3234E-03
18.302	0.3447E-01	0.3624E-01	0.3280E-01	0.3835E-01	0.8955E-11	0.4383E-03
18.836	0.2986E-01	0.3158E-01	0.2736E-01	0.3368E-01	0.3403E-09	0.1737E-01
19.380	0.2438E-01	0.2606E-01	0.2140E-01	0.3067E-01	0.1794E-09	0.9566E-02
19.952	0.2106E-01	0.2321E-01	0.1718E-01	0.2332E-01	0.6722E-09	0.3736E-01
20.535	0.1746E-01	0.1966E-01	0.1498E-01	0.1983E-01	0.3920E-09	0.2267E-01

RMS VALUES -ALIGNMENT INPUT

LATERAL CONTACT FORCES

AXLE 1 =0.244E+03
 AXLE 2 =0.228E+03
 AXLE 3 =0.320E+03
 AXLE 4 =0.300E+03

LATERAL POSITION OF RESULTANT CENTERPLATE FORCE = 0.955E-03

LATERAL FORCE AT THE CENTERPLATE = 0.113E+02

FREQUENCY (HZ)

PSD VALUES FOR CROSS LEVEL INPUT

CENTERPLATE FORCE LATERAL POSITION LATERAL MAGNITUDE

FREQUENCY (HZ)	LATERAL CONTACT FORCES			CENTERPLATE FORCE LATERAL POSITION			LATERAL MAGNITUDE
	AXLE 1	AXLE 2	AXLE 3	AXLE 4	AXLE 5	AXLE 6	
0.100	0.1623E+03	0.1712E+03	0.2611E+03	0.2736E+03	0.5925E-05	0.5925E-05	0.7629E+03
0.106	0.1786E+03	0.1884E+03	0.2875E+03	0.3011E+03	0.5995E-05	0.5995E-05	0.7642E+03
0.112	0.1970E+03	0.2076E+03	0.3167E+03	0.3316E+03	0.6073E-05	0.6073E-05	0.7656E+03
0.119	0.2176E+03	0.2291E+03	0.3491E+03	0.3652E+03	0.6159E-05	0.6159E-05	0.7671E+03
0.126	0.2406E+03	0.2532E+03	0.3849E+03	0.4023E+03	0.6254E-05	0.6254E-05	0.7686E+03
0.133	0.2665E+03	0.2799E+03	0.4246E+03	0.4433E+03	0.6359E-05	0.6359E-05	0.7702E+03
0.141	0.2954E+03	0.3098E+03	0.4687E+03	0.4886E+03	0.6475E-05	0.6475E-05	0.7719E+03
0.150	0.3279E+03	0.3431E+03	0.5176E+03	0.5388E+03	0.6602E-05	0.6602E-05	0.7735E+03
0.158	0.3643E+03	0.3801E+03	0.5723E+03	0.5944E+03	0.6740E-05	0.6740E-05	0.7752E+03
0.168	0.4051E+03	0.4212E+03	0.6335E+03	0.6564E+03	0.6891E-05	0.6891E-05	0.7770E+03
0.178	0.4509E+03	0.4668E+03	0.7025E+03	0.7258E+03	0.7054E-05	0.7054E-05	0.7780E+03
0.188	0.5019E+03	0.5173E+03	0.7808E+03	0.8041E+03	0.7228E-05	0.7228E-05	0.7790E+03
0.200	0.5593E+03	0.5731E+03	0.8707E+03	0.8930E+03	0.7413E-05	0.7413E-05	0.7795E+03
0.211	0.6234E+03	0.6345E+03	0.9750E+03	0.9952E+03	0.7606E-05	0.7606E-05	0.7794E+03
0.224	0.6953E+03	0.7018E+03	0.1097E+04	0.1114E+04	0.7806E-05	0.7806E-05	0.7783E+03
0.237	0.7756E+03	0.7752E+03	0.1243E+04	0.1254E+04	0.8007E-05	0.8007E-05	0.7759E+03
0.251	0.8653E+03	0.8546E+03	0.1420E+04	0.1421E+04	0.8203E-05	0.8203E-05	0.7719E+03
0.266	0.9655E+03	0.9365E+03	0.1637E+04	0.1625E+04	0.8387E-05	0.8387E-05	0.7657E+03
0.282	0.1077E+04	0.1029E+04	0.1908E+04	0.1875E+04	0.8546E-05	0.8546E-05	0.7567E+03
0.299	0.1201E+04	0.1122E+04	0.2252E+04	0.2188E+04	0.8666E-05	0.8666E-05	0.7442E+03
0.316	0.1337E+04	0.1213E+04	0.2696E+04	0.2587E+04	0.8730E-05	0.8730E-05	0.7274E+03
0.335	0.1486E+04	0.1299E+04	0.3282E+04	0.3109E+04	0.8715E-05	0.8715E-05	0.7053E+03
0.355	0.1646E+04	0.1368E+04	0.4079E+04	0.3811E+04	0.8596E-05	0.8596E-05	0.6771E+03
0.378	0.1813E+04	0.1409E+04	0.5213E+04	0.4804E+04	0.8344E-05	0.8344E-05	0.6418E+03
0.398	0.1984E+04	0.1410E+04	0.6942E+04	0.6316E+04	0.7930E-05	0.7930E-05	0.5984E+03
0.422	0.2192E+04	0.1426E+04	0.9878E+04	0.8891E+04	0.7322E-05	0.7322E-05	0.5458E+03
0.447	0.2790E+04	0.1935E+04	0.1571E+05	0.1399E+05	0.6479E-05	0.6479E-05	0.4817E+03
0.473	0.6506E+04	0.5975E+04	0.2940E+05	0.2558E+05	0.5300E-05	0.5300E-05	0.3970E+03
0.501	0.2771E+05	0.2583E+05	0.5914E+05	0.4772E+05	0.3533E-05	0.3533E-05	0.2639E+03
0.531	0.6401E+05	0.4925E+05	0.7320E+05	0.4995E+05	0.1425E-05	0.1425E-05	0.9519E+02
0.562	0.4663E+05	0.2770E+05	0.4356E+05	0.2384E+05	0.2982E-06	0.2982E-06	0.1521E+02
0.596	0.2321E+05	0.1049E+05	0.2317E+05	0.1058E+05	0.1833E-06	0.1833E-06	0.1033E+00
0.631	0.1270E+05	0.4618E+04	0.1447E+05	0.5856E+04	0.5451E-06	0.5451E-06	0.2325E+02
0.668	0.8255E+04	0.2727E+04	0.1007E+05	0.3729E+04	0.2524E-05	0.2524E-05	0.1055E+03
0.708	0.6209E+04	0.2081E+04	0.7138E+04	0.2471E+04	0.6770E-05	0.6770E-05	0.2798E+03
0.750	0.5186E+04	0.1844E+04	0.4743E+04	0.1686E+04	0.1426E-04	0.1426E-04	0.5831E+03
0.794	0.4646E+04	0.1742E+04	0.2700E+04	0.1347E+04	0.2605E-04	0.2605E-04	0.1053E+04
0.841	0.4359E+04	0.1680E+04	0.1128E+04	0.1497E+04	0.4312E-04	0.4312E-04	0.1721E+04
0.891	0.4218E+04	0.1625E+04	0.2595E+03	0.2090E+04	0.6613E-04	0.6613E-04	0.2604E+04
0.944	0.4171E+04	0.1572E+04	0.2808E+03	0.2907E+04	0.9511E-04	0.9511E-04	0.3695E+04
1.000	0.4189E+04	0.1522E+04	0.1168E+04	0.3552E+04	0.1290E-03	0.1290E-03	0.4942E+04
1.029	0.4215E+04	0.1501E+04	0.1844E+04	0.3669E+04	0.1470E-03	0.1470E-03	0.5595E+04
1.059	0.4251E+04	0.1483E+04	0.2584E+04	0.3589E+04	0.1652E-03	0.1652E-03	0.6245E+04
1.090	0.4294E+04	0.1469E+04	0.3303E+04	0.3293E+04	0.1830E-03	0.1830E-03	0.6868E+04
1.122	0.4341E+04	0.1459E+04	0.3906E+04	0.2795E+04	0.1996E-03	0.1996E-03	0.7440E+04
1.155	0.4389E+04	0.1455E+04	0.4305E+04	0.2143E+04	0.2143E-03	0.2143E-03	0.7933E+04
1.188	0.4436E+04	0.1456E+04	0.4431E+04	0.1424E+04	0.2262E-03	0.2262E-03	0.8316E+04
1.223	0.4479E+04	0.1461E+04	0.4247E+04	0.7529E+03	0.2345E-03	0.2345E-03	0.8560E+04
1.259	0.4511E+04	0.1481E+04	0.3761E+04	0.2554E+03	0.2383E-03	0.2383E-03	0.8637E+04
1.296	0.4532E+04	0.1494E+04	0.2155E+04	0.2064E+03	0.2369E-03	0.2369E-03	0.8525E+04
1.334	0.4539E+04	0.1494E+04	0.2155E+04	0.2064E+03	0.2297E-03	0.2297E-03	0.8206E+04
1.372	0.4516E+04	0.1506E+04	0.1278E+04	0.7449E+03	0.2165E-03	0.2165E-03	0.7676E+04
1.413	0.4471E+04	0.1513E+04	0.5506E+03	0.1595E+04	0.1973E-03	0.1973E-03	0.6943E+04
1.454	0.4392E+04	0.1514E+04	0.1100E+03	0.2604E+04	0.1727E-03	0.1727E-03	0.6030E+04
1.496	0.4282E+04	0.1504E+04	0.4426E+02	0.3563E+04	0.1437E-03	0.1437E-03	0.4978E+04
1.540	0.4143E+04	0.1480E+04	0.3660E+03	0.4241E+04	0.1120E-03	0.1120E-03	0.3847E+04
1.585	0.3962E+04	0.1439E+04	0.5981E+03	0.4451E+04	0.7966E-04	0.7966E-04	0.2718E+04
1.631	0.3753E+04	0.1380E+04	0.1781E+04	0.4110E+04	0.4938E-04	0.4938E-04	0.1668E+04
1.679	0.3517E+04	0.1302E+04	0.2503E+04	0.3282E+04	0.2405E-04	0.2405E-04	0.8049E+03
1.728	0.3264E+04	0.1206E+04	0.2181E+04	0.2181E+04	0.6682E-05	0.6682E-05	0.2214E+03
1.778	0.3003E+04	0.1096E+04	0.2996E+04	0.1125E+04	0.1118E-07	0.1118E-07	0.3602E+00
1.830	0.2763E+04	0.9772E+03	0.2597E+04	0.4387E+03	0.6171E-05	0.6171E-05	0.2007E+03
1.884	0.2549E+04	0.8554E+03	0.1877E+04	0.3351E+03	0.2626E-04	0.2626E-04	0.8443E+03
1.939	0.2376E+04	0.7377E+03	0.1076E+04	0.8157E+03	0.5996E-04	0.5996E-04	0.1906E+04
1.995	0.2258E+04	0.6300E+03	0.4820E+03	0.1643E+04	0.1053E-03	0.1053E-03	0.3304E+04

2.053	0.2199E+04	0.5368E+03	0.3242E+03	0.2414E+04	0.1583E-03	0.4906E+04
2.113	0.2199E+04	0.4602E+03	0.6739E+03	0.2732E+04	0.2137E-03	0.6531E+04
2.175	0.2247E+04	0.4003E+03	0.1391E+04	0.2404E+04	0.2647E-03	0.7970E+04
2.239	0.2327E+04	0.3557E+03	0.2160E+04	0.1575E+04	0.3041E-03	0.9014E+04
2.304	0.2417E+04	0.3254E+03	0.2614E+04	0.6963E+03	0.3249E-03	0.9491E+04
2.371	0.2492E+04	0.3090E+03	0.2509E+04	0.3086E+03	0.3249E-03	0.9295E+04
2.441	0.2530E+04	0.3084E+03	0.1863E+04	0.7246E+03	0.3004E-03	0.8425E+04
2.512	0.2511E+04	0.3271E+03	0.9737E+03	0.1793E+04	0.2548E-03	0.6995E+04
2.585	0.2427E+04	0.3690E+03	0.2755E+03	0.2926E+04	0.1949E-03	0.5222E+04
2.661	0.2277E+04	0.4373E+03	0.1062E+03	0.3436E+04	0.1302E-03	0.3397E+04
2.738	0.2073E+04	0.5323E+03	0.4864E+03	0.3008E+04	0.7156E-04	0.1813E+04
2.818	0.1836E+04	0.6502E+03	0.1095E+04	0.1960E+04	0.2822E-04	0.6910E+03
2.901	0.1594E+04	0.7827E+03	0.1473E+04	0.1061E+04	0.4927E-05	0.1159E+03
2.985	0.1378E+04	0.9170E+03	0.1349E+04	0.9404E+03	0.2890E-06	0.6485E+01
3.073	0.1210E+04	0.1037E+04	0.8493E+03	0.1557E+04	0.7176E-05	0.1515E+03
3.162	0.1103E+04	0.1128E+04	0.4031E+03	0.2222E+04	0.1574E-04	0.3060E+03
3.255	0.1051E+04	0.1176E+04	0.3766E+03	0.2237E+04	0.1820E-04	0.3121E+03
3.350	0.1036E+04	0.1182E+04	0.7390E+03	0.1597E+04	0.1296E-04	0.1782E+03
3.447	0.1031E+04	0.1156E+04	0.1086E+04	0.9976E+03	0.5169E-05	0.5234E+02
3.548	0.1012E+04	0.1119E+04	0.1043E+04	0.1060E+04	0.2392E-05	0.9137E+02
3.652	0.9957E+03	0.1096E+04	0.6635E+03	0.1594E+04	0.7938E-05	0.3107E+03
3.758	0.8749E+03	0.1104E+04	0.3733E+03	0.1832E+04	0.1713E-04	0.5450E+03
3.866	0.7749E+03	0.1146E+04	0.4692E+03	0.1434E+04	0.2066E-04	0.5762E+03
3.981	0.6913E+03	0.1207E+04	0.7521E+03	0.9587E+03	0.1349E-04	0.3424E+03
4.097	0.6564E+03	0.1256E+04	0.7827E+03	0.1057E+04	0.2162E-05	0.5085E+02
4.217	0.6840E+03	0.1262E+04	0.4819E+03	0.1478E+04	0.3315E-05	0.7306E+02
4.340	0.7565E+03	0.1200E+04	0.2573E+03	0.1442E+04	0.3250E-04	0.6740E+03
4.467	0.8272E+03	0.1071E+04	0.4213E+03	0.8831E+03	0.9022E-04	0.1766E+04
4.597	0.8416E+03	0.9070E+03	0.7300E+03	0.5434E+03	0.1557E-03	0.2880E+04
4.731	0.7678E+03	0.7631E+03	0.7698E+03	0.7172E+03	0.1955E-03	0.3421E+04
4.870	0.6198E+03	0.6909E+03	0.5900E+03	0.6769E+03	0.1824E-03	0.3042E+04
5.012	0.4586E+03	0.7125E+03	0.5256E+03	0.8769E+03	0.1224E-03	0.1916E+04
5.158	0.3622E+03	0.8043E+03	0.5609E+03	0.8137E+03	0.4455E-04	0.6742E+03
5.309	0.3748E+03	0.9018E+03	0.4362E+03	0.9285E+03	0.1532E-05	0.2142E+02
5.464	0.4691E+03	0.9297E+03	0.2500E+03	0.7203E+03	0.2062E-04	0.2728E+03
5.623	0.5596E+03	0.8475E+03	0.2884E+03	0.4146E+03	0.9036E-04	0.1130E+04
5.78E	0.5635E+03	0.6797E+03	0.4450E+03	0.4237E+03	0.1599E-03	0.1892E+04
5.957	0.4646E+03	0.5010E+03	0.4789E+03	0.5285E+03	0.1757E-03	0.1969E+04
6.130	0.3300E+03	0.3881E+03	0.4612E+03	0.5468E+03	0.1242E-03	0.1321E+04
6.309	0.2598E+03	0.3716E+03	0.4695E+03	0.3525E+03	0.6983E-04	0.5999E+03
6.494	0.2972E+03	0.4186E+03	0.3497E+03	0.2943E+03	0.2124E-04	0.1808E+03
6.683	0.3834E+03	0.4578E+03	0.2392E+03	0.2932E+03	0.1994E-04	0.1854E+03
6.878	0.4154E+03	0.4354E+03	0.2588E+03	0.2673E+03	0.7134E-04	0.6411E+03
7.079	0.3542E+03	0.3533E+03	0.3219E+03	0.3217E+03	0.9679E-04	0.8469E+03
7.286	0.2652E+03	0.2599E+03	0.3695E+03	0.3525E+03	0.6983E-04	0.5999E+03
7.499	0.2423E+03	0.2096E+03	0.3497E+03	0.2943E+03	0.2124E-04	0.1808E+03
7.718	0.2930E+03	0.2182E+03	0.2915E+03	0.2169E+03	0.3006E-08	0.2657E-01
7.943	0.3328E+03	0.2512E+03	0.2390E+03	0.1825E+03	0.1598E-04	0.1378E+03
8.175	0.3027E+03	0.2600E+03	0.2252E+03	0.2257E+03	0.3488E-04	0.3072E+03
8.414	0.2474E+03	0.2291E+03	0.2884E+03	0.2348E+03	0.2839E-04	0.2578E+03
8.659	0.2385E+03	0.1892E+03	0.2716E+03	0.1934E+03	0.8227E-05	0.7765E+02
8.912	0.2644E+03	0.1769E+03	0.2620E+03	0.1753E+03	0.1213E-07	0.1209E+00
9.173	0.2626E+03	0.1903E+03	0.2104E+03	0.1816E+03	0.4717E-05	0.4899E+02
9.440	0.2297E+03	0.1980E+03	0.2176E+03	0.2057E+03	0.6571E-05	0.7173E+02
9.716	0.2109E+03	0.1867E+03	0.2090E+03	0.1845E+03	0.2501E-05	0.2854E+02
10.000	0.2081E+03	0.1737E+03	0.2046E+03	0.1817E+03	0.8259E-07	0.9623E+00
10.292	0.1941E+03	0.1718E+03	0.1755E+03	0.1752E+03	0.9322E-07	0.1010E+01
10.592	0.1755E+03	0.1705E+03	0.1710E+03	0.1752E+03	0.4742E-10	0.2429E+00
10.902	0.1608E+03	0.1646E+03	0.1439E+03	0.1843E+03	0.2018E-06	0.4815E+01
11.220	0.1401E+03	0.1626E+03	0.1389E+03	0.1625E+03	0.2298E-07	0.5046E+00
11.548	0.1254E+03	0.1588E+03	0.1153E+03	0.1588E+03	0.9230E-06	0.2077E+02
11.885	0.1179E+03	0.1419E+03	0.1174E+03	0.1438E+03	0.3327E-05	0.7867E+02
12.232	0.9731E+02	0.1282E+03	0.9310E+02	0.1344E+03	0.1486E-05	0.3726E+02
12.589	0.8516E+02	0.1249E+03	0.7968E+02	0.1178E+03	0.5919E-06	0.1581E+02
12.957	0.8566E+02	0.1086E+03	0.8390E+02	0.9996E+02	0.5806E-05	0.1652E+03
13.335	0.7124E+02	0.8545E+02	0.7499E+02	0.9348E+02	0.3609E-05	0.1094E+03
13.724	0.6853E+02	0.7890E+02	0.6493E+02	0.7443E+02	0.2516E-06	0.8122E+01
14.125	0.7278E+02	0.7270E+02	0.6619E+02	0.6816E+02	0.5545E-05	0.1902E+03
14.538	0.6462E+02	0.5898E+02	0.7233E+02	0.6429E+02	0.2719E-05	0.9893E+02
14.962	0.7152E+02	0.5729E+02	0.6739E+02	0.5492E+02	0.4641E-06	0.1788E+02

15.399	0.7138E+02	0.6050E+02	0.7010E+02	0.6026E+02	0.3240E-05	0.1318E+03
15.849	0.7056E+02	0.5753E+02	0.7279E+02	0.5727E+02	0.4319E-06	0.1852E+02
16.311	0.7358E+02	0.6050E+02	0.6913E+02	0.5983E+02	0.5730E-06	0.2582E+02
16.788	0.6910E+02	0.6292E+02	0.7023E+02	0.6141E+02	0.3964E-06	0.1871E+02
17.278	0.6677E+02	0.6188E+02	0.6675E+02	0.6160E+02	0.2728E-08	0.1339E+00
17.782	0.6084E+02	0.6077E+02	0.6073E+02	0.6085E+02	0.9985E-08	0.5600E+00
18.302	0.5336E+02	0.5775E+02	0.5254E+02	0.5834E+02	0.1376E-07	0.7558E+00
18.836	0.4652E+02	0.5286E+02	0.4582E+02	0.5156E+02	0.5230E-06	0.2975E+02
19.386	0.3827E+02	0.4551E+02	0.3765E+02	0.4651E+02	0.2759E-06	0.1627E+02
19.952	0.3363E+02	0.4003E+02	0.3233E+02	0.3724E+02	0.1034E-05	0.6312E+02
20.535	0.2827E+02	0.3155E+02	0.2912E+02	0.3287E+02	0.6031E-06	0.3807E+02

RMS VALUES-CROSS LEVEL INPUT

LATERAL CONTACT FORCES

AXLE 1 =0.134E+03
 AXLE 2 =0.107E+03
 AXLE 3 =0.130E+03
 AXLE 4 =0.127E+03

LATERAL POSITION OF RESULTANT CENTERPLATE FORCE = 0.254E-01

LATERAL FORCE AT THE CENTERPLATE = 0.123E+03

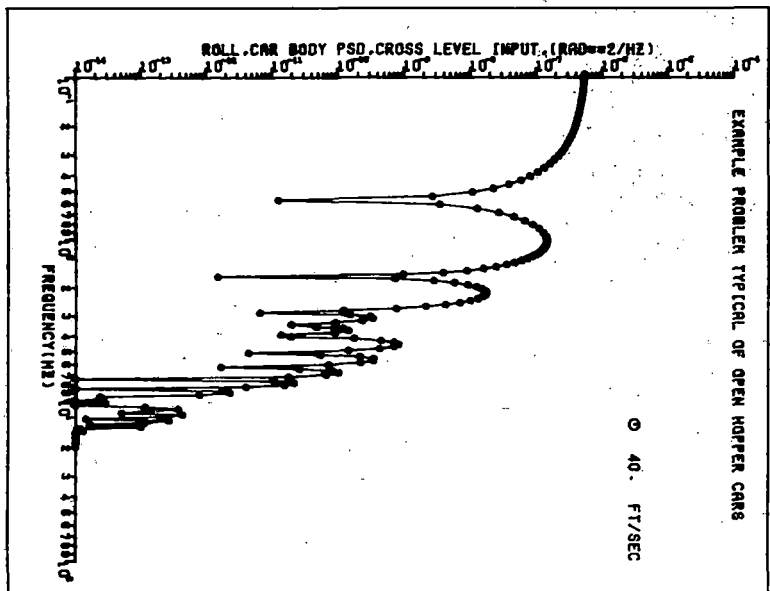
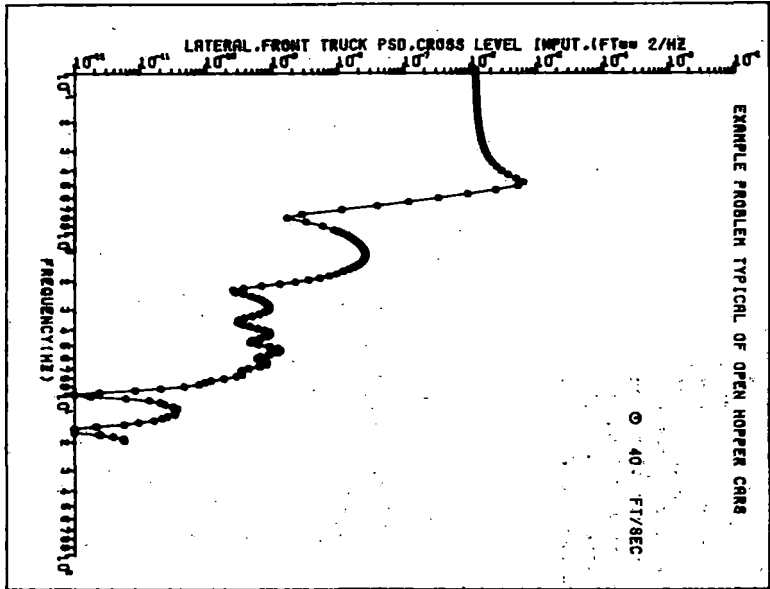
SAMPLE PLOTTED OUTPUT

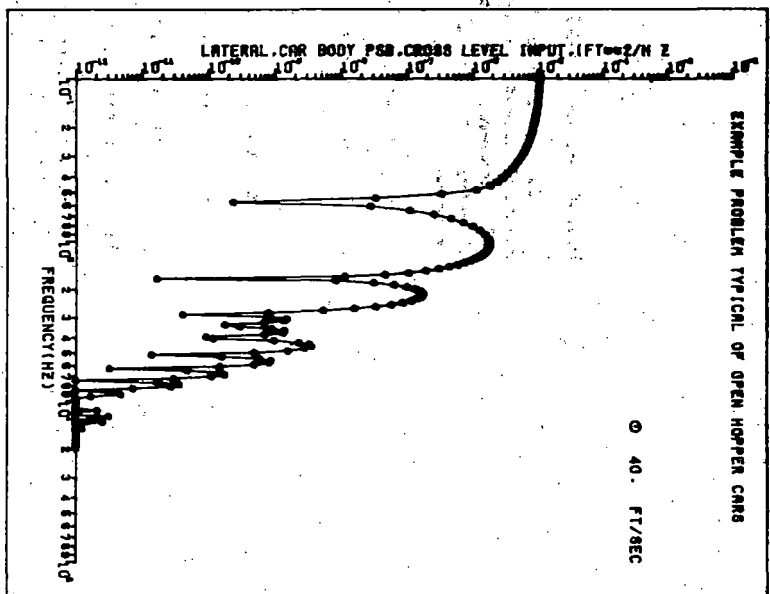
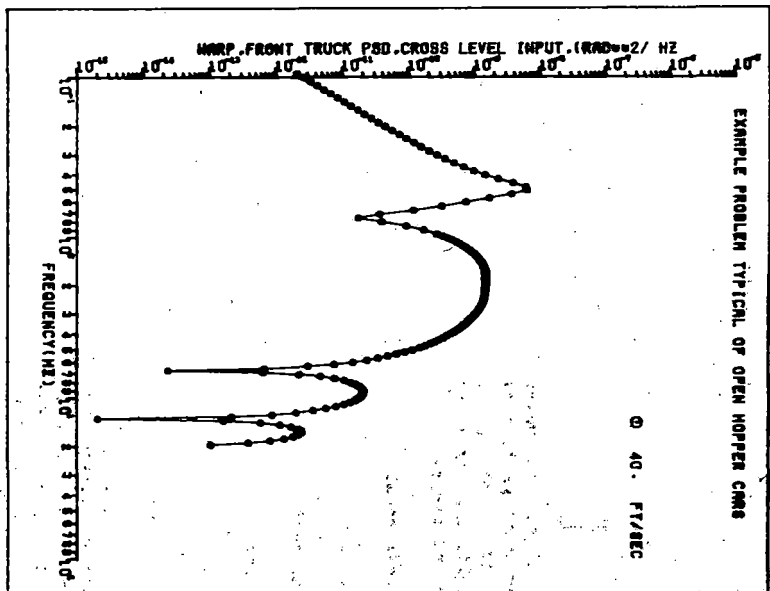
The following 12 plots depict the power spectral density of (PSD) information plotted by this computer program. The first six plots illustrate the PSD's for the following variables in response to a random, crosslevel input:

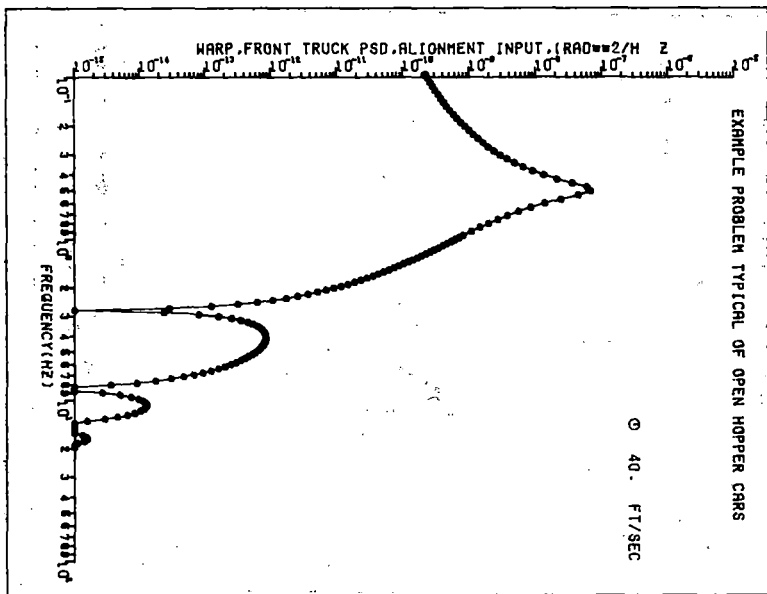
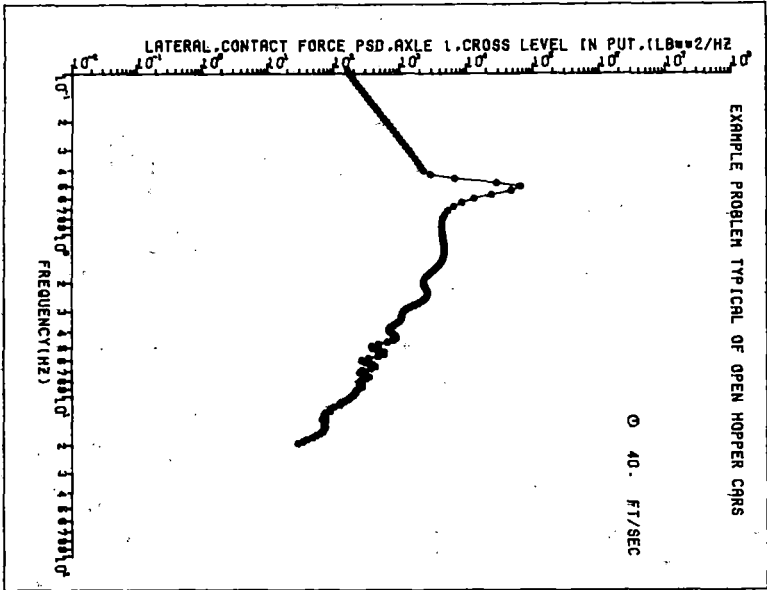
1. Front-truck lateral displacement
2. Front truck warp displacement
3. Car body lateral displacement
4. Car body roll displacement
5. Lateral contact force, axle 1
6. Lateral contact force, axle 3.

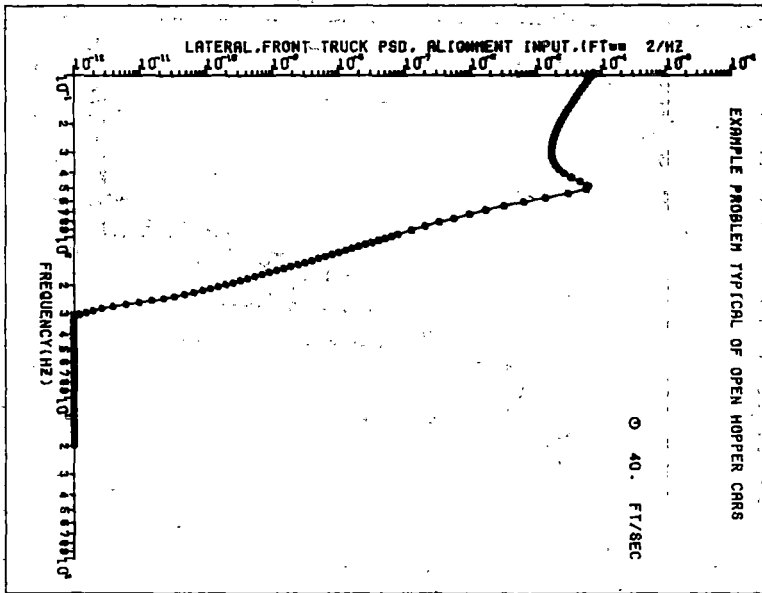
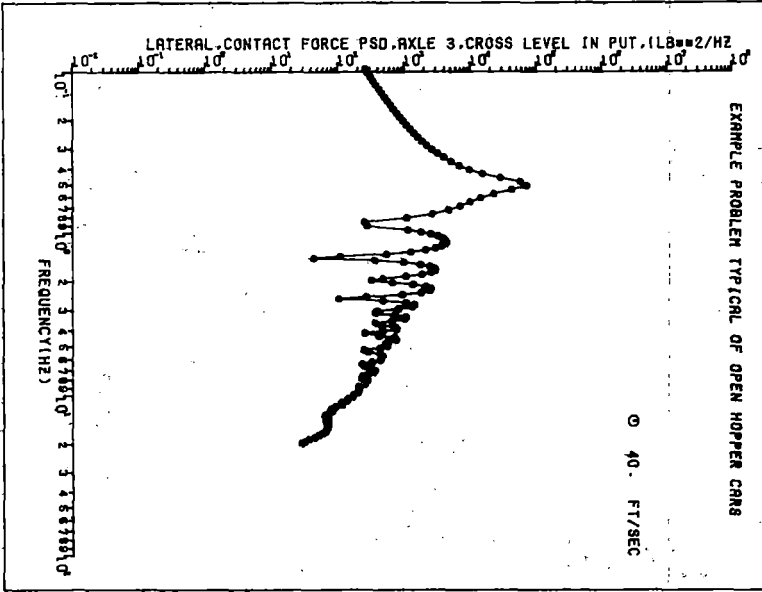
The second six plots show the response of the same variables to a random alignment disturbance. Although the response is shown at only one speed in this example, results for multiple speeds will be plotted on the same plots if multiple speed calculations are specified.

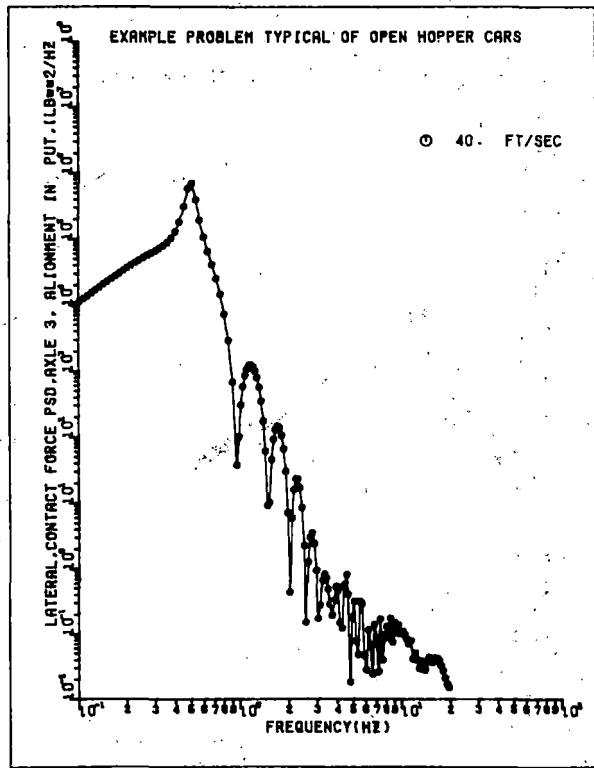
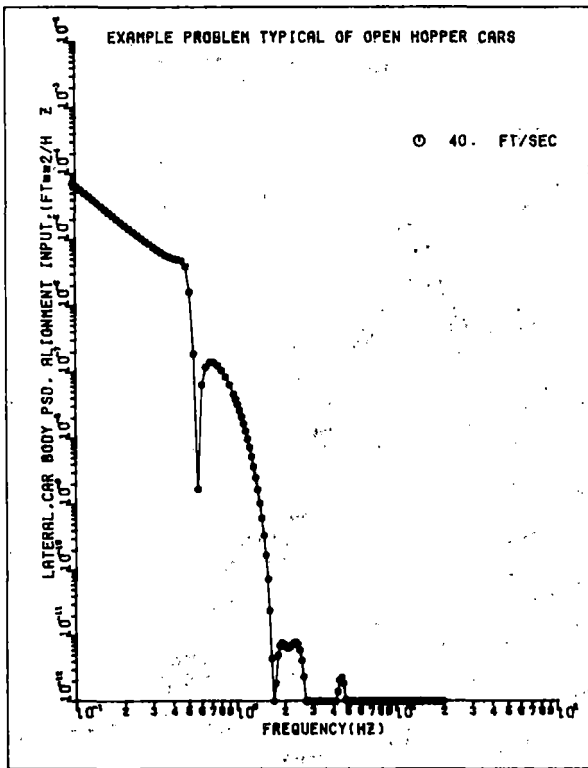
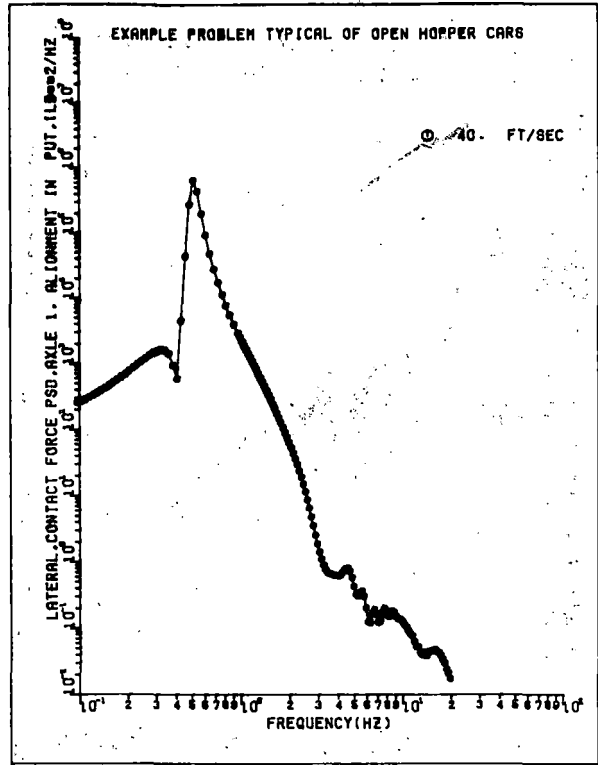
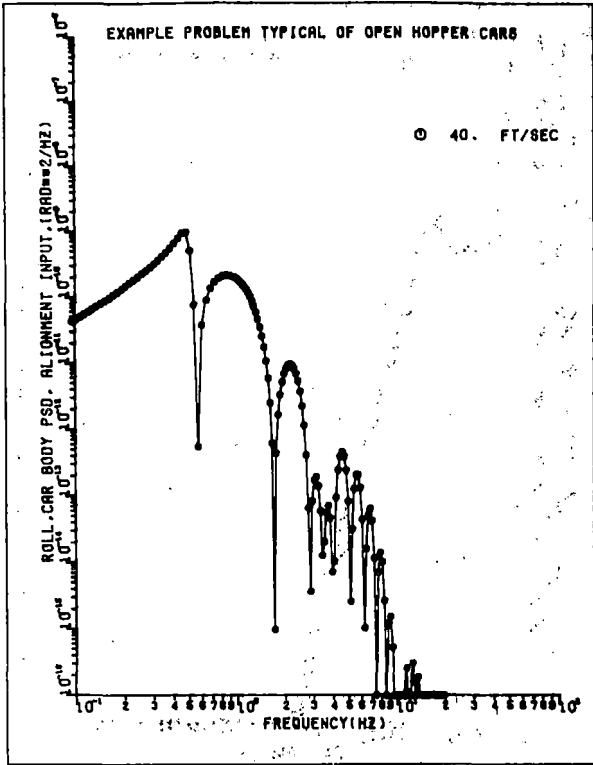
In the truck lateral and warp PSD's, the dominant kinematic mode at about 0.5 Hz is evident, both in response to crosslevel and alignment inputs. This mode is partially masked in the car body lateral and roll response by dropouts that occur at nearly the same frequency. These dropouts are due to the geometric filtering effect of the truck and car body acting as traveling chords. Higher harmonics of the fundamental filter frequencies cause the lobes in these plots at high frequencies.











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3. Haque, I., Law, E.H. and Cooperrider, N.K., "Users' Manual for Lateral Stability Computer Programs for Railway Freight Car Models," Federal Railroad Administration Report No. FRA-OR+D-80-30, April 1980.
4. Cooperrider, N.K., Law, E.H., Hull, R., Kadala, P.S. and Tuten, J.M., "Analytical and Experimental Determination on Nonlinear Wheel/Rail Geometric Constraints," Report No. FRA-OR+D-76-244 (PB 252290) December 1975.
5. Hedrick, J.K., Cooperrider, N.K. and Law, E.H., "The Application of Quasilinearization Techniques to Rail Vehicle Dynamic Analyses," FRA-OR+D-78-56, November 1978.
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8. Kalker, J.J., "On the Rolling Contact of Two Elastic Bodies in the Presence of Dry Friction," Doctoral Dissertation, Technische Hogeschool, Delft, The Netherlands, 1967.
9. Goree, J.G. and Law, E.H., "Users' Manual for Kalker's Simplified Nonlinear Creep Theory," FRA-OR+D-78-06, August 1977.
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C	TERM64=-W*W	00073000
C	TERM65=ICZ/WC	00074000
C	TERM73=TERM27*W	00075000
C	TERM74=TERM26*W	00076000
C	TERM75=TERM20*W	00077000
C	TERM76=TERM17*W	00078000
C	TERM77=TERM16*W	00079000
C	TERM78=TERM15*W	00080000
C	TERM79=TERM14*W	00081000
C	TERM80=-TERM13*W	00082000
C	TERM83=IWX*V/(R0*X)	00083000
C	TERM89=A13+A14	00084000
C	TERM90=A13-A14	00085000
C	TERM91=A11+A12	00086000
C	TERM92=A11-A12	00087000
C	TERM93=2.*R0*F12/(V*X)	00088000
C	TERM94=4.*L1*L1*F11/V	00089000
C	TERM96=4.*F12/V	00090000
C	TERM98=4.*(F22+X*X*F33)/V	00091000
C	TERM99=2.*F11*R0*L1/(X*V)	00092000
C		00093000
C	EQUIVALENCE (RW,XRW),(LWX,XLW1),(LWY,XLW2),(HB,XHB),	00094000
1	(LEY,XLB2),(LBZ,XLB3),(MSF,XMS),(LSFY,XLS2),(MC,XMC),	00095000
2	(ICY,XIC2),(ICZ,XIC3),(ICYZ,XIC23),(L1,TL),(X,A),(H2,H1,HCG),	00096000
3	(L2,CLF),(L3,CLR),(A11,GAM1),(A12,GAM2),(A13,GAM3),(A14,GAM4),	00097000
+	(D111,BDEL1),(DT12,BDEL2),(DT13,BDEL3),(DT14,BDEL4),	00098000
5	(D101,DEL01),(D102,DEL02),(D103,DEL03),(D104,DEL04),	00099000
6	(LB11,ALAM11),(LB12,ALAM12),(LB13,ALAM13),(LB14,ALAM14),	00100000
7	(KYF,XKYF),(KXF,XKXF),(KYR,XKYR),(KXR,XKXR),(DTHBF,DTCPF),	00101000
8	(DTHWF,DTWF),(KTHBF,XKICPF),(KTHWF,XKTWF),(DTHBR,DTCPB),	00102000
9	(DTHWR,DTWR),(KTHBR,XKICPB),(KTHWR,XKTWR)	00103000
	COMMON BR,BI,TE,TI	00104000
	DCUELE PRECISION DR,DI,DEIR,DETI,DEI	00105000
	REAL L1,L2,L3,RW,MSF,RC,LB11,LB12,LE13,LB14,MB	00106000
	REAL KXF,KXR,KYF,KYR,KTHBF,KTHBR,KTHWF,KTHWR	00107000
	REAL LSFY,LEY,LBZ,LWX,LWY,ICY,ICZ,ICYZ,H,K	00108000
	DIMENSION FR(200),BR(5),EI(9),FAR(9,8),FAL(9,8),UR(8),UI(8),	00109000
1	TFSE(10,200),TRMS(10),DR(81),DI(81),IC(9),MC1(9),TF(9),TI(9),	00110000
2	M(9,9),K(9,9),C(9,9),T(9,200),TRMS(10),I1PSD(10,200)	00111000
	DIMENSION FCLR(9,4),FCLF(9,4),U1R(4),D1I(4),D1R(9),D1I(9),	00112000
1	T1E(9),T1I(9),T1(9,200)	00113000
	DIMENSION FRL(6),F1(6),F(6,200),F1E(6),F1I(6),F1(6,200)	00114000
	DIMENSION FPSD(10),I1PSD(10),FPSD(6),F1PSD(6)	00115000
	DIMENSION FRMS(6),FRSE(6,200),F1RMS(6),F1PSE(6,200)	00116000
	DIMENSION LABEL(20)	00117000
	COMMON /NAME1/A11,A12,A13,A14,ALH11,ALH21,ALH31,ALH41,	00118000
1	D,DEL0F,DEL0R,D101,D102,D103,D104,D111,DT12,DT13,DT14,	00119000
2	DTHBF,DTHBR,DXF,DXR,DYF,DYR,EPL11,EPL21,EPL31,EPL41,	00120000
3	EPL51,EPL61,EPL71,EPL81,F11,F12,F22,F33,H1,IBY,IBZ,	00121000
4	ICY,ICZ,ICYZ,IWX,IWY,KTHBF,KTHBR,KTHWF,KTHWR,KXF,KXR,	00122000
5	KYF,KYR,L1,L2,L3,LB11,LE12,LE13,LE14,MB,MC,MSF,MW,	00123000
6	FO,RHO1,RHO21,RHO31,RHO41,RHO51,BHC61,RHO71,RHO81,W3,WC,	00124000
7	WF,WN,WR,WT,X,DTHWF,DTHWR,LSFY,ALH51,ALH61,ALH71,ALH81	00125000
	COMMON /NAME2/TERM13,TERM14,TERM15,TERM16,TERM17,TERM20,	00126000
1	TERM26,TERM27,TERM34,TERM40,TERM44,TERM42,TERM43,TERM44,	00127000
2	TERM45,TERM46,TERM47,TERM48,TERM49,TERM50,TERM51,	00128000
3	TERM52,TERM53,TERM54,TERM55,TERM56,TERM57,TERM58,	00129000
4	TERM59,TERM60,TERM64,TERM65,TERM89,TERM90,TERM91,	00130000
5	TERM92,TERM21,TERM35	00131000
		00132000

```

C *** INPUT AND INITIALIZATION ***
READ (1,*) IVO, IVP, IDV
READ (1,*) FSTART, FSTEP, FSTOP
FE(1)=FSTART
DTF=10.** (1./FSTEP)
IFSTEP=FSTEP
DC 101 IWN=1, IFSTEP
FR(IWN+1)=FR(IWN)*DTF
N=IWN
101 CONTINUE
DTF=10.** (.5/FSTEP)
DC 102 IWN=IWN,197
FR(IWN+1)=FR(IWN)*DTF
N=IWN
IF (FR(IWN).GT.FSTOP) GO TO 104
102 CONTINUE
STOP
104 REAL (1,*) AX, APHI, OHGC, OHGS
C
C *** INPUT***
READ (1,151) (LABEL(I), I=1,20)
151 FCENAT(20A4)
READ (1,*,END=50) IWB, XIW1, XIW2
READ (1,*) XWB, XIW2, XIW3
READ (1,*) XNS, XIS2
READ (1,*) XMC, XIC2, XIC3, XIC23
REAL (1,*) TL, D, RO, A
READ (1,*) HCG, CLF, CLR
REAL (1,*) GAM1, BDEL1, DEL01, ALAM11
REAL (1,*) GAM2, BDEL2, DEL02, ALAM12
REAL (1,*) GAM3, BDEL3, DEL03, ALAM13
REAL (1,*) GAM4, BDEL4, DEL04, ALAM14
REAL (1,*) F11, F12, F22, F33
READ (1,*) DYF, DXF, XKYF, XKXF
READ (1,*) DYB, DXR, XKYR, XKXR
READ (1,*) DTCPF, DTWF, XKICFF, KKTWF
REAL (1,*) DTCPR, DTWR, XKICER, KKTWR
AIH11=.5*A11
AIH21=.5*A12
AIH31=.5*A13
AIH41=.5*A14
AIH51=.5*A11
AIH61=.5*A12
AIH71=.5*A13
AIH81=.5*A14
EEL11=.5*DT11
EEL21=.5*DT12
EEL31=.5*DT13
EEL41=.5*DT14
EEL51=.5*DT11
EEL61=.5*DT12
EEL71=.5*DT13
EEL81=.5*DT14
RHC11=.5*LB11
RHC21=.5*LB12
RHC31=.5*LB13
RHC41=.5*LB14
RHC51=.5*LB11
RHC61=.5*LB12
RHC71=.5*LB13
RHC81=.5*LB14
WF=(4.*MW+4.*MSF+MC+2.*ME)/4.*32.2
WF=WF
WT=32.2*(2.*MW+2.*MSF+MB)
WE=32.2*MB
WC=MC*32.2
WN=WF/2
DELOF=16.1*(L3*MC+(L2+L3)*MB)/KYF/(L2+L3)
DELOB=16.1*(L2*MC+(L2+L3)*MB)/KYR/(L2+L3)
00133000
00134000
00135000
00136000
00137000
00138000
00139000
00140000
00141000
00142000
00143000
00144000
00145000
00146000
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00197000
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00199000
00200000
00201000
00202000

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N=9
PI=3.141593
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CMGS2=OMGS**2

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00204000

00205000

00206000

00207000

00208000

00209000

00210000

00211000

00212000

00213000

00214000

00215000

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00217000

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00248000

00249000

00250000

00251000

00252000

00253000

00254000

00255000

00256000

00257000

00258000

00259000

00260000

00261000

00262000

00263000

00264000

00265000

00266000

00267000

00268000

00269000

00270000

00271000

00272000

C *** PRINT INPUT PARAMETERS ***

WRITE(6,300) LABEL

300 FORMAT(1H1,1CX,20A4/////)

WRITE(6,320) MC,MB,MSF,M*,ICX,ICZ,ICYZ,IBY,IBZ,ISFY

320 FORMAT(25X,'MASS PROPERTIES',///5X,

1'XMC (MASS OF THE CAR BODY)',5X,'=',E10.4,' SLUGS',/5X,

2'XMB (MASS OF THE BOLSTER)',6X,'=',E10.4,' SLUGS',/5X,

3'XMS (MASS OF THE SIDEFAME)',4X,'=',E10.4,' SLUGS',/5X,

4'XMW (MASS OF THE WHEELSET)',5X,'=',E10.4,' SLUGS',/5X,

5'XIC2 (MOMENT OF INERTIA OF THE CAR BODY IN YAW)',8X,

6'=',E10.4,' SLUG-FT**2',/5X,

7'XIC3 (MOMENT OF INERTIA OF THE CAR BODY IN ROLL)',7X,

8'=',E10.4,' SLUG-FT**2',/5X,

9'XIC23 (CROSS PRODUCT OF INERTIA FOR CAR BODY)',11X,

1'=',E10.4,' SLUG-FT**2',/5X,

2'XIE2 (MOMENT OF INERTIA OF THE BOLSTER IN YAW)',9X,

3'=',E10.4,' SLUG-FT**2',/5X,

4'XIE3 (MOMENT OF INERTIA OF THE BOLSTER IN ROLL)',8X,

5'=',E10.4,' SLUG-FT**2',/5X,

6'XIS2 (MOMENT OF INERTIA OF THE SIDEFAME IN YAW)',7X,

7'=',E10.4,' SLUG-FT**2')

WRITE(6,325) IWX,IWY

325 FORMAT(5X,

8'XIW1 (MOMENT OF INERTIA OF THE WHEELSET ABOUT AXLE)',4X,

9'=',E10.4,' SLUG-FT**2',/5X,

1'XIW2 (MOMENT OF INERTIA OF THE WHEELSET IN YAW)',8X,

2'=',E10.4,' SLUG-FT**2',/5X)

WRITE(6,330) KXF,KAR,KYF,KYR,KXBF,KXBR,KYWF,KYWR

330 FORMAT(25X,'STIFFNESS PROPERTIES',///5X,

1'KXFB (LATERAL STIFFNESS, SIDEFAME TO BOLSTER -FRONT-)',5X,

1'=',E10.4,' LB/FT',/5X,

2'KXBR (LATERAL STIFFNESS, SIDEFAME TO BOLSTER -REAR-)',6X,

2'=',E10.4,' LB/FT',/5X,

3'KYFB (VERTICAL STIFFNESS, SIDEFAME TO BOLSTER -FRONT-)',4X,

3'=',E10.4,' LB/FT',/5X,

4'KYBR (VERTICAL STIFFNESS, SIDEFAME TO BOLSTER -REAR-)',5X,

4'=',E10.4,' LB/FT',/5X,

5'KXCF (CENTERPLATE STIFFNESS -FRONT-)',23X,

5'=',E10.4,' FT-LB/RAD',/5X,

6'KXCR (CENTERPLATE STIFFNESS -REAR-)',24X,

6'=',E10.4,' FT-LB/RAD',/5X,

7'KXWF (TRUCK WARPING STIFFNESS -FRONT-)',21X,

7'=',E10.4,' FT-LB/RAD',/5X,

8'KXWR (TRUCK WARPING STIFFNESS -REAR-)',22X,

8'=',E10.4,' FT-LB/RAD',/5X)

WRITE(6,350) DTFW,DTRW,DXF,DXR,DYF,DYR,DTFBF,DTRBF

350 FORMAT(25X,'DAMPING PROPERTIES',///5X,

1'DTFB (WARPING DAMPING -FRONT-)',27X,

1'=',E10.4,' LB-SEC/FT',/5X,

2'DTRB (WARPING DAMPING -REAR-)',27X,

2'=',E10.4,' LB-SEC/FT',/5X,

3'DXF (LATERAL SIDEFAME TO BOLSTER DAMPING -FRONT-)',5X,

3'=',E10.4,' LB-SEC/FT',/5X,

4'DXBR (LATERAL SIDEFAME TO BOLSTER DAMPING -REAR-)',6X,

4'=',E10.4,' LB-SEC/FT',/5X,

5'DYFB (VERTICAL SIDEFAME TO BOLSTER DAMPING -FRONT-)',4X,

5'=',E10.4,' LB-SEC/FT',/5X,

6'DYBR (VERTICAL SIDEFAME TO BOLSTER DAMPING -REAR-)',5X,

6'=',E10.4,' LB-SEC/FT',/5X,

7'DTCF (CENTERPLATE DAMPING -FRONT-)',22X,

7'=',E10.4,' LB-SEC/FT',/5X,

8'DTCR (CENTERPLATE DAMPING -REAR-)',23X,

8'=',E10.4,' LB-SEC/FT',/5X)

WRITE(6,360) X,D,H1,L1,L2,L3,R0

360 FORMAT(1H1,24X,'DIMENSIONS',///5X,

1'A	(SEMI-DISTANCE BETWEEN WHEEL CONTACT POINTS)', 8X,	00273000
1'	'E10.4,' FT',/5X,	00274000
2'D	(SEMI-SPACING OF SIDEFRADE CENTER OF GRAVITIES)', 5X,	00275000
2'	'E10.4,' FT',/5X,	00276000
3'HCG	(VERTICAL DISTANCE BETWEEN TRUCK CG AND BODY CG)', 4X,	00277000
3'	'E10.4,' FT',/5X,	00278000
5'TL	(SEMI TRUCK WHEELBASE)', 30X,	00281000
5'	'E10.4,' FT',/5X,	00282000
6'CLF	(DISTANCE FROM BODY CG TO FRONT TRUCK)', 14X,	00283000
6'	'E10.4,' FT',/5X,	00284000
7'CLR	(DISTANCE FROM BODY CG TO REAR TRUCK)', 15X,	00285000
7'	'E10.4,' FT',/5X,	00286000
8'RO	(WHEEL ROLLING RADIUS)', 30X,	00287000
8'	'E10.4,' FT' ///	00288000
	WRITE(6,370) A11,A12,A13,A14,DT11,DT12,DT13,DT14	00289000
370	FORMAT(25X,'WHEEL CHARACTERISTICS',///5X,	00290000
1'GAM1	(ROLL COEFFICIENT, AXLE 1)', 4X,'=' 'E10.4,/5X,	00291000
2'GAM2	(ROLL COEFFICIENT, AXLE 2)', 4X,'=' 'E10.4,/5X,	00292000
3'GAM3	(ROLL COEFFICIENT, AXLE 3)', 4X,'=' 'E10.4,/5X,	00293000
4'GAM4	(ROLL COEFFICIENT, AXLE 4)', 4X,'=' 'E10.4,/5X,	00294000
5'BDEL1	(CONTACT ANGLE COEFFICIENT, AXLE 1)', 4X,'=' 'E10.4,/5X,	00295000
6'BDEL2	(CONTACT ANGLE COEFFICIENT, AXLE 2)', 4X,'=' 'E10.4,/5X,	00296000
7'BDEL3	(CONTACT ANGLE COEFFICIENT, AXLE 3)', 4X,'=' 'E10.4,/5X,	00297000
8'BDEL4	(CONTACT ANGLE COEFFICIENT, AXLE 4)', 4X,'=' 'E10.4/)	00298000
	WRITE(6,375) DL01,DL02,DL03,DL04,LB11,LB12,LB13,LB14	00299000
375	FORMAT(5X,	00300000
9'DE101	(INITIAL WHEEL/RAIL CONTACT ANGLE, AXLE 1)', 4X,	00301000
9'	'E10.4,/5X,	00302000
1'DE102	(INITIAL WHEEL/RAIL CONTACT ANGLE, AXLE 2)', 4X,	00303000
1'	'E10.4,/5X,	00304000
2'DE103	(INITIAL WHEEL/RAIL CONTACT ANGLE, AXLE 3)', 4X,	00305000
2'	'E10.4,/5X,	00306000
3'DE104	(INITIAL WHEEL/RAIL CONTACT ANGLE, AXLE 4)', 4X,	00307000
3'	'E10.4 //5X,	00308000
4'ALAM11	(CONICITY, AXLE 1)', 4X,'=' 'E10.4,/5X,	00309000
5'ALAM12	(CONICITY, AXLE 2)', 4X,'=' 'E10.4,/5X,	00310000
6'ALAM13	(CONICITY, AXLE 3)', 4X,'=' 'E10.4,/5X,	00311000
7'ALAM14	(CONICITY, AXLE 4)', 4X,'=' 'E10.4 //)	00312000
	WRITE(6,390) F11,F12,F22,F33	00313000
390	FORMAT(25X,'CREEP COEFFICIENTS',///5X,	00314000
1'F11	(LATERAL CREEP COEFFICIENT)', 9X,	00315000
1'	'E10.4,' LB',/5X,	00316000
2'F12	(LATERAL/SPIN CREEP COEFFICIENT)', 4X,	00317000
2'	'E10.4,' LB-FT',/5X,	00318000
3'F22	(SPIN CREEP COEFFICIENT)', 12X,	00319000
3'	'E10.4,' LB-FT**2',/5X,	00320000
4'F33	(LONGITUDINAL CREEP COEFFICIENT)', 4X,	00321000
4'	'E10.4,' LB' ///	00322000
	WRITE(6,395) AX,APHI,CMGC,CMGS	00323000
395	FORMAT(25X,'TRACK PROPERTIES',///5X,	00324000
1'AX	(CENTERLINE ALIGNMENT PSD COEFFICIENT)', 4X,'=' 'E10.4,	00325000
1'	FI**2-RAD/FT',/5X,	00326000
2'APHI	(CROSS LEVEL PSD COEFFICIENT)', 11X,'=' 'E10.4,	00327000
2'	FI**2-RAD/FT',/5X,	00328000
3'CMGC	(PSD ROLL OFF FREQUENCY)', 16X,	00329000
3'	'E10.4,' RAD/FT',/5X,	00330000
4'CMGS	(CROSS LEVEL PSD CONSTANT)', 14X,	00331000
4'	'E10.4,' RAD/FT'	00332000
		00333000
		00334000
	****INITIALIZATION OF PARAMETERS****	00335000
	CALL SETUP(M,C,K,FAR,FCLF)	00336000
	CALL PLOTS(0,0,3)	00337000
	CALL EXTEND(72.0)	00338000
	CALL PLOT(0.,0.,3)	00339000
	CALL FACTOR(-435)	00340000
	CALL PLOTA(LABEL)	00341000
	K1=0	00342000
	S=0.	00343000

```

C *** LOOP THROUGH EACH VELOCITY ***
  IWN=0
  DC 900 IV=IVO,IVF,IVD
  IVN=IVN+1
  V=IV
  PRINT 80,V
  80 FCNNAI(1H,2X,'VELOCITY=',F3.2,'FI/SEC//)
C ***TEEMS PROPORTIONAL TO VELOCITY***
  CALL VEL(N,C,K,V)
C
C ***FIND TRANSFER RATIO AT EACH FREQUENCY***
  DC 180 IWN=1,N
  W=FR(IWN)*6.2832
  CALL FREQ(FAI,FCUL,V,N)
C
  NAZ=AN*NN
  DC 100 I=1,NN
  DB(I)=0.
  DI(I)=0.
  100 CCNTINUE
  DC 110 I=1,NN
  DC 110 J=1,NN
  L=NN*(I-1)+J
  DB(L)=TERM64*M(I,J)+K(I,J)
  CI(L)=W*C(I,J)
  110 CCNTINUE
C ***INVERT DR AND DI ***
  CALL DCMINV(DR,DI,NN,DETR,DETI,LC,MC1)
C ***CHECK FOR SINGULAR MATRIX ****
  DET=DETR*DETI
  IF(DET) 140,120,140
  120 PRINT 130,V
  130 FCNNAI(2X,'*****SINGULAR MATRIX FOR V=',F3.2,'*****')
  GC IC 290
  140 CCNTINUE
  DC 144 I=1,NN
  TE(I)=0.
  TI(I)=0.
  EE(I)=0.
  EI(I)=0.
  144 CCNTINUE
  DC 150 I=1,NN
  TE(I)=0.
  TI(I)=0.
  EE(I)=0.
  EI(I)=0.
  150 CCNTINUE
C *** DEFINE INPUT VECTOR, REAL AND IMAG ***
C
  UF(1)=1.
  UF(2)=1.
  UR(3)=COS(2.*L1*W/V)
  UF(4)=UR(3)
  UE(5)=COS((L2+L3)*W/V)
  UF(6)=UR(5)
  UE(7)=COS((2.*L1+L2+L3)*W/V)
  UE(8)=UR(7)
  UI(1)=0.
  UI(2)=0.
  UI(3)=SIN(2.*L1*W/V)
  UI(4)=UI(3)
  UI(5)=SIN((L2+L3)*W/V)
  UI(6)=UI(5)
  UI(7)=SIN((2.*L1+L2+L3)*W/V)
  UI(8)=UI(7)
  U1E(1)=1.
  U1E(2)=UR(3)

```


UR (3) = UR (5) 004 15000
 UR (4) = UR (7) 004 16000
 U1I (1) = 0. 004 17000
 U1I (2) = UI (3) 004 18000
 U1I (3) = UI (5) 004 19000
 U1I (4) = UI (7) 004 20000
 DC 152 I = 1, 9 004 21000
 DC 152 J = 1, 4 004 22000
 B1R (I) = B1R (I) + FC1R (I, J) * U1R (J) - FC1I (I, J) * U1I (J)
 E1I (I) = B1I (I) + FC1R (I, J) * U1I (J) + FC1I (I, J) * U1R (J)
 152 CCNTINUE 004 23000
 DC 155 I = 1, 9 004 24000
 DC 155 J = 1, 8 004 25000
 BR (I) = BR (I) + FAR (I, J) * UR (J) - FARI (I, J) * UI (J)
 EI (I) = BI (I) + FAR (I, J) * U1 (J) + FALI (I, J) * UR (J)
 155 CCNTINUE 004 26000
 DC 160 I = 1, MN 004 27000
 DC 160 J = 1, MN 004 28000
 J1 = J + (I - 1) * MN 004 29000
 TR (I) = TR (I) + DR (J) * DR (J1) - BI (J) * DI (J1)
 TI (I) = TI (I) + BR (J) * DI (J1) + BI (J) * DR (J1)
 T1R (I) = T1R (I) + D1R (J) * DR (J1) - B1I (J) * D1I (J1)
 T1I (I) = T1I (I) + B1R (J) * DI (J1) + B1I (J) * DR (J1)
 160 CCNTINUE 004 30000

C ** LATERAL POSITION OF THE RESULTANT CENTERPLATE FORCE **
 FFL (1) = TERF65 * TERF64 * TR (9) - H2 * TR (9) + TERF64 * TR (7) / 32.2)
 F1 (1) = TERM65 * TERM64 * TI (9) - H2 * TI (9) + TERM64 * TI (7) / 32.2)
 F1R (1) = TERM65 * TERM64 * TR (9) - H2 * TR (9) + TERM64 * TR (7) / 32.2)
 F1I (1) = TERM65 * TERM64 * TI (9) - H2 * TI (9) + TERM64 * TI (7) / 32.2)
 004 4000
 004 45000
 004 46000
 004 47000
 004 48000
 004 49000
 004 50000
 004 51000
 004 52000
 004 53000

C ** LATERAL FORCE AT CENTERPLATE **
 FFI (2) = WC * TR (9) + TERM64 * TR (7) / 32.2)
 FI (2) = WC * TI (9) + TERM64 * TI (7) / 32.2)
 FIR (2) = WC * TR (9) + TERM64 * TR (7) / 32.2)
 FII (2) = WC * TI (9) + TERM64 * TI (7) / 32.2)
 004 54000
 004 55000
 004 56000
 004 57000
 004 58000
 004 59000

C ** LATERAL CONTACT FORCE **
 FFL (3) = TERM40 * TI (1) + TERM41 * TR (1) + TERM42 * TI (2) + TERM43 * TR (2)
 1TERM38 * TI (3) + F11 * TR (3) + TERM44
 FI (3) = TERF40 * TR (1) + TERF41 * TI (1) + TERF42 * TR (2) + TERF43 * TI (2)
 1TERM38 * TR (3) + F11 * TI (3) + TERM44
 FIR (3) = TERF40 * TI (1) + TERF41 * TR (1) + TERF42 * TI (2) + TERF43 * TR (2)
 1TERM38 * TI (3) + F11 * TR (3) + TERM44
 F1I (3) = TERM40 * TR (1) + TERM41 * TI (1) + TERM42 * TR (2) + TERM43 * TI (2)
 1TERM38 * TR (3) + F11 * TI (3) + TERM44
 FFI (4) = TERF45 * TI (1) + TERF46 * TR (1) + TERF47 * TI (2) + TERF48 * TR (2)
 1TERM38 * TI (3) + F11 * TR (3) + TERM49
 FI (4) = TERM45 * TR (1) + TERM46 * TI (1) + TERM47 * TR (2) + TERM48 * TI (2)
 1TERM38 * TR (3) + F11 * TI (3) + TERM49
 FIR (4) = TERF45 * TI (1) + TERF46 * TR (1) + TERF47 * TI (2) + TERF48 * TR (2)
 1TERM38 * TI (3) + F11 * TR (3) + TERM49
 F1I (4) = TERM45 * TR (1) + TERM46 * TI (1) + TERM47 * TR (2) + TERM48 * TI (2)
 1TERM38 * TR (3) + F11 * TI (3) + TERM49
 FFI (5) = TERM50 * TI (4) + TERM51 * TR (4) + TERM52 * TI (5) + TERM53 * TR (5)
 1TERM38 * TI (6) + F11 * TR (6) + TERM54
 FI (5) = TERM50 * TR (4) + TERM51 * TI (4) + TERM52 * TR (5) + TERM53 * TI (5)
 1TERM38 * TR (6) + F11 * TI (6) + TERM54
 FIR (5) = TERM50 * TI (4) + TERM51 * TR (4) + TERM52 * TI (5) + TERM53 * TR (5)
 1TERM38 * TI (6) + F11 * TR (6) + TERM54
 F1I (5) = TERM50 * TR (4) + TERM51 * TI (4) + TERM52 * TR (5) + TERM53 * TI (5)
 1TERM38 * TR (6) + F11 * TI (6) + TERM54
 FFI (6) = TERM55 * TI (4) + TERM56 * TR (4) + TERM57 * TI (5) + TERM58 * TR (5)
 1TERM38 * TI (6) + F11 * TR (6) + TERM59
 FI (6) = TERM55 * TR (4) + TERM56 * TI (4) + TERM57 * TR (5) + TERM58 * TI (5)
 1TERM38 * TR (6) + F11 * TI (6) + TERM59
 FIR (6) = TERM55 * TI (4) + TERM56 * TR (4) + TERM57 * TI (5) + TERM58 * TR (5)
 1TERM38 * TI (6) + F11 * TR (6) + TERM59
 F1I (6) = TERM55 * TR (4) + TERM56 * TI (4) + TERM57 * TR (5) + TERM58 * TI (5)
 1TERM38 * TR (6) + F11 * TI (6) + TERM59
 004 75000
 004 76000
 004 77000
 004 78000
 004 79000
 004 80000
 004 81000
 004 82000
 004 83000
 004 84000
 004 85000

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C **** TRANSFER RATIO MAGNITUDE ***
C DC 170 J=1,9
C T(J,IWN)=SQRT(TR(J)**2+T1(J)**2)
C T1(J,IWN)=SQRT(T1R(J)**2+T1L(J)**2)
170 CCNTINUE
C DC 175 J=1,6
C F(J,IWN)=SQRT(FRL(J)**2+FI(J)**2)
C F1(J,IWN)=SQRT(F1R(J)**2+F1L(J)**2)
175 CCNTINUE
180 CCNTINUE
C ** FIND RMS AND PSD VALUES **
C N1=NN+1
C DC 190 I=1,N1
C TRMS(I)=0.
C TRMS(I)=0.
C DC 190 J=1,N
C TESI(I,J)=0.
C T1PSD(I,J)=0.
190 CCNTINUE
C DC 200 I=1,6
C FRMS(I)=0.
C FRMS(I)=0.
C DC 200 J=1,N
C FESE(I,J)=0.
C FESE(I,J)=0.
200 CCNTINUE
C *** LOOP THROUGH EACH FREQUENCY ***
C DC 280 IWN=1,N
C W=2.*PI*FR(IWN)
C W2=W**2
C V2=V*V
C V3=V*V2
C ** CHOOSE TRACK APPROXIMATION ***
C ** CENTERLINE ALIGNMENT TRACK APPROXIMATION **
C FAX=2.*PI*AX*V/W2/(1.+W2/V2/OMGC2)
C ** CROSS LEVEL TRACK APPROXIMATION **
C PAPHI=1.28*PI*APHI*V3*CMGC2/(W2+V2*OMGS2)/(W2+V2*OMGC2)
C
C T1ESD(N1,IWN)=PAX
C T1ESD(N1,IWN)=PAPHI
C DC 230 I=1,NN
C TESI(I,IWN)=T(I,IWN)**2*FAX
C T1ESI(I,IWN)=T1(I,IWN)**2*PAPHI
230 CCNTINUE
C DC 235 I=1,6
C FESE(I,IWN)=F(I,IWN)**2*FAX
C F1ESE(I,IWN)=F1(I,IWN)**2*FAPHI
235 CCNTINUE
C IF(I*NN-1) 240,240,260
C FECCG=FR(IWN)
C DC 250 I=1,N1
C T1ESD(I)=TPSD(I,IWN)
C T1ESD0(I)=T1PSD(I,IWN)
250 CCNTINUE
C DC 255 I=1,6
C FESE0(I)=FPSPD(I,IWN)
C F1PSD0(I)=F1PSD(I,IWN)
255 CCNTINUE
C GC TO 280
C DFEQ=FR(IWN)-FREQ
C FECCO=FR(IWN)
C DC 270 I=1,N1
C TRMS(I)=TRMS(I)+.5*DFREQ*(TPSD0(I)+TPSD(I,IWN))
C TRMS(I)=T1RMS(I)+.5*CFREQ*(T1PSD0(I)+T1PSD(I,IWN))
C T1PSD0(I)=T1PSD(I,IWN)
270 CCNTINUE

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```

DC 275 I=1,6
FRMS(I) =FRMS(I) +.5*DEBEG*(FSPSD(I) +FSPSD(I,1M))
F1RMS(I) =F1RMS(I) +.5*DEBEG*(F1PSD0(I) +F1PSD(I,1M))
FSPSD(I) =FSPSD(I,1M)
F1PSD0(I) =F1PSD(I,1M)
00556000
00557000
00558000
00559000
00560000
00561000
00562000
00563000
00564000
00565000
00566000
00567000
00568000
00569000
00570000
00571000
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00573000
00574000
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00613000
00614000
00615000
00616000
00617000
00618000
00619000
00620000
00621000
00622000
00623000
00624000
00625000

C
*** OUTPUT ****
PRINT 710
FCRMAI(1H1,21X,*****ESD VALUES FOR ALIGNMENT INPUTS*****)
PRINT 760
FCRMAI(///,4X,'FREQUENCY',3X,'PSD(1)',5X,'PSD(2)',5X,'PSD(3)',5X,
1'ESD(4)',5X,'PSD(5)',5X,'PSD(6)',5X,'ESD(7)',5X,'PSD(8)',5X,
1'ESD(9)')
DC 781 I=1,N
PRINT 770,FR(I), (TPSD(J),J=1,9)
FCRMAI(2X,F9.5,9(2X,E9.4))
PRINT 790
FCRMAI(1H1,6X,'RMS VALUES-ALIGNMENT INPUT')
PRINT 800,(I,FRMS(I),I=1,10)
FCRMAI(///,9(2X,RMS(I),I=1,9) =,E9.3//,2X,'RMS(I),I=,E9.3)
ERINT 801
FCRMAI(1H1,21X,***** PSD VALUES FOR GROSS LEVEL INPUT *****)
ERINT 760
DC 780 I=1,N
PRINT 770,FR(I), (F1ESD(J),J=1,9)
CONTINUE
PRINT 791
FCRMAI(1H1,6X,'RMS VALUES-CROSS LEVEL INPUT')
ERINT 800,(I,F1RMS(I),I=1,10)
WRITE(6,850)
FCRMAI(1H1,45X,'PSD VALUES FOR ALIGNMENT INPUT',//10X,'FREQUENCY',
1H2)',1X,'LATERAL CONTACT FORCES',25X,'CENTERPLATE FORCE',/29X,
2'AXLE 1',7X,'AXLE 2',7X,'AXLE 3',7X,'AXLE 4',5X,
34X,'LATERAL POSITION LATERAL MAGNITUDE')
DC 860 IPR=1,N
WRITE(6,855) FR(IPR), (FSPSD(JPR,IPR),JPR=3,6),FSPSD(1,IPR),
1 FSPSD(2,IPR)
FCRMAI(12X,F10.3,5X,4(E10.4,34),5X,E10.4,12X,E10.4)
CONTINUE
PRINT 810
FCRMAI(1H1,6X,'RMS VALUES -ALIGNMENT INPUT')
ERINT 820,(FRMS(I),I=3,6),FRMS(1),FRMS(2)
FCRMAI(///,6X,'LATERAL CONTACT FORCES',//11X,
1'AXLE 1 =,E9.3//11X,
1'AXLE 2 =,E9.3//11X,
1'AXLE 3 =,E9.3//11X,
1'AXLE 4 =,E9.3//6X,
1'LATERAL POSITION OF RESULTANT CENTERPLATE FORCE =,E9.3//6X,
1'LATERAL FORCE AT THE CENTERPLATE =,E9.3)
WRITE(6,870)
FCRMAI(1H1,46X,'PSD VALUES FOR GROSS LEVEL INPUT',//10X,'FREQUENCY',
1(HZ)',11X,'LATERAL CONTACT FORCES',25X,'CENTERPLATE FORCE',/29X,
2'AXLE 1',7X,'AXLE 2',7X,'AXLE 3',7X,'AXLE 4',5X,
34X,'LATERAL POSITION LATERAL MAGNITUDE')
DC 873 IPR=1,N
WRITE(6,855) FR(IPR), (F1ESD(JPR,IPR),JPR=3,6),F1PSD(1,IPR),
1 F1ESD(2,IPR)
CONTINUE
873 CONTINUE
00625000

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PRINT 830
830 PCNMAT(IH1,6Y,BMS,VALUES-CROSS-LEVEL,INPUT*)
PRINT 820,(FIRMS(T),I=3,6),FIRMS(1),FIRMS(2)
S=S+1.
K1=K1+1
CALL PLOTB(FR,TPSD,IIESD,FRSD,FIPSD,M,K1,V,S)
900 CCNTINUE
CALL PLOT(O,0.999)
50 STOP
END
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SUBROUTINE SETUP(M,C,K,FAR,FCLR)
C*****
C
C THIS SUBROUTINE COMPUTES THE VELOCITY INDEPENDENT TERMS OF
C THE M,C,K,FAR AND FCLR MATRICES. THE VEHICLE EQUATIONS ARE
C IN THE FOLLOWING FORM,
C
C M*XDOT + C*XDOT + D*X = FA*UA + FCC*UPHI
C*****
C
DIMENSION M(9,9),C(9,9),K(9,9),FC1B(9,4),FAR(9,8)
COMMON /NAME1/A11,A12,A13,A14,ALH11,ALH21,ALH31,ALH41,
1 D,DELOF,DELOB,DLO1,DLO2,DLO3,DLO4,DT11,DT12,DT13,DT14,
2 LTBEE,DTHBR,DXE,DXR,DYF,DYR,EPL11,EPL21,EPL31,EPL41,
3 EPL51,EPL61,EPL71,EPL81,F11,F12,F22,F33,H1,IBY,IBZ,
4 ICY,ICZ,ICYZ,IWY,KIHBF,KIHBR,KIHWF,KIHWB,KXF,KXR,
5 KYF,KYR,L1,L2,L3,LE11,LE12,LE13,LE14,MB,MC,MSF,MW,
6 FO,RHO11,RHO21,RHO31,RHO41,RHO51,RHO61,RHO71,RHO81,WB,WC,
7 WF,WN,WR,WT,X,DHWF,DHWR,ISFY,ALH51,ALH61,ALH71,ALH81
COMMON /NAME2/TERM13,TERM14,TERM15,TERM16,TERM17,TERM20,
1 TERM26,TERM27,TERM34,TERM40,TERM41,TERM42,TERM43,TERM44,
2 TERM45,TERM46,TERM47,TERM48,TERM49,TERM50,TERM51,
3 TERM52,TERM53,TERM54,TERM55,TERM56,TERM57,TERM58,
4 TERM59,TERM60,TERM64,TERM65,TERM89,TERM90,TERM91,
5 TERM92,TERM21,TERM35
REAL L1,L2,L3,M,MSE,MC,IB11,LB12,LE13,LB14,MB
REAL KXF,KXR,KYF,KYR,KIHBF,KIHBR,KIHWF,KIHWB,KIHWB,KIHWB
REAL ISFY,IBY,IBZ,IWY,IWY,ICY,ICZ,ICYZ,M,K
H2=E1
DC 650 I=1,9
DC 650 J=1,9
M(I,J)=0.0
C(I,J)=0.0
K(I,J)=0.0
650 CCNTINUE
M(1,1)=2.*(MSF+MW)
M(2,2)=2.*(IWY+ISFY+D*D*MSF+L1*MW)+I*BY
M(2,3)=IBY+2.*IWY+2.*MSE*D*D
M(3,3)=M(2,3)
M(3,2)=M(2,3)
M(4,4)=M(1,1)
M(5,5)=M(2,2)
M(5,6)=M(2,3)
M(6,6)=M(2,3)
M(6,5)=M(2,3)
M(7,7)=MC+2.*MB
M(7,8)=MB*(L2-L3)
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H (7,9)=2.*H2*MB
 H (8,7)=H (7,8)
 H (8,8)=ICY+MB*(L2*L2+L3*L3)
 H (8,9)=-ICYZ+NB*(L2-L3)*H2
 H (9,7)=H (7,8)
 H (9,8)=H (8,9)
 H (9,9)=ICZ+2.*IBZ+2.*B2*H2*MB

 C (1,7)=-2.*DXF
 C (1,8)=-2.*DXF*L2
 C (1,9)=-2.*DXF*H2

 C (2,8)=-DTHBF
 C (2,9)=-DYF*L1*D*D/X*(A11-A12)

 C (3,8)=C (2,8)

 C (4,7)=-2.*DXR
 C (4,8)=2.*DXR*L3
 C (4,9)=-2.*DXR*H2

 C (5,8)=-DTHBR
 C (5,9)=-DYR*L1*D*D/X*(A13-A14)
 C (6,8)=C (5,8)

 C (7,7)=2.*(DXF+DXR)
 C (7,1)=-2.*DXF
 C (7,4)=-2.*DXR
 C (7,8)=2.*(DXF*L2-DXR*L3)
 C (7,9)=2.*H2*(DXF+DXR)

 C (8,8)=DTHBF+DTHBR+2.*(DXR*L3*L3+DXF*L2*L2)
 C (8,9)=2.*H2*(DXF*L2-DXR*L3)
 C (8,7)=C (7,8)
 C (8,1)=-2.*DXF*L2
 C (8,4)=2.*DXR*L3
 C (8,2)=-DTHBF
 C (8,3)=C (8,2)
 C (8,5)=-DTHBR
 C (8,6)=C (8,5)

 C (9,1)=-2.*H2*DXF-D*D/X*(A11+A12)*DYF
 C (9,2)=-D*D*L1/X*(A11-A12)*DYF
 C (9,4)=-2.*H2*DXR-D*D/X*(A13+A14)*DYR
 C (9,5)=-D*D*L1/X*(A13-A14)*DYR
 C (9,7)=2.*H2*(DXF+DXR)
 C (9,8)=2.*H2*(DXF*L2-DXR*L3)
 C (9,9)=2.*D*D*(DYF+DYR)+2.*H2*H2*(DXF+DXR)

 C ***SEEING CONSTANT***
 K (1,1)=2.*(KXF-F12*(DT11+DT12)/(X*F0)+WF*(A11+A12+DT11+DT12)/X/2.)
 K (1,2)=-4.*F11-2.*L1*F12*(DT11-DT12)/(X*F0)+L1*WF*
 1/(A11-A12+DT11-DT12)/X
 K (1,3)=-4.*F11
 K (1,7)=-2.*KXF
 K (1,8)=-2.*KXF*L2
 K (1,9)=-2.*KXF*H2

 C
 K (2,1)=WF*L1/X*(DT11+A11-DT12-A12)+2.*(-F22/R0/X*(DT11+DT12)
 1+X*F33/R0*(LB11+LB12)-L1*F12/R0/X*(DT11-DT12))
 K (2,2)=KTHBF+4.*F12-X*WF*(DL01+DL02)+
 1/L1*L1*WF*(DT11+DT12+A11+A12)/X-2.*L1*F22*(DT11-DT12)
 1/(R0*X)+2.*X*F33*L1*(LB11-LB12)/R0
 1-2.*L1*L1*F12*(DT11+DT12)/(R0*X)
 K (2,3)=KTHBF+4.*F12-X*WF*(DL01+DL02)
 K (2,8)=-KTHBF
 K (2,9)=-KYP*L1*D*D/X*(A11-A12)

 C
 K (3,1)=2.*X*F33/R0*(LB11+LB12)-2.*F22/R0/X*(DT11+DT12)
 K (3,2)=KTHBF+4.*F12-Y*WF*(DL01+DL02)

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1-2.*F22*L1/R0/X*(DT11-D112)+2,*X*X*F33*L1
1/R0/X*(LB11-LB12)
K(3,3)=-K(2,3)+KTHWF
K(3,8)=-K(2,8)
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C
K(4,4)=2.*(KXR-F12/X/R0*(DT13+DT14))+WR/X*(A13+A14+
DT13+DT14)
K(4,5)=-4.*F11-2.*L1*F12/X/R0*(DT13-D114)+L1*WR
1/X*(A13-A14+DT13-DT14)
K(4,6)=-K(1,3)
K(4,7)=-2.*KXR
K(4,8)=2.*KXB*L3
K(4,9)=-2.*KXR*H2
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C
K(5,4)=-WR*L1/X*(DT13+A13-DT14-A14)-2.*F22/R0/X*(DT13
+DT14)+2.*X*F33/R0*(LE13+LB14)-2.*L1*F12
1/R0/X*(DT13-DT14)
K(5,5)=-KTHBR+4.*F12-X*WR*(DL03+DL04)+
L1*L1*WR/X*(DT13+DT14+A13+A14)-2.*L1*F22/R0/X*
1*(DT13-DT14)+2.*X*F33*L1/R0*(LB13-LE14)
1-2.*L1*L1*F12/R0/X*(DT13+DT14)
K(5,6)=-KTHBR+4.*F12-X*WR*(DL03+DL04)
K(5,8)=-KTHBR
K(5,9)=-KYR*L1*D*D/X*(A13-A14)
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C
K(6,4)=2./R0*(X*F33*(LB13+LB14)-F22/X*(DT13+DT14))
K(6,5)=-KTHBR+4.*F12-X*WR*(DL03+DL04)
1-2.*F22*L1/R0/X*(DT13-D114)
1+2.*X*X*F33*L1/R0/X*(LB13-LB14)
K(6,6)=-KTHWR+KTHBR+4.*F12-X*WR*(DL03+DL04)
K(6,8)=-K(5,8)
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C
K(7,7)=2.*(KXF+KXB)
K(7,1)=-2.*KXF
K(7,4)=-2.*KXR
K(7,8)=2.*(KXF*L2-KXB*L3)
K(7,9)=2.*H2*(KXF+KXB)
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C
K(8,8)=-KTHBR+KTHBR+2.*(KXR*L3*LJ+KXF*L2*L2)
K(8,9)=-H2*K(7,8)
K(8,7)=-K(7,8)
K(8,1)=-2.*KXF*L2
K(8,4)=-2.*KXR*L3
K(8,2)=-KTHBF
K(8,3)=-K(8,2)
K(8,5)=-KTHBR
K(8,6)=-K(8,5)
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C
1)
K(9,1)=-2.*H2*KXF-D*D/X*(A11+A12)*KXF
K(9,2)=-D*D*L1/X*(A11-A12)*KXF
K(9,4)=-2.*H2*KXR-D*D/X*(A13+A14)*KXR
K(9,5)=-D*D*L1/X*(A13-A14)*KXR
K(9,7)=-K(7,9)
K(9,8)=-K(7,9)*H2
K(9,9)=2.*(H2*H2*(KXF+KXR)+D*D*(KYF+KXB)-H2*DL0F*KXF-H2*DL0F*KXB)
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C
****MATRIX SETUP****
C INPUT MATRIX, VELOCITY INDEPENDENT TERMS
TEHM1=WF/X
TEHM2=2.*F12/R0/X
TEHM3=-L1*WF/X+2.*F22/R0/X+2.*L1*F12/R0/X
TEHM4=L1*WF/X
TEHM5=2.*X*F33/R0
TEHM6=2.*F22/R0/X
TEHM7=2.*X*F33/R0
TEHM8=D*D*KXF/X
TEHM9=D*D*KXR/X
TEHM10=WR/X
TEHM11=-L1*WR/X+2.*F22/R0/X+2.*L1*F12/R0/X
TEHM12=L1*WR/X
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TERM16=D*D*DYF/X	00825000
TERM17=D*D*DIR/X	00826000
TERM18=L1*WF/X+2.*F22/RO/X-2.*L1*F12/BO/X	00827000
TERM19=L1*WR/X+2.*F22/RO/X-2.*L1*F12/BO/X	00828000
TERM22=(2.*F12/RO-WF)*BO/X	00829000
TERM23=2.*F33*X	00830000
TERM24=(-WF*RO*L1+2.*F22+2.*L1*F12)/X	00831000
TERM25=(WF*RO*L1+2.*F22-2.*L1*F12)/X	00832000
TERM28=2.*F22/X	00833000
TERM29=(2.*F12/RO-WR)*RO/X	00834000
TERM30=(-WR*RO*L1+2.*F22+2.*L1*F12)/X	00835000
TERM31=(WR*RO*L1+2.*F22-2.*L1*F12)/X	00836000
TERM32=D*D*KYF	00837000
TERM33=D*D*KYR	00838000
TERM34=C*D*DYF	00839000
TERM35=C*D*DYR	00840000
TERM61=F12/RO	00841000
TERM65=ICZ/WC	00842000
TERM41=-((A11+DT11)*WN-TERM61*DT11)/X	00843000
TERM43=F11+L1/X*(TERM61*DT11-(A11+DT11)*WN)	00844000
TERM44=DLO1*(WN-TERM61)	00845000
TERM46=-((A12+DT12)*WN-TERM61*DT12)/X	00846000
TERM48=F11-L1/X*(TERM61*DT12-(A12+DT12)*WN)	00847000
TERM49=DLO2*(WN-TERM61)	00848000
TERM51=-((A13+DT13)*WN-TERM61*DT13)/X	00849000
TERM53=F11+L1/X*(TERM61*DT13-(A13+DT13)*WN)	00850000
TERM54=DLO3*(WN-TERM61)	00851000
TERM56=-((A14+DT14)*WN-TERM61*DT14)/X	00852000
TERM58=F11-L1/X*(TERM61*DT14-(A14+DT14)*WN)	00853000
TERM59=DLO4*(WN-TERM61)	00854000
TERM89=A13+A14	00855000
TERM90=A13-A14	00856000
TERM91=A11+A12	00857000
TERM92=A11-A12	00858000
FAR(1,1)=-TERM1*(ALH11+EPL11)+TERM2*EPL11	00860000
FAR(1,2)=-TERM1*(ALH21+EPL21)+TERM2*EPL21	00861000
FAR(1,3)=-TERM1*(ALH31+EPL31)+TERM2*EPL31	00862000
FAR(1,4)=-TERM1*(ALH41+EPL41)+TERM2*EPL41	00863000
FAR(2,1)=TERM3*EPL11-TERM4*ALH11-TERM5*RHO11	00864000
FAR(2,2)=TERM3*EPL21-TERM4*ALH21-TERM5*RHO21	00865000
FAR(2,3)=TERM3*EPL31-TERM4*ALH31-TERM5*RHO31	00866000
FAR(2,4)=TERM3*EPL41-TERM4*ALH41-TERM5*RHO41	00867000
FAR(3,1)=TERM6*EPL11-TERM7*RHO11	00868000
FAR(3,2)=TERM6*EPL21-TERM7*RHO21	00869000
FAR(3,3)=TERM6*EPL31-TERM7*RHO31	00870000
FAR(3,4)=TERM6*EPL41-TERM7*RHO41	00871000
FAR(4,5)=-TERM10*(ALH51+EPL51)+TERM2*EPL51	00872000
FAR(4,6)=-TERM10*(ALH61+EPL61)+TERM2*EPL61	00873000
FAR(4,7)=-TERM10*(ALH71+EPL71)+TERM2*EPL71	00874000
FAR(4,8)=-TERM10*(ALH81+EPL81)+TERM2*EPL81	00875000
FAR(5,5)=TERM11*EPL51-TERM12*ALH61-TERM5*RHO51	00876000
FAR(5,6)=TERM11*EPL61-TERM12*ALH61-TERM5*RHO61	00877000
FAR(5,7)=TERM11*EPL71-TERM12*ALH71-TERM5*RHO71	00878000
FAR(5,8)=TERM11*EPL81-TERM12*ALH81-TERM5*RHO81	00879000
FAR(6,5)=TERM6*EPL51-TERM7*RHO51	00880000
FAR(6,6)=TERM6*EPL61-TERM7*RHO61	00881000
FAR(6,7)=TERM6*EPL71-TERM7*RHO71	00882000
FAR(6,8)=TERM6*EPL81-TERM7*RHO81	00883000
FAR(9,1)=TERM8*ALH11	00884000
FAR(9,2)=TERM8*ALH21	00885000
FAR(9,3)=TERM8*ALH31	00886000
FAR(9,4)=TERM8*ALH41	00887000
FAR(9,5)=TERM9*ALH51	00888000
FAR(9,6)=TERM9*ALH61	00889000
FAR(9,7)=TERM9*ALH71	00890000
FAR(9,8)=TERM9*ALH81	00891000
	00892000


```

C INPUT MATRIX TERMS THAT DEPEND ON VELOCITY
C (1,1)=4.*F11/V+2.*DXF
C (1,3)=TERM96-TERM88*TERM91
C (1,2)=C(1,3)+TERM99*TERM92
C (2,2)=DTHBF-TERM93*L1*TERM92+TERM98+TERM94*L1*TERM99*TERM91
C (2,3)=DTHBF-TERM88*L1*TERM92+TERM98
C (3,1)=(TERM88-TERM93)*TERM91-TERM96
C (3,2)=C(3,1)+TERM99*TERM92
C (3,3)=DTHBF+(TERM88-TERM93)*L1*TERM92+TERM98
C (4,4)=4.*F11/V+2.*DXF
C (4,6)=TERM96-TERM88*TERM89
C (4,5)=C(4,6)+TERM99*TERM90
C (5,5)=DTHBR-TERM93*L1*TERM90+TERM98+TERM94*L1*TERM99*TERM89
C (5,6)=DTHBR-TERM88*L1*TERM90+TERM98
C (6,4)=(TERM88-TERM93)*TERM89-TERM96
C (6,5)=DTHBR+(TERM88-TERM93)*L1*TERM90+TERM98
C (6,6)=DTHBR+DTHBR+TERM98
WRITE(6,91)
C ***DEBUG CHECK* STIFFNESS, DAMPING AND MASS MATRICES***
DC 99 I=1,9
99 WHITE(6,92) (K(I,J),J=1,9)
   WHITE(6,93)
DC 98 I=1,9
98 WHITE(6,92) (C(I,J),J=1,9)
   WHITE(6,94)
DC 97 I=1,9
97 WHITE(6,92) (M(I,J),J=1,9)
   FCRMAT(//1H,'K-MATRIX')
92 FCRMAT(2X,9(E9.3,3X))
93 FCRMAT(//1H,'C-MATRIX')
94 FCRMAT(//1H,'M-MATRIX')
RETURN
END
00952000
00953000
00954000
00955000
00956000
00957000
00958000
00959000
00960000
00961000
00962000
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00984000
00985000
00986000

```

TERM42=(TERM40*L1-TERM60*M)
 TERM45=-F11/V*(1.+R0*A12/X)*M
 TERM47=(-TERM45*L1-TERM60*M)
 TERM50=-F11/V*(1.+R0*A13/X)*M
 TERM52=(TERM50*L1-TERM60*M)
 TERM55=-F11/V*(1.+R0*A14/X)*M
 TERM57=(-TERM55*L1-TERM60*M)
 TERM74=TERM26*M
 TERM75=TERM20*M
 TERM73=TERM27*M
 TERM76=TERM17*M
 TERM77=TERM16*M
 TERM78=TERM15*M
 TERM79=TERM14*M
 TERM80=-TERM13*M

FAL(1,1)=TERM80*ALH11
 FAL(1,2)=TERM80*ALH21
 FAL(1,3)=TERM80*ALH31
 FAL(1,4)=TERM80*ALH41
 FAL(2,1)=TERM79*ALH11
 FAL(2,2)=TERM79*ALH21
 FAL(2,3)=TERM75*ALH31
 FAL(2,4)=TERM75*ALH41
 FAL(3,1)=TERM78*ALH11
 FAL(3,2)=TERM78*ALH21
 FAL(3,3)=TERM78*ALH31
 FAL(3,4)=TERM78*ALH41
 FAL(4,5)=TERM80*ALH51
 FAL(4,6)=TERM80*ALH61
 FAL(4,7)=TERM80*ALH71
 FAL(4,8)=TERM80*ALH81
 FAL(5,5)=TERM79*ALH51
 FAL(5,6)=TERM79*ALH61
 FAL(5,7)=TERM75*ALH71
 FAL(5,8)=TERM75*ALH81
 FAL(6,5)=TERM78*ALH51
 FAL(6,6)=TERM78*ALH61
 FAL(6,7)=TERM78*ALH71
 FAL(6,8)=TERM78*ALH81
 FAL(9,1)=TERM77*ALH11
 FAL(9,2)=TERM77*ALH21
 FAL(9,3)=TERM77*ALH31
 FAL(9,4)=TERM77*ALH41
 FAL(9,5)=TERM76*ALH51
 FAL(9,6)=TERM76*ALH61
 FAL(9,7)=TERM76*ALH71
 FAL(9,8)=TERM76*ALH81

FCL1(1,1)=-M*TERM21
 FCL1(1,2)=FCL1(1,1)
 FCL1(2,1)=TERM74-TERM73
 FCL1(2,2)=TERM74+TERM73
 FCL1(3,1)=TERM74
 FCL1(3,2)=TERM74
 FCL1(4,3)=FCL1(1,1)
 FCL1(4,4)=FCL1(1,1)
 FCL1(5,3)=FCL1(2,1)
 FCL1(5,4)=FCL1(2,2)
 FCL1(6,3)=FCL1(3,1)
 FCL1(6,4)=FCL1(3,2)
 FCL1(9,1)=TERM34*M
 FCL1(9,2)=FCL1(9,1)
 FCL1(9,3)=TERM35*M
 FCL1(9,4)=FCL1(9,3)
 RETURN
 END

0 1015000
 0 1016000
 0 1017000
 0 1018000
 0 1019000
 0 1020000
 0 1021000
 0 1022000
 0 1023000
 0 1024000
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 0 1080000
 0 1081000

SUBROUTINE DCMINY

SUBROUTINE DCMINY (AR, AI, N, DB, DI, L, N)
 IMPLICIT REAL*8 (A-H, O-Z)

DIMENSION AR (81), AI (81), L (9), N (9)

DR=1.0

DI=0.0

MK=-N

DO 80 K=1, N

MK=NK+M

L (K)=K

M (K)=K

KK=NK+K

BIGAR=AR (KK)

BIGAI=AI (KK)

BIGA=DSQRT (BIGAR**2+BIGAI**2)

DO 20 J=K, N

IZ=N*(J-1)

DO 20 I=K, N

IJ=IZ+I

T=DSQRT (AR (IJ)**2+AI (IJ)**2)

10 IF (BIGA-T) 15, 20, 20

15 BIGAR=AR (IJ)

BIGAI=AI (IJ)

BIGA=DSQRT (BIGAR**2+BIGAI**2)

L (K)=I

M (K)=J

20 CONTINUE

J=L (K)

IF (J-K) 35, 35, 25

25 KI=K-N

DO 30 I=1, N

KI=KI+N

HOLDR=-AR (KI)

HOLDI=-AI (KI)

JI=KI-K+J

AR (KI)=AR (JI)

AI (KI)=AI (JI)

AR (JI)=HOLDE

AI (JI)=HOLDI

30 AI (KI)=HOLDI

35 I=N (K)

IF (I-K) 45, 45, 38

38 JP=N*(I-1)

DO 40 J=1, N

JK=NK+J

JI=JP+J

HOLDR=-AR (JK)

HOLDI=-AI (JK)

AR (JK)=AR (JI)

AI (JK)=AI (JI)

AR (JI)=HOLDE

AI (JI)=HOLDI

40 AI (JK)=HOLDI

45 IF (BIGA) 48, 46, 48

46 DR=0.0

DI=0.0

RETURN

48 DO 55 I=1, N

IF (I-K) 50, 55, 50

50 IK=NK+I

CALL DDIV (AR (IK), AI (IK), -BIGAR, -BIGAI, CR, CI)

AR (IK)=CR

AI (IK)=CI

55 CONTINUE

DO 65 I=1, N

IK=NK+I

IJ=I-N

DO 65 J=1, N

IJ=IJ+N

IF (I-N) 60, 65, 60

01082000
 01083000
 01084000
 01086000
 01087000
 01088000

01089000
 01090000
 01091000
 01092000
 01093000

01094000
 01095000
 01096000
 01097000
 01098000

01099000
 01100000
 01101000
 01102000
 01103000

01104000
 01105000
 01106000
 01107000
 01108000

01109000
 01110000
 01111000
 01112000
 01113000

01114000
 01115000
 01116000
 01117000
 01118000

01119000
 01120000
 01121000
 01122000
 01123000

01124000
 01125000
 01126000
 01127000
 01128000

01129000
 01130000
 01131000
 01132000
 01133000

01134000
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 01136000
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 01138000

01139000
 01140000
 01141000
 01142000
 01143000

01144000
 01145000
 01146000
 01147000
 01148000

01149000

60	IF(J-K) 62,65,62	01150000
62	KJ=J-I+K	01151000
	CALL DMULT(AR(KN),AI(KK),AR(KJ),AI(KJ),CR,CI)	01152000
	AR(IJ)=AR(IJ)+CR	01153000
	AI(IJ)=AI(IJ)+CI	01154000
65	CONTINUE	01155000
	KJ=K-N	01156000
	DO 75 J=1,N	01157000
	KJ=KJ+N	01158000
	IF(J-K) 70,75,70	01159000
70	CALL DDIIV(AR(KJ),AI(KJ),BIGAR,BIGAI,CR,CI)	01160000
	AR(KJ)=CR	01161000
	AI(KJ)=CI	01162000
75	CONTINUE	01163000
	CALL DMULT(DB,DI,BIGAR,BIGAI,CR,CI)	01164000
	DB=CR	01165000
	DI=CI	01166000
	TR=1.0	01167000
	TI=0.	01168000
	CALL DDIIV(TR,TI,BIGAR,BIGAI,CR,CI)	01169000
	AR(KK)=CR	01170000
	AI(KK)=CI	01171000
80	CONTINUE	01172000
	K=N	01173000
100	K=(K-1)	01174000
	IF(K) 150,150,105	01175000
105	I=L(K)	01176000
	IF(I-K) 120,120,108	01177000
108	JO=N*(K-1)	01178000
	JH=N*(I-1)	01179000
	DO 110 J=1,N	01180000
	JK=JO+J	01181000
	HOLDI=AR(JK)	01182000
	HOLDI=AI(JK)	01183000
	JI=JH+J	01184000
	AR(JK)=-AR(JI)	01185000
	AI(JK)=-AI(JI)	01186000
110	AR(JI)=HOLDI	01187000
120	J=H(K)	01188000
	IF(J-K) 100,100,125	01189000
125	KI=K-N	01190000
	DO 130 I=1,N	01191000
	KI=KI+N	01192000
	HOLDI=AR(KI)	01193000
	HOLDI=AI(KI)	01194000
	JI=KI-K+J	01195000
	AR(KI)=-AR(JI)	01196000
	AI(KI)=-AI(JI)	01197000
130	AR(JI)=HOLDI	01198000
	GO TO 100	01199000
150	RETURN	01200000
	END	01201000
		01202000
		01203000

SUBROUTINE DDIIV

SUBROUTINE DDIIV(AR, AI, BR, BI, CR, CI)
DOUBLE PRECISION AR, AI, BR, BI, CR, CI, EE
ER=BR+BR+BI+BI
CH=(AR+BR+AI+BI)/EE
CI=(AI+BR-AR+BI)/EE
RETURN
END

01204000
01205000
01206000
01207000
01208000
01209000
01210000

SUBROUTINE DMULT

SUBROUTINE DMULT (AR, AI, BR, BI, CR, CI)	01211000
DOUBLE PRECISION AR, AI, BR, BI, CR, CI	01212000
CR=AR*BR-AI*BI	01213000
CI=AI*BR+AR*BI	01214000
RETURN	01215000
END	01216000

SUBROUTINE PLOTG

SUBROUTINE PLOTG (LABEL)	01217000
DIMENSION LABEL (20)	01218000
CALL PLOT (8.5, 0., 2)	01219000
CALL PLOT (8.5, 11., 2)	01220000
CALL PLOT (0., 11., 2)	01221000
CALL PLOT (0., 0., 2)	01222000
CALL SYMBOL (1.5, 10.5, .14, LABEL, 0.0, 72)	01223000
CALL PLOT (1.0, 1.0, -3)	01224000
CALL LGAXS (0., 0., 13HFREQUENCY (HZ), -13, 7.0, 0.0, -1., -429)	01225000
RETURN	01226000
END	01227000

SUBROUTINE PLOTD

SUBROUTINE PLOTD (K1, S1, S2, IVEL)	01228000
CALL SYMBOL (5.07, S1, .14, K1, 0.0, -1)	01229000
CALL SYMBOL (5.375, S2, .14, IVEL, 0.0, 4)	01230000
CALL SYMBOL (6.25, S2, .14, 6HFT/SEC, 0.0, 6)	01231000
RETURN	01232000
END	01233000

SUBROUTINE PLOTA

SUBROUTINE PLOTA (LABEL)	01234000
DIMENSION LABEL (20)	01235000
CALL PLOT (0.5, 0.5, -3)	01236000
CALL PLOTG (LABEL)	01237000
CALL LGAXS (0., 0., 'LATERAL, FRONT TRUCK PSD, CROSS LEVEL INPUT, (FT**2/HZ)', 52, 9.5, 90., .1E-11, 1.053)	01238000
CALL PLOT (-1.0, 11., -3)	01239000
CALL PLOTG (LABEL)	01240000
CALL LGAXS (0., 0., 'LATERAL, FRONT TRUCK PSD, CROSS LEVEL INPUT, (RAD**2/HZ)', 50, 9.5, 90., .1E-14, 1.053)	01241000
CALL PLOT (9.0, -1.0, -3)	01242000
CALL PLOTG (LABEL)	01243000
CALL LGAXS (0., 0., 'LATERAL, CAR BODY PSD, CROSS LEVEL INPUT, (FT**2/HZ)', 49, 9.5, 90., .1E-11, 1.053)	01244000
CALL PLOTG (LABEL)	01245000
CALL LGAXS (0., 0., 'LATERAL, CAR BODY PSD, CROSS LEVEL INPUT, (FT**2/HZ)', 49, 9.5, 90., .1E-11, 1.053)	01246000
CALL PLOTG (LABEL)	01247000

```

CALL PLOT (-1.0,-13.0,-3)
CALL PLOT(C LABEL)
CALL LGAYS(0.,0.,'ROLL,CAR BODY PSD,CROSS LEVEL INPUT,(RAD**2/HZ)
1,48,9.5,90.,.1E-13,1.053)
CALL PLOT(9.0,-1.0,-3)
CALL PLOT(C LABEL)
CALL LGAYS(0.,0.,'LATERAL,CONTACT FORCE PSD,AXLE 1,CROSS LEVEL IN
1PUT,(LB**2/HZ)',61,9.5,90.,.1E-11,1.053)
CALL PLOT(-1.0,11.,-3)
CALL PLOT(C LABEL)
CALL LGAYS(0.,0.,'LATERAL,CONTACT FORCE PSD,AXLE 3,CROSS LEVEL IN
1PUT,(LB**2/HZ)',61,9.5,90.,.1E-11,1.053)
CALL PLOT(9.0,-1.0,-3)
CALL PLOT(C LABEL)
CALL LGAYS(0.,0.,'LATERAL,FRONT TRUCK PSD, ALIGNMENT INPUT, (FT**
12/HZ)',52,9.5,90.,.1E-11,1.053)
CALL PLOT(-1.0,-13.0,-3)
CALL PLOT(C LABEL)
CALL LGAYS(0.,0.,'WARP,FRONT TRUCK PSD,ALIGNMENT INPUT,(RAD**2/H
12)',49,9.5,90.,.1E-14,1.053)
CALL PLOT(9.0,-1.0,-3)
CALL PLOT(C LABEL)
CALL LGAYS(0.,0.,'ROLL,CAR BODY PSD, ALIGNMENT INPUT,(FT**2/H
1,47,9.5,90.,.1E-15,1.053)
CALL PLOT(9.0,-1.0,-3)
CALL PLOT(C LABEL)
CALL LGAYS(0.,0.,'LATERAL,CONTACT FORCE PSD,AXLE 1, ALIGNMENT IN
1PUT,(LB**2/HZ)',61,9.5,90.,.1E-11,1.053)
CALL PLOT(-1.0,-13.0,-3)
CALL PLOT(C LABEL)
CALL LGAYS(0.,0.,'LATERAL,CONTACT FORCE PSD,AXLE 3, ALIGNMENT IN
1PUT,(LB**2/HZ)',61,9.5,90.,.1E-11,1.053)
CALL PLOT(-50.05,0.,-3)
CALL PLOT(9.0,-1.0,-3)
CALL PLOT(C LABEL)
CALL LGAYS(0.,0.,'PSD CROSS LEVEL INPUT(RAD**2/HZ)',33,9.5,90.,
1,1E-11,1.053)
CALL PLOT(-1.0,11.0,-3)
CALL PLOT(C LABEL)
CALL LGAYS(0.,0.,'PSD ALIGNMENT INPUT (FT**2/HZ)',33,9.5,90.,
1,1E-11,1.053)
CALL PLOT(-60.05,-12.0,-3)
CALL PLOT(9.0,-1.0,-3)
CALL PLOT(C LABEL)
CALL PLOT(-1.0,-13.0,-3)
CALL PLOT(C LABEL)
CALL PLOT(-70.05,0.,-3)
RETURN
END

```

SUBROUTINE PLOTB

```

SUBROUTINE PLOTB(FR,TPSD,T1PSD,TPSD,H,K1,V,S)
DIMENSION FR(1),TPSD(10,1),T1PSD(10,1),PPSD(6,1),P1PSD(6,1),
1 A1(200),A3(200),A7(200),A9(200),A10(200),
1 B1(200),B3(200),B7(200),B9(200),B10(200),
1 C3(200),C5(200),D3(200),D5(200)
DO 100 I=1,N
A1(I)=TPSD(1,I)
A3(I)=P1PSD(3,I)

```

A7(I)=TPSD(7,I)
A9(I)=TPSD(9,I)
A10(I)=TPSD(10,I)
B1(I)=T1PSD(1,I)
B3(I)=T1PSD(3,I)
B7(I)=T1PSD(7,I)
B9(I)=T1PSD(9,I)
B10(I)=T1PSD(10,I)
C3(I)=FPD(3,I)
C5(I)=FPD(5,I)
D3(I)=F1PSD(3,I)
D5(I)=F1PSD(5,I)

C

C ** PROTECT PAPER LIMITS **

IF(A1(I)-LT..1E-11) A1(I)=.1E-11
IF(A3(I)-LT..1E-14) A3(I)=.1E-14
IF(A7(I)-LT..1E-11) A7(I)=.1E-11
IF(A9(I)-LT..1E-15) A9(I)=.1E-15
IF(A10(I)-LT..1E-11) A10(I)=.1E-11
IF(B1(I)-LT..1E-11) B1(I)=.1E-11
IF(B3(I)-LT..1E-14) B3(I)=.1E-14
IF(B7(I)-LT..1E-11) B7(I)=.1E-11
IF(B9(I)-LT..1E-13) B9(I)=.1E-13
IF(B10(I)-LT..1E-11) B10(I)=.1E-11
IF(C3(I)-LT..1E-1) C3(I)=.1E-1
IF(C5(I)-LT..1E-1) C5(I)=.1E-1
IF(D3(I)-LT..1E-1) D3(I)=.1E-1
IF(D5(I)-LT..1E-1) D5(I)=.1E-1

C

100 CONTINUE

A1(N+1)=.1E-11
A3(N+1)=.1E-14
A7(N+1)=.1E-11
A9(N+1)=.1E-15
A10(N+1)=.1E-11
A1(N+2)=1.053
A3(N+2)=1.053
A7(N+2)=1.053
A9(N+2)=1.053
A10(N+2)=1.053
B1(N+1)=.1E-11
B3(N+1)=.1E-14
B7(N+1)=.1E-11
B9(N+1)=.1E-13
B10(N+1)=.1E-11
E1(N+2)=1.053
B3(N+2)=1.053
B7(N+2)=1.053
E9(N+2)=1.053
B10(N+2)=1.053
C3(N+1)=.1E-1
C5(N+1)=.1E-1
C3(N+2)=1.053
C5(N+2)=1.053
D3(N+1)=.1E-1
D5(N+2)=1.053

C

FR(N+1)=.1

FR(N+2)=.429

C

WRITE(8,10) V

10 FORMAT(F4.0)

EACKSPACE 8

READ(8,20) IVEL

20 FORMAT(A4)

S1=8.445-(-.375*S)

S2=8.375-(-.375*S)

CALL IGLIB(FR,B1,B,1,1,K1,0)

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01378000

CALL PLOTD (R1,S1,S2,IVEL)	01379000
CALL PLOT (0.,12.,-3)	01380000
CALL IGLIN (FR,B3,N,1,1,K1,0)	01381000
CALL PLOTD (K1,S1,S2,IVEL)	01382000
CALL PLOT (10.,0.,-3)	01383000
CALL IGLIN (FR,B7,N,1,1,K1,0)	01384000
CALL PLOTD (K1,S1,S2,IVEL)	01385000
CALL PLOT (0.,-12.,-3)	01386000
CALL IGLIN (FR,B9,N,1,1,K1,0)	01387000
CALL PLOTD (K1,S1,S2,IVEL)	01388000
CALL PLOT (10.,0.,-3)	01389000
CALL IGLIN (FR,D3,N,1,1,K1,0)	01390000
CALL PLOTD (K1,S1,S2,IVEL)	01391000
CALL PLOT (0.,12.,-3)	01392000
CALL IGLIN (FR,D5,N,1,1,K1,0)	01393000
CALL PLOTD (K1,S1,S2,IVEL)	01394000
CALL PLOT (10.,0.,-3)	01395000
CALL IGLIN (FR,A1,N,1,1,K1,0)	01396000
CALL PLOTD (K1,S1,S2,IVEL)	01397000
CALL PLOT (0.,-12.,-3)	01398000
CALL IGLIN (FR,A3,N,1,1,K1,0)	01399000
CALL PLOTD (K1,S1,S2,IVEL)	01400000
CALL PLOT (10.,0.,-3)	01401000
CALL IGLIN (FR,A7,N,1,1,K1,0)	01402000
CALL PLOTD (K1,S1,S2,IVEL)	01403000
CALL PLOT (0.,12.,-3)	01404000
CALL IGLIN (FR,A9,N,1,1,K1,0)	01405000
CALL PLOTD (K1,S1,S2,IVEL)	01406000
CALL PLOT (10.,0.,-3)	01407000
CALL IGLIN (FR,C3,N,1,1,K1,0)	01408000
CALL PLOTD (K1,S1,S2,IVEL)	01409000
CALL PLOT (0.,-12.,-3)	01410000
CALL IGLIN (FR,C5,N,1,1,K1,0)	01411000
CALL PLOTD (K1,S1,S2,IVEL)	01412000
CALL PLOT (-50.04,0.,-3)	01413000
CALL PLOT (10.,0.,-3)	01414000
CALL IGLIN (FR,B10,N,1,1,K1,0)	01415000
CALL PLOTD (K1,S1,S2,IVEL)	01416000
CALL PLOT (0.,12.,-3)	01417000
CALL IGLIN (FR,A10,N,1,1,K1,0)	01418000
CALL PLOTD (K1,S1,S2,IVEL)	01419000
CALL PLOT (-60.04,-12.,-3)	01420000
CALL PLOT (10.,0.,-3)	01421000
CALL IGLIN (FR,F6,N,1,1,K1,0)	01422000
CALL PLOTD (K1,S1,S2,IVEL)	01423000
CALL PLOT (0.,-12.,-3)	01424000
CALL IGLIN (FR,F5,N,1,1,K1,0)	01425000
CALL PLOT (-70.05,0.,-3)	01426000
CALL PLOT (-70.05,0.,-3)	01427000
RETURN	01428000
BND	

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US DOT, FRA, Neil K Cooperrider, E Harry Law

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